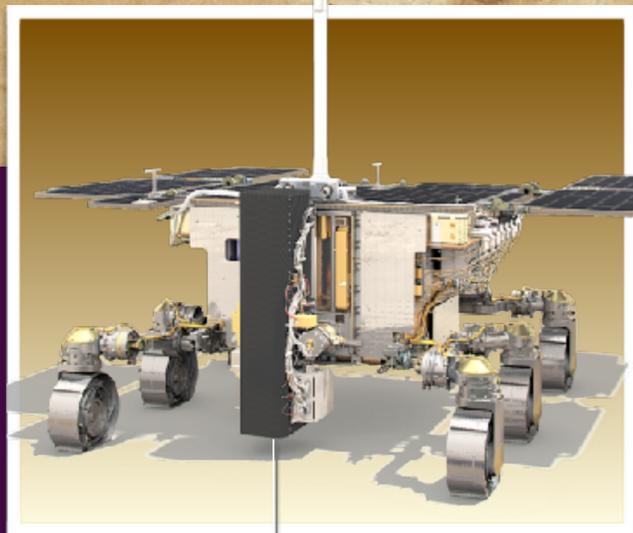


Search for Life on Mars

2020



SCIENTIFIC OBJECTIVES

- ▶ To search for signs of past and present life on Mars;
- ▶ To investigate the water/subsurface environment as a function of depth.

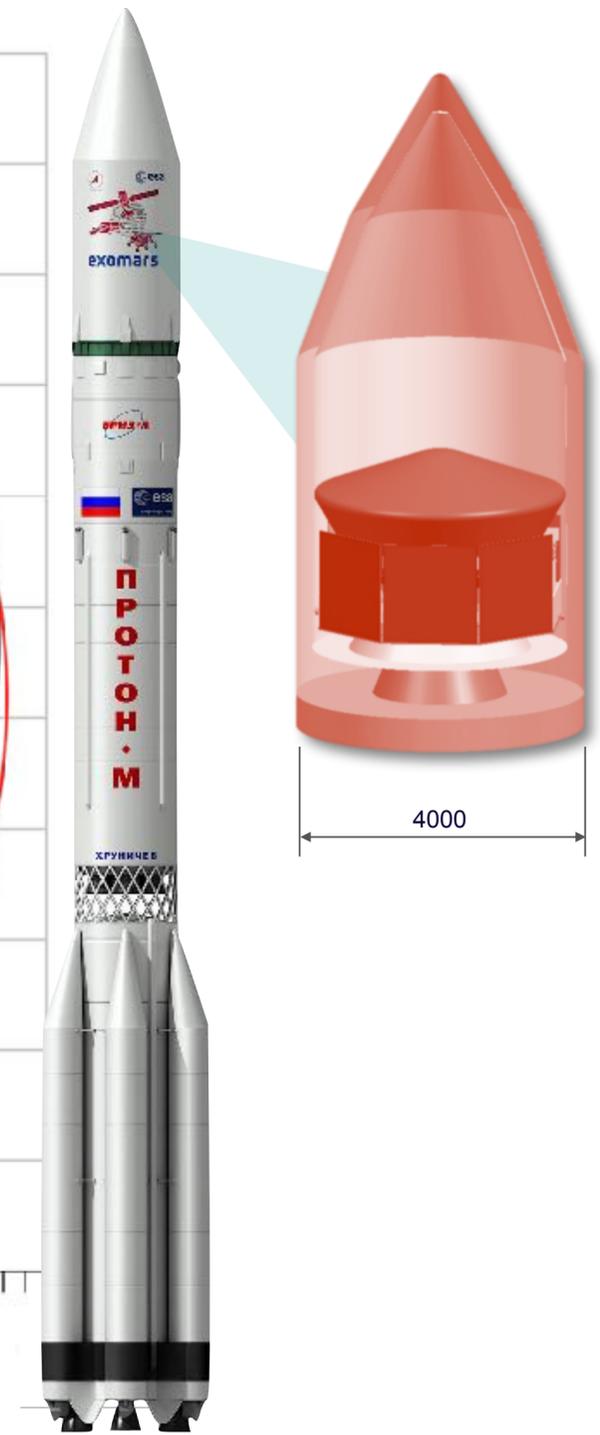
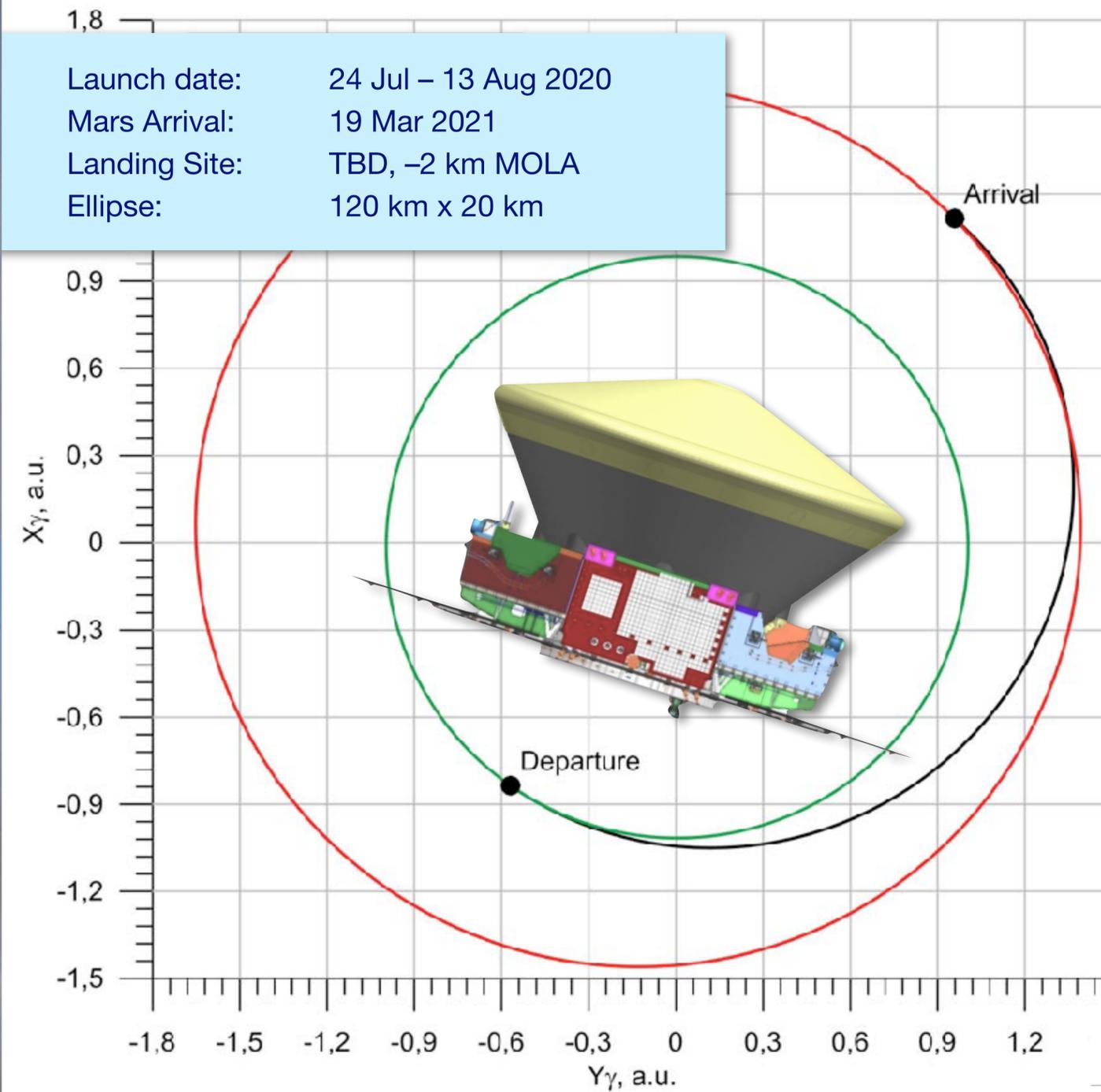
TECHNOLOGY OBJECTIVES

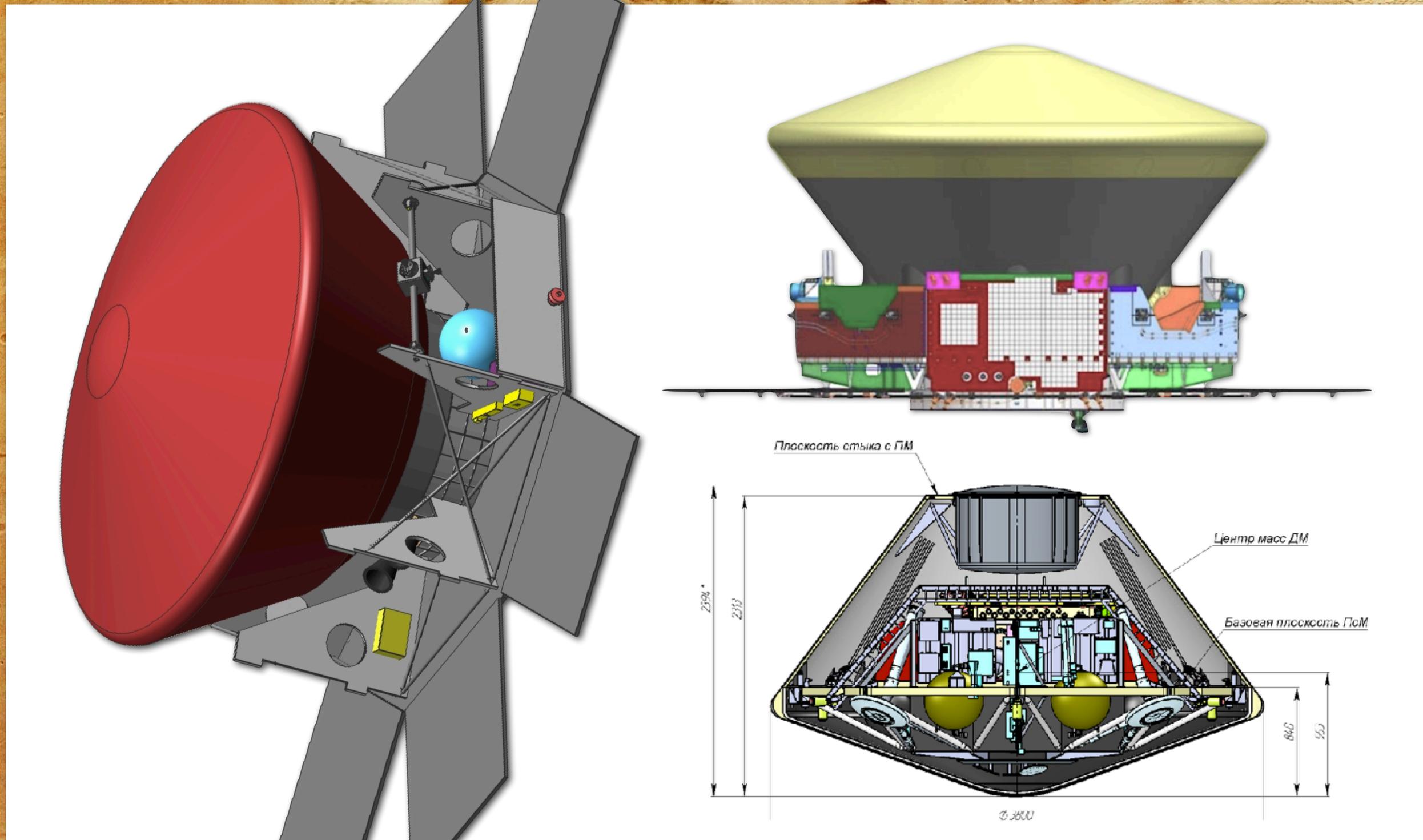
- ▶ Surface mobility with a rover (having several kilometres range);
- ▶ Access to the subsurface to collect samples (with a drill, down to 2-m depth);
- ▶ Sample acquisition, preparation, distribution, and analysis.

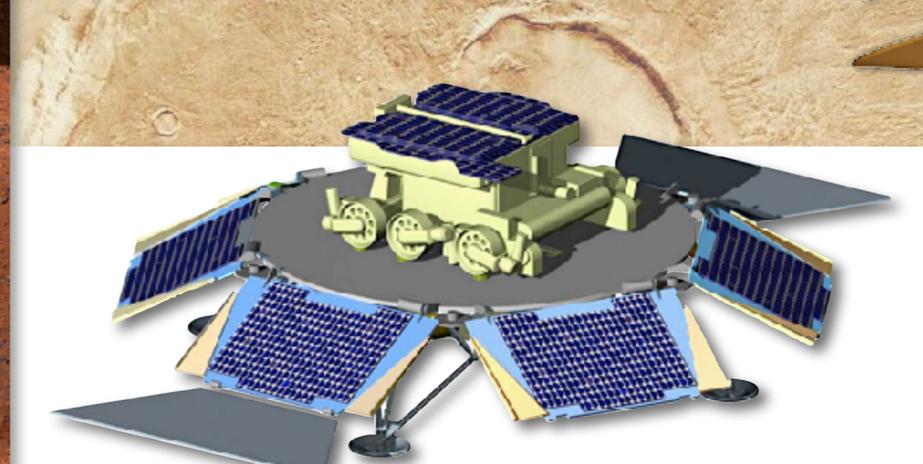
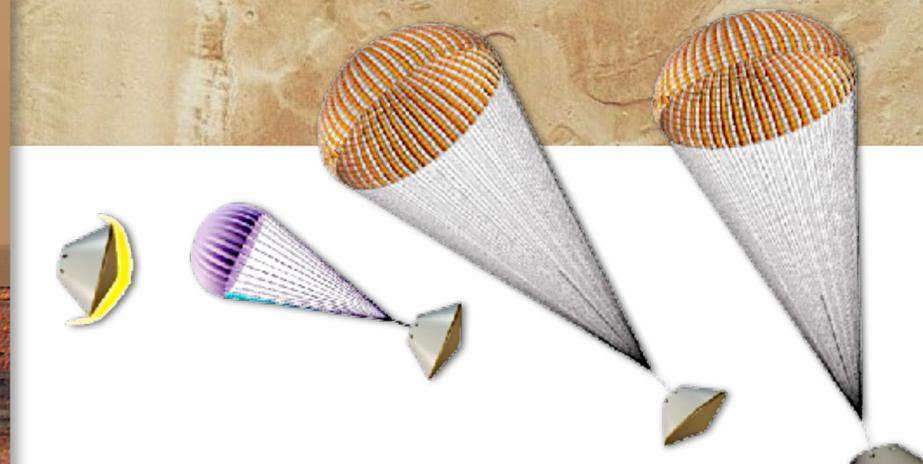
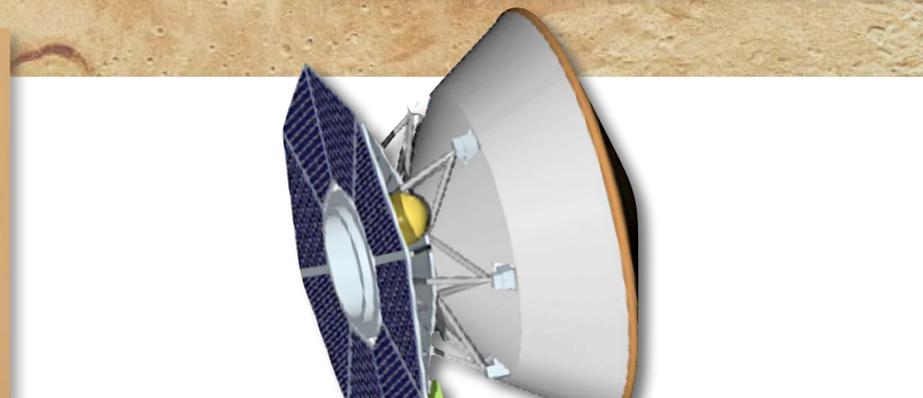


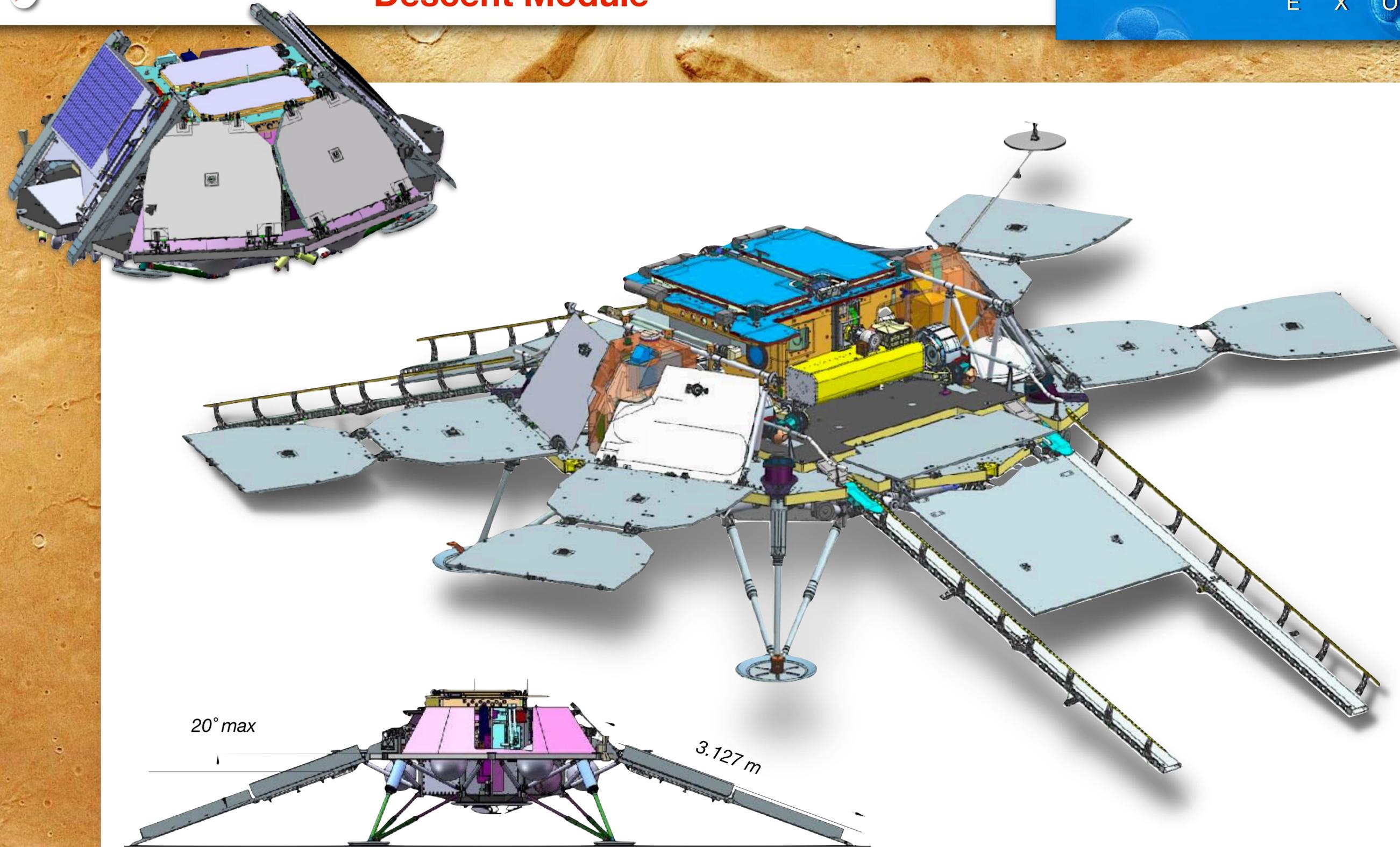
- ▶ To characterise the surface environment.

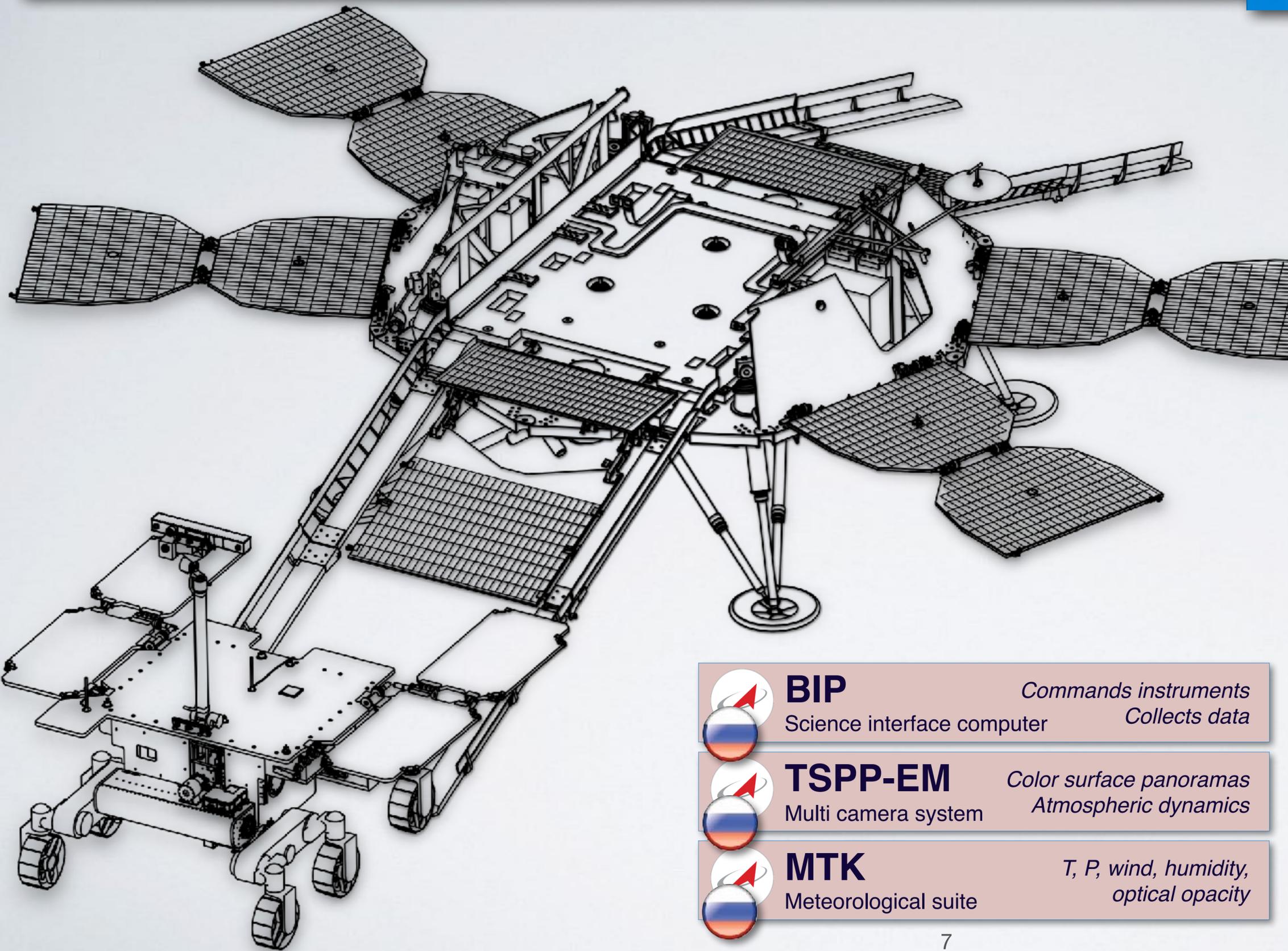
- ▶ Throttleable braking engines for planetary landing.
- ▶ Russian deep-space communications stations working in combination with ESA's ESTRACK.





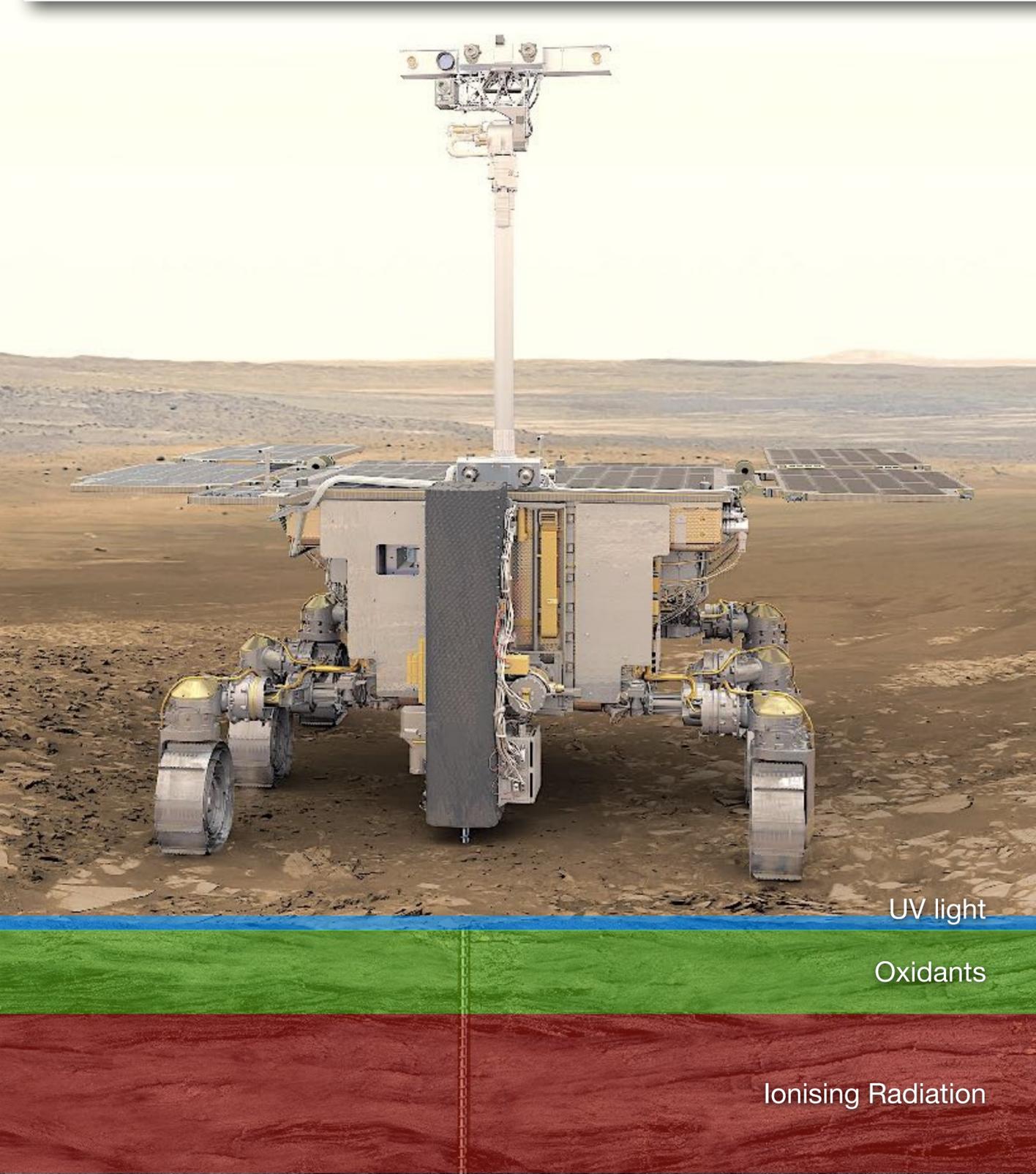




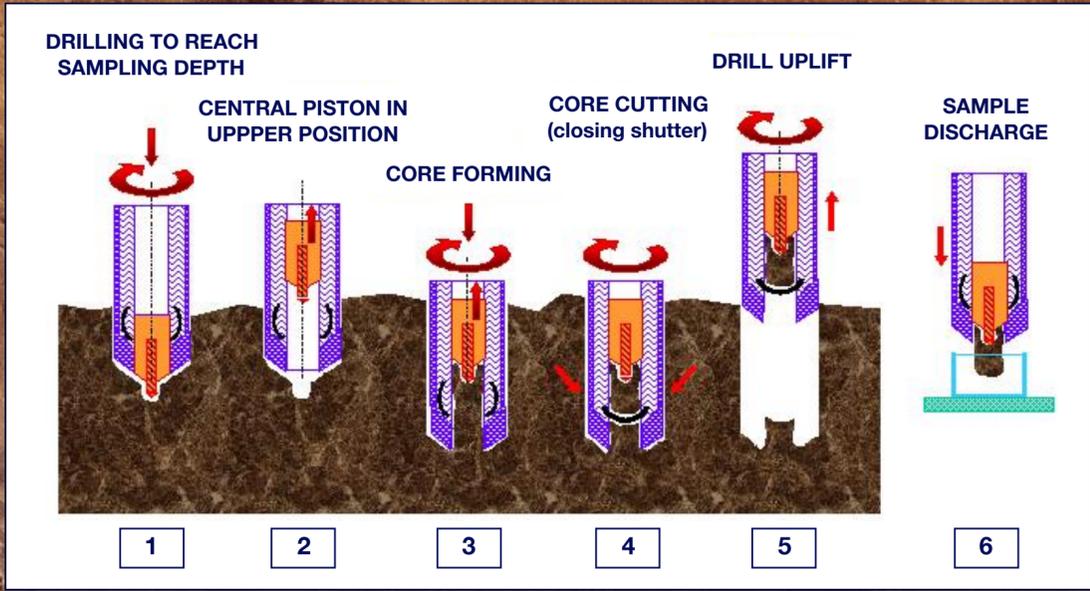


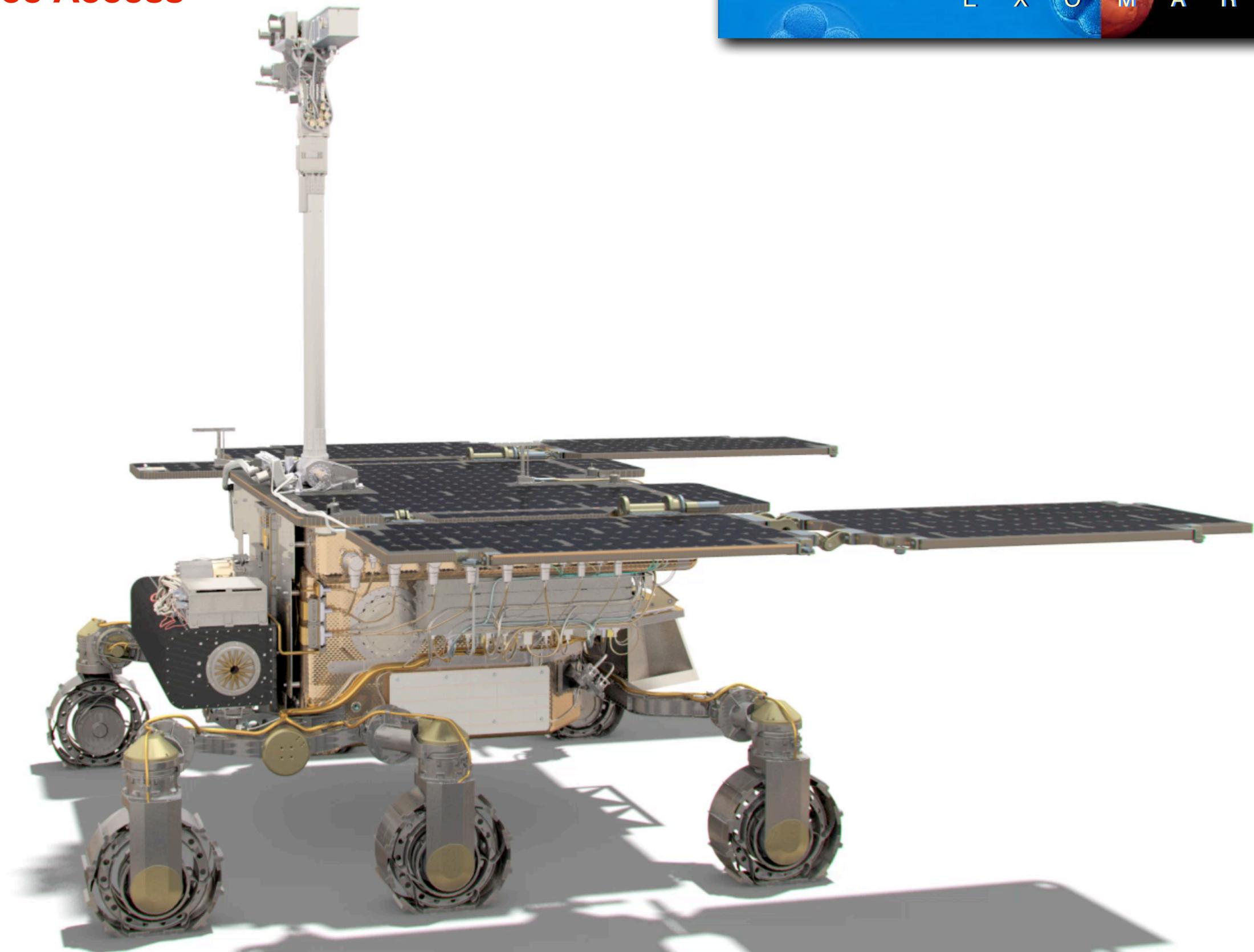
- 
BIP *Commands instruments*
 Science interface computer *Collects data*
- 
TSPP-EM *Color surface panoramas*
 Multi camera system *Atmospheric dynamics*
- 
MTK *T, P, wind, humidity,*
 Meteorological suite *optical opacity*

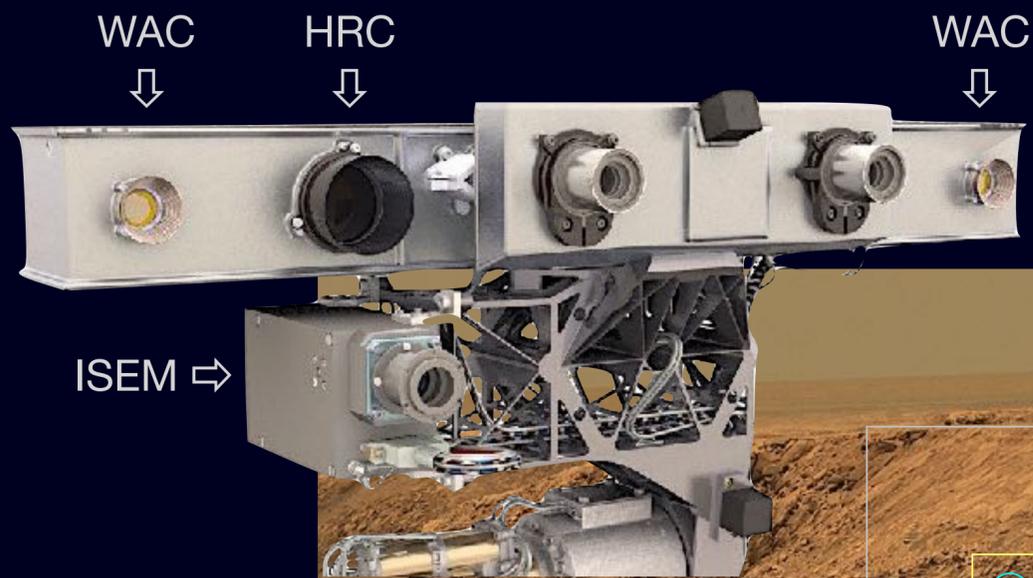
- 
PK *Dust properties and*
 Dust suite *E field monitoring*
- 
FAST *Trace gases*
 IR Fourier spectrometer *T and aerosol monitoring*
- 
RAT-M *Surface and atmospheric*
 Microwave radiometer *T monitoring*
- 
ADRON-EM *Subsurface water content*
 Neutron detector *Radiation dosimetry*
- 
MAIGRET *Magnetic field*
 Magnetometer *measurements*
- 
MGAK *Atmospheric*
 GCMS *Analysis*
- 
SEM *Internal Mars structure*
 Seismometer *investigations*
- 
M-DLS *Atmospheric chemical and*
 Diode laser spectrometer *isotopic composition*
- 
LaRa *Radio science for internal*
 Coherent transponder *structure investigations*
- 
HABIT *T, UV dose, humidity,*
 Habitability studies *salt deliquescence*



Nominal mission : 218 sols
 Nominal science : 6 Experiment Cycles + 2 Vertical Surveys
 EC length : 16–20 sols
 Rover mass : 300-kg class
 Mobility range : Several km

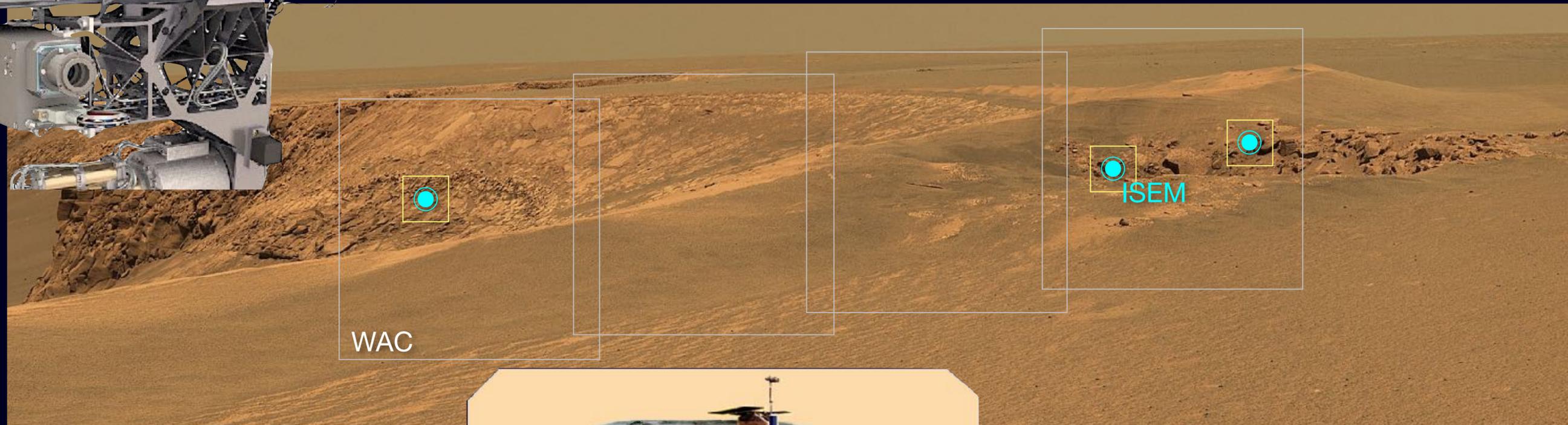






AT PANORAMIC SCALE: To establish the geological context

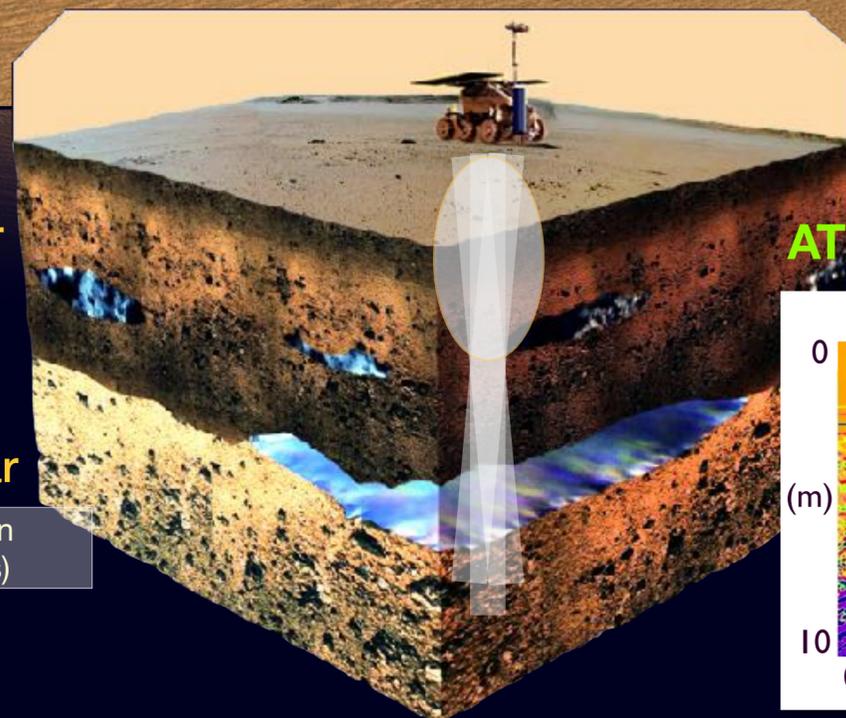
Two Wide Angle Cameras (WAC): Colour, stereo, 35° FOV;
One High-Resolution Camera (HRC): Colour, 5° FOV
One IR spectrometer (ISEM): 1° FOV.



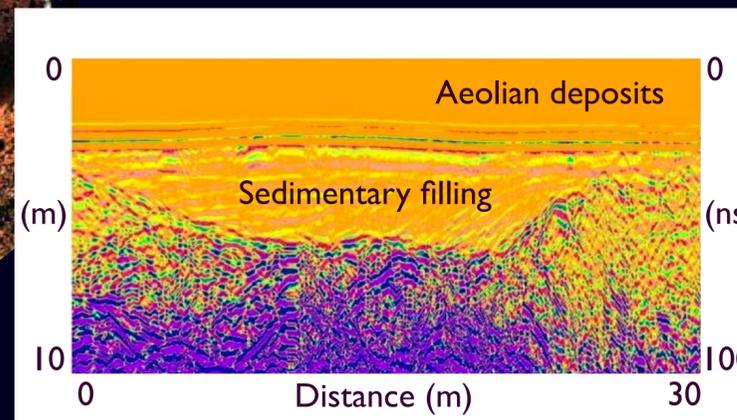
Neutron Detector

Ground Penetrating Radar

~3-m penetration, with ~2-cm resolution
(depends on subsurface EM properties)

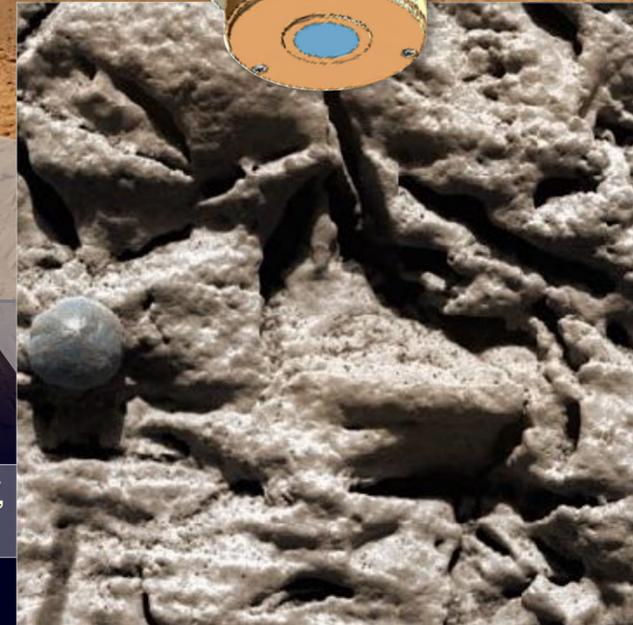
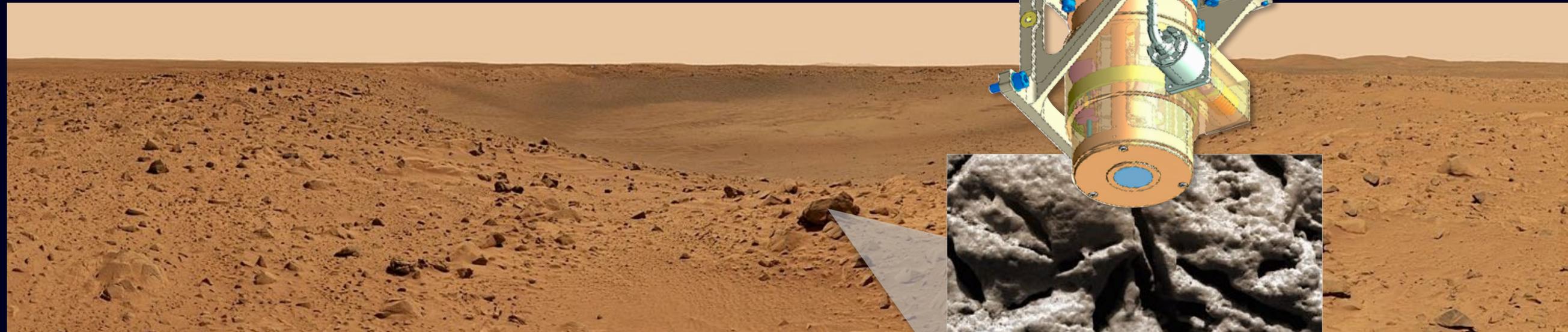


AT DEPTH: To study the stratigraphy for drilling



Heggy et al. 2007

AT ROCK SCALE: To ascertain the past presence of water
For a more detailed morphological examination



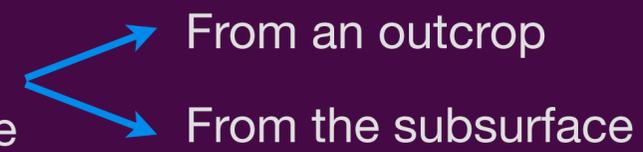
High-Resolution Camera

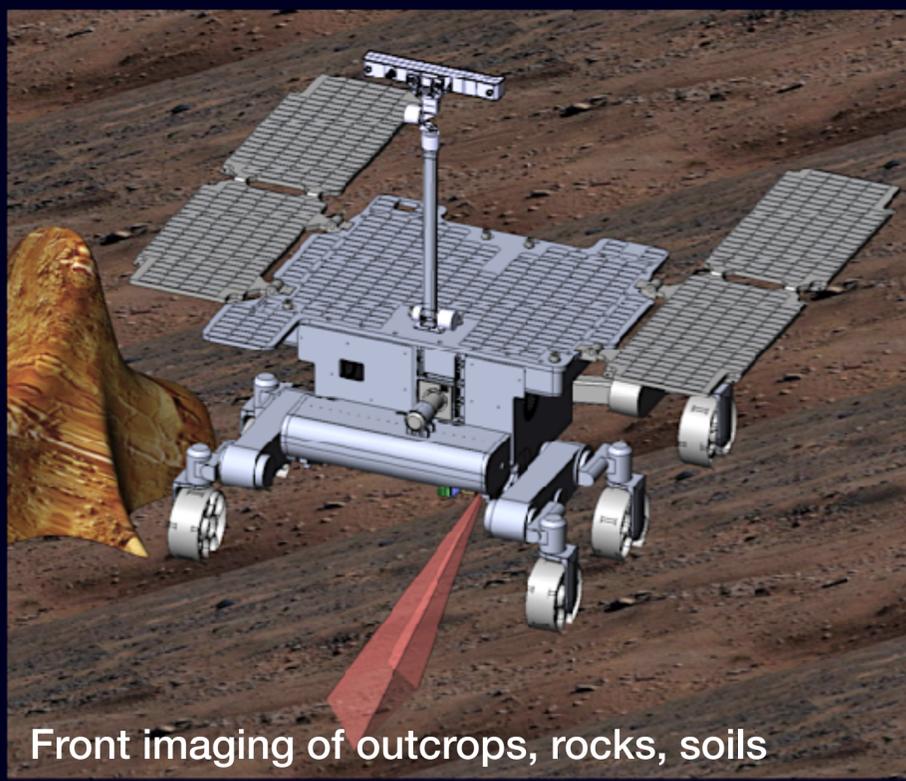
Close-Up Imager

Colour, 20–100- μm /pixel resolution, 19° FOV,
Focusing range: 10 cm to ∞

Next step: **ANALYSIS**

Use the drill to collect a sample

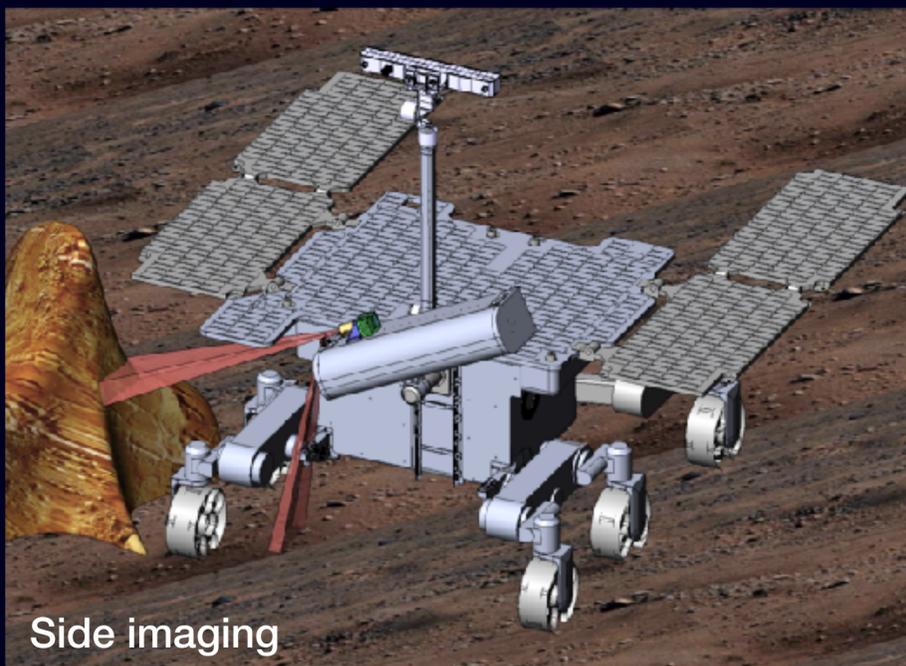




Front imaging of outcrops, rocks, soils



Image collected samples



Side imaging

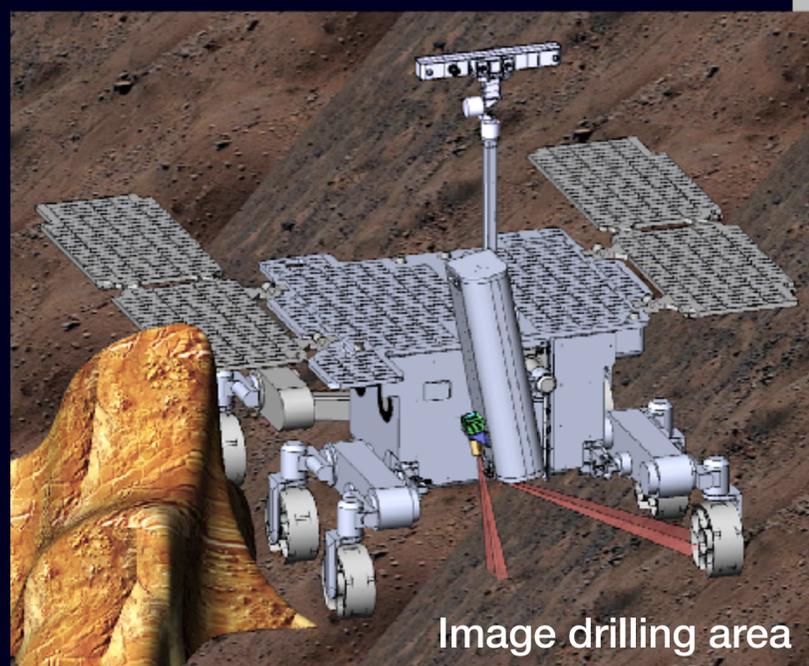
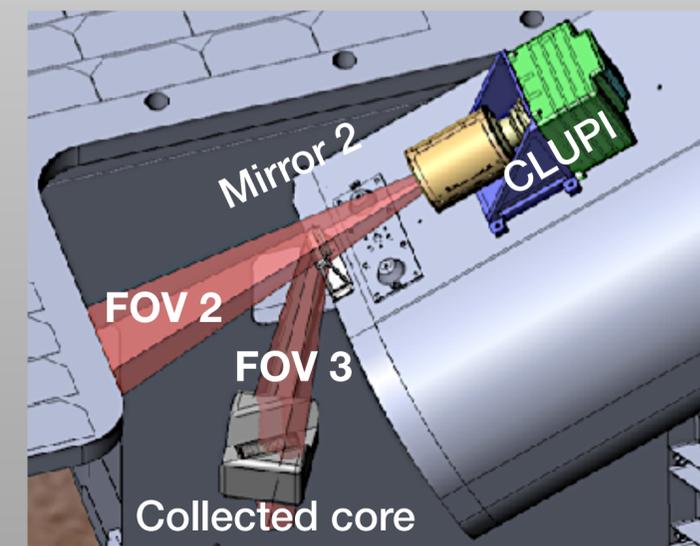
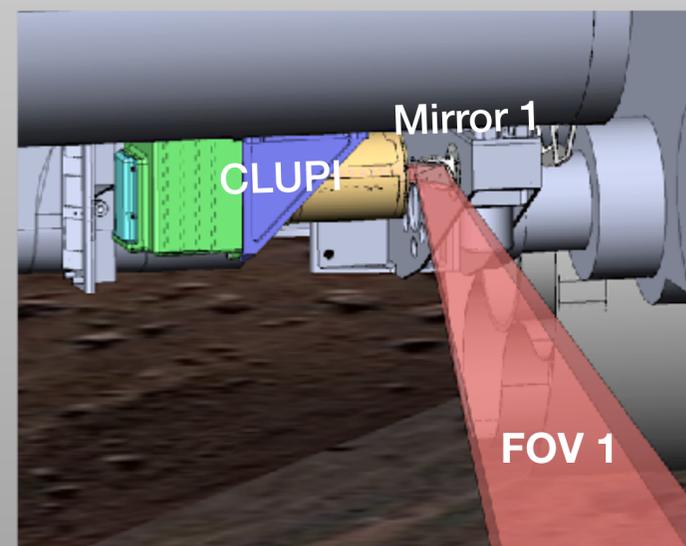
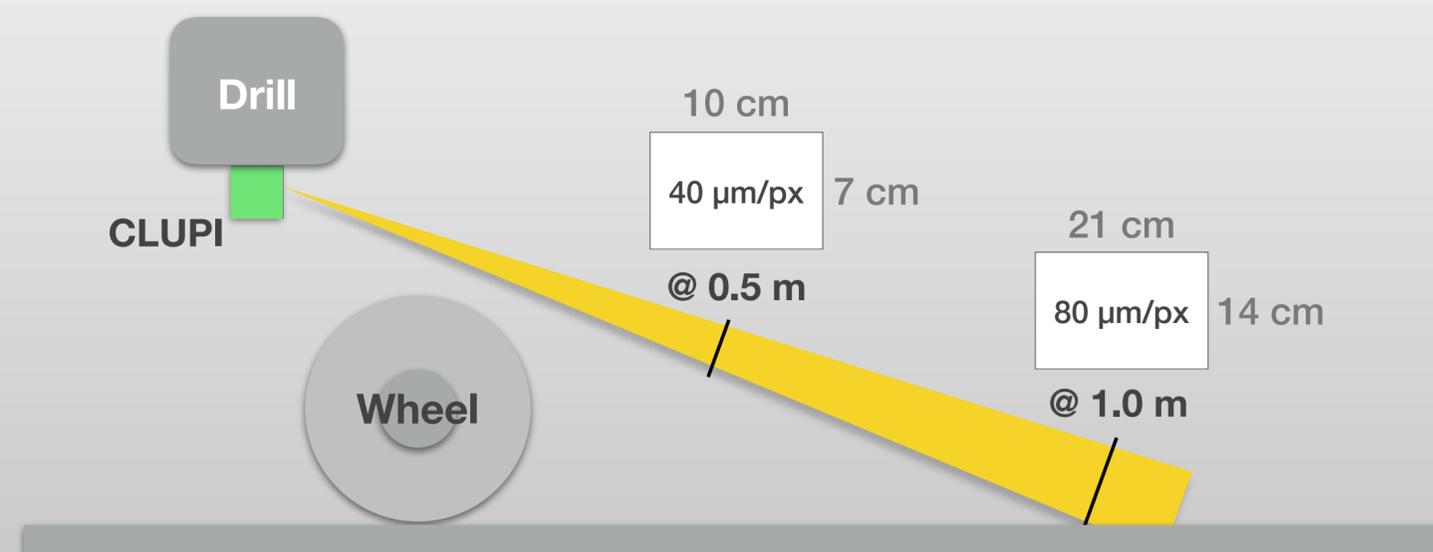
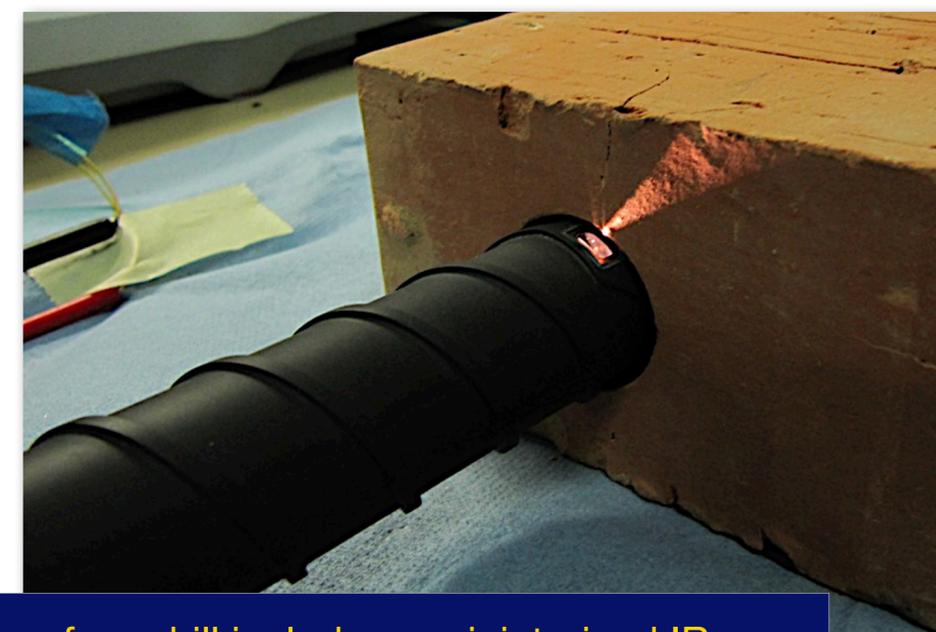
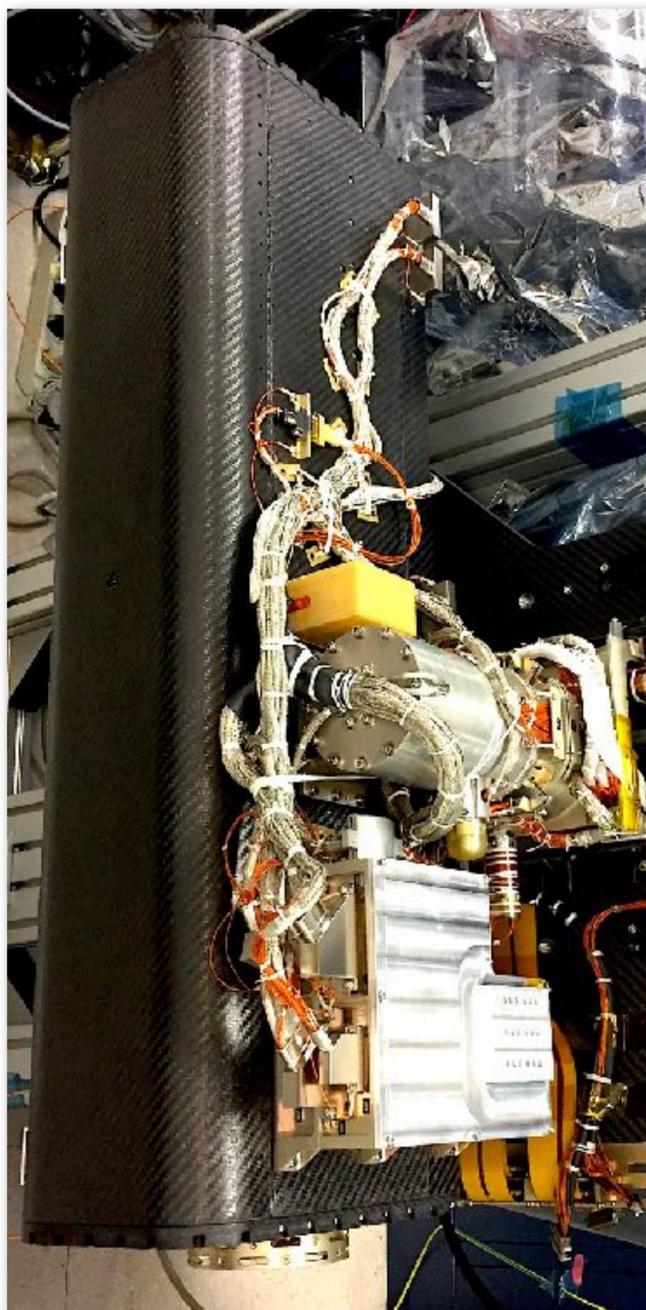


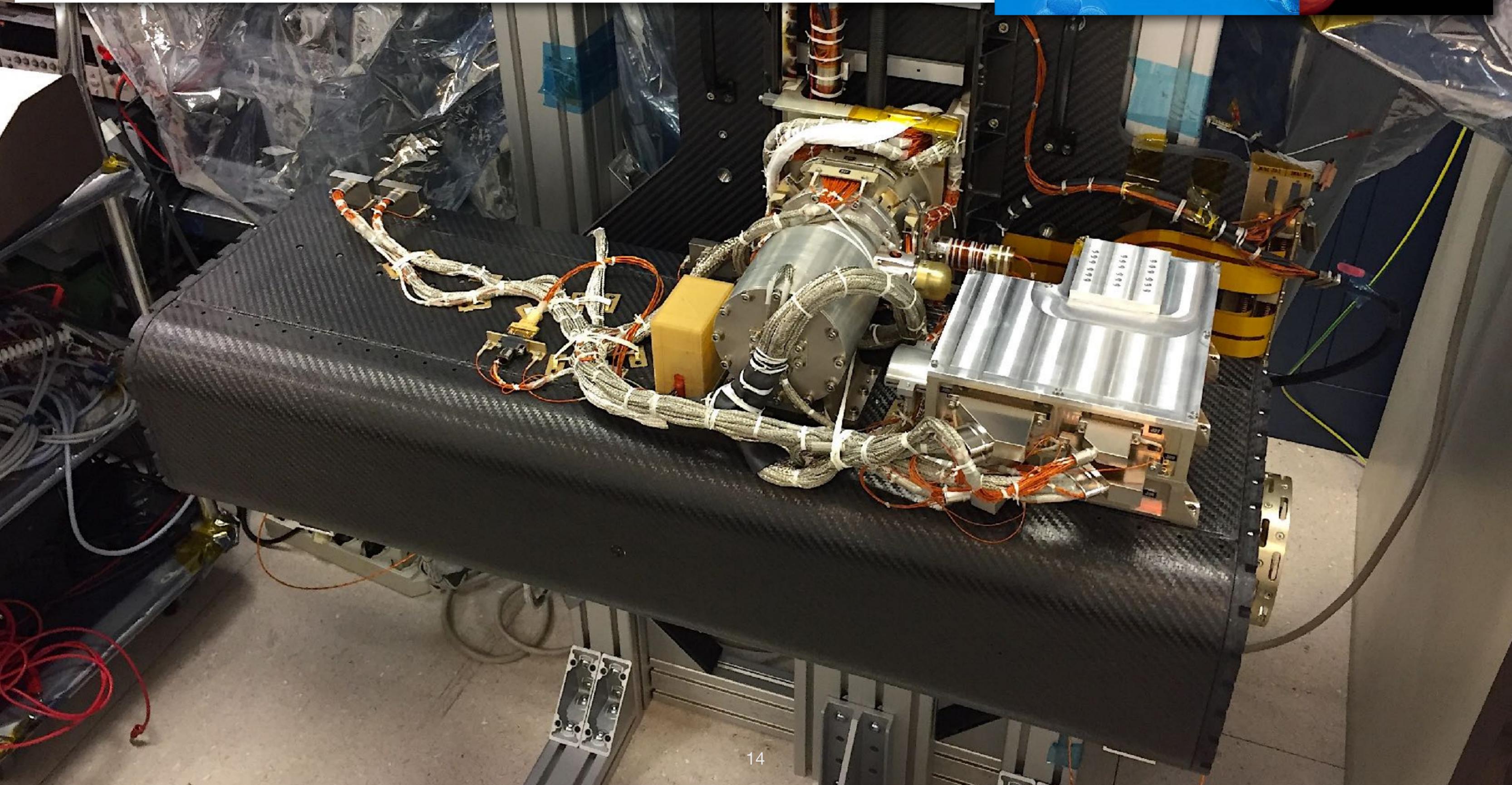
Image drilling area



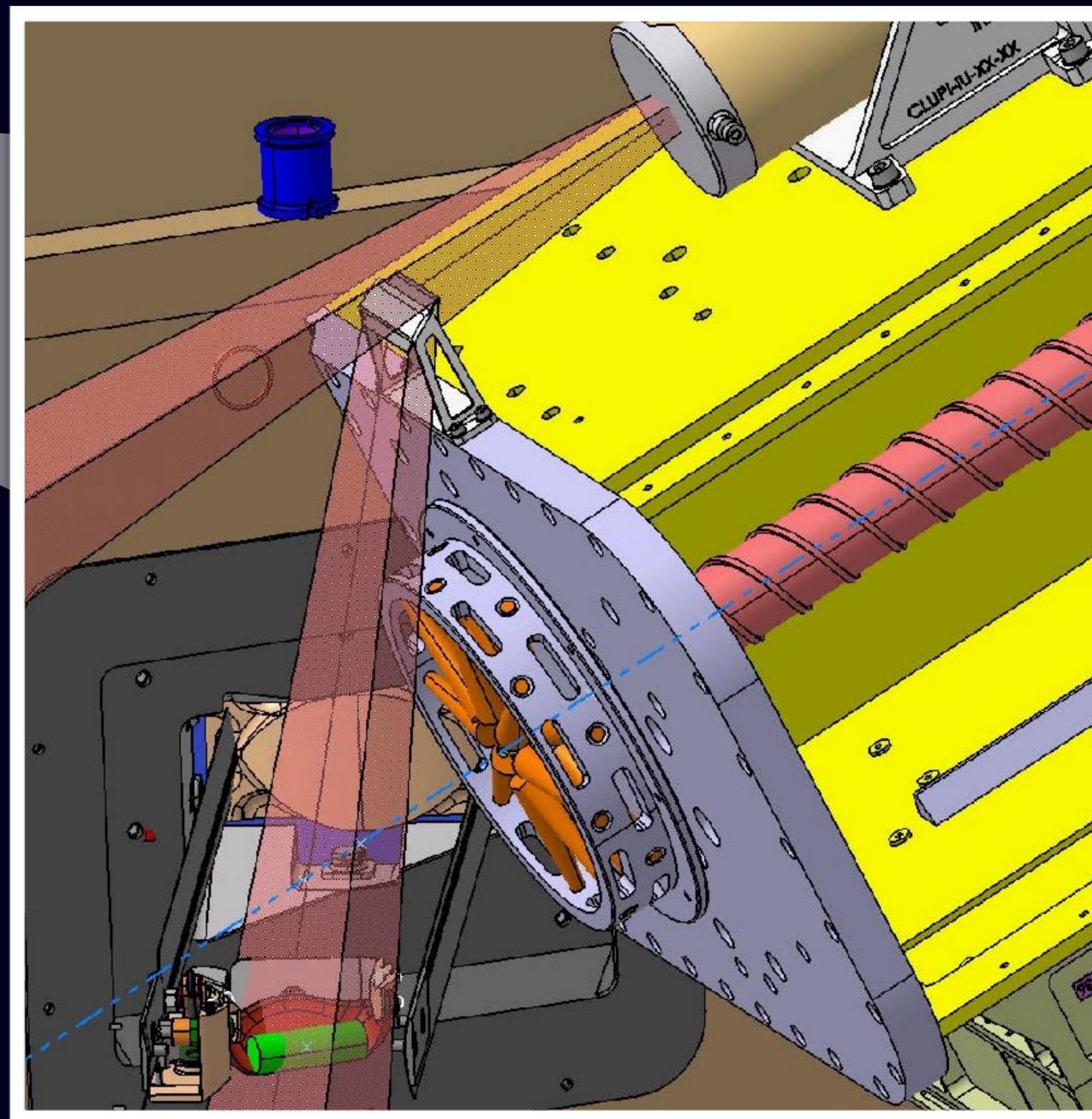
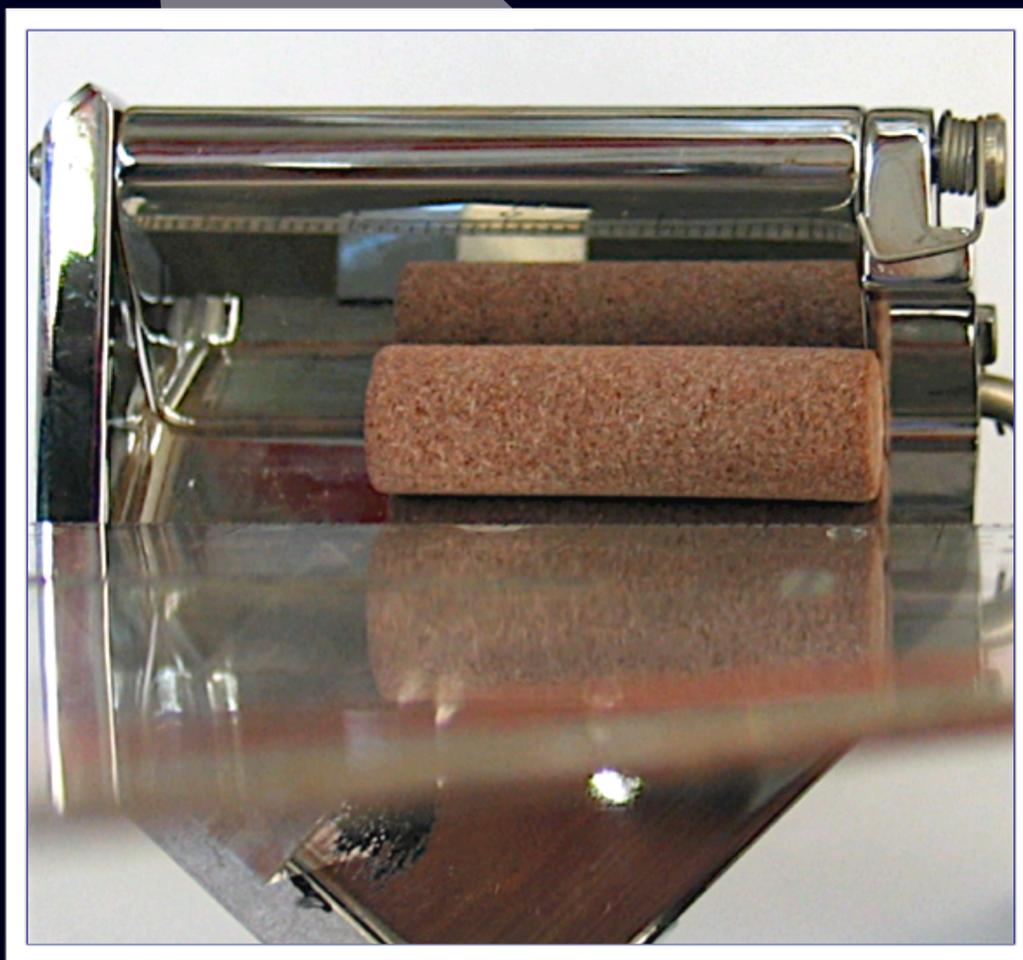
OBTAIN SAMPLES FOR ANALYSIS: From 0 down to 2-m depth

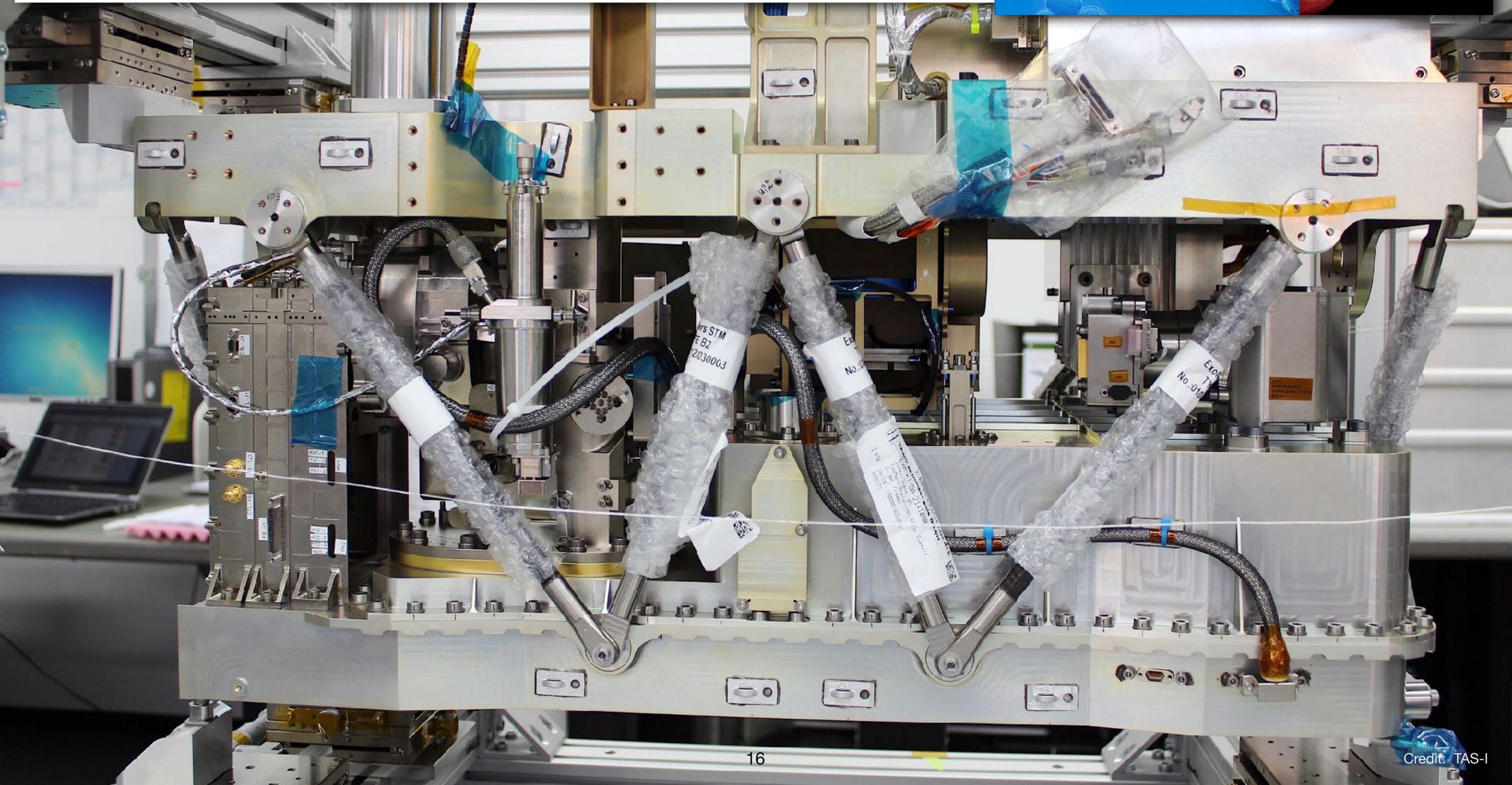


Subsurface drill includes a miniaturised IR spectrometer for borehole investigations.

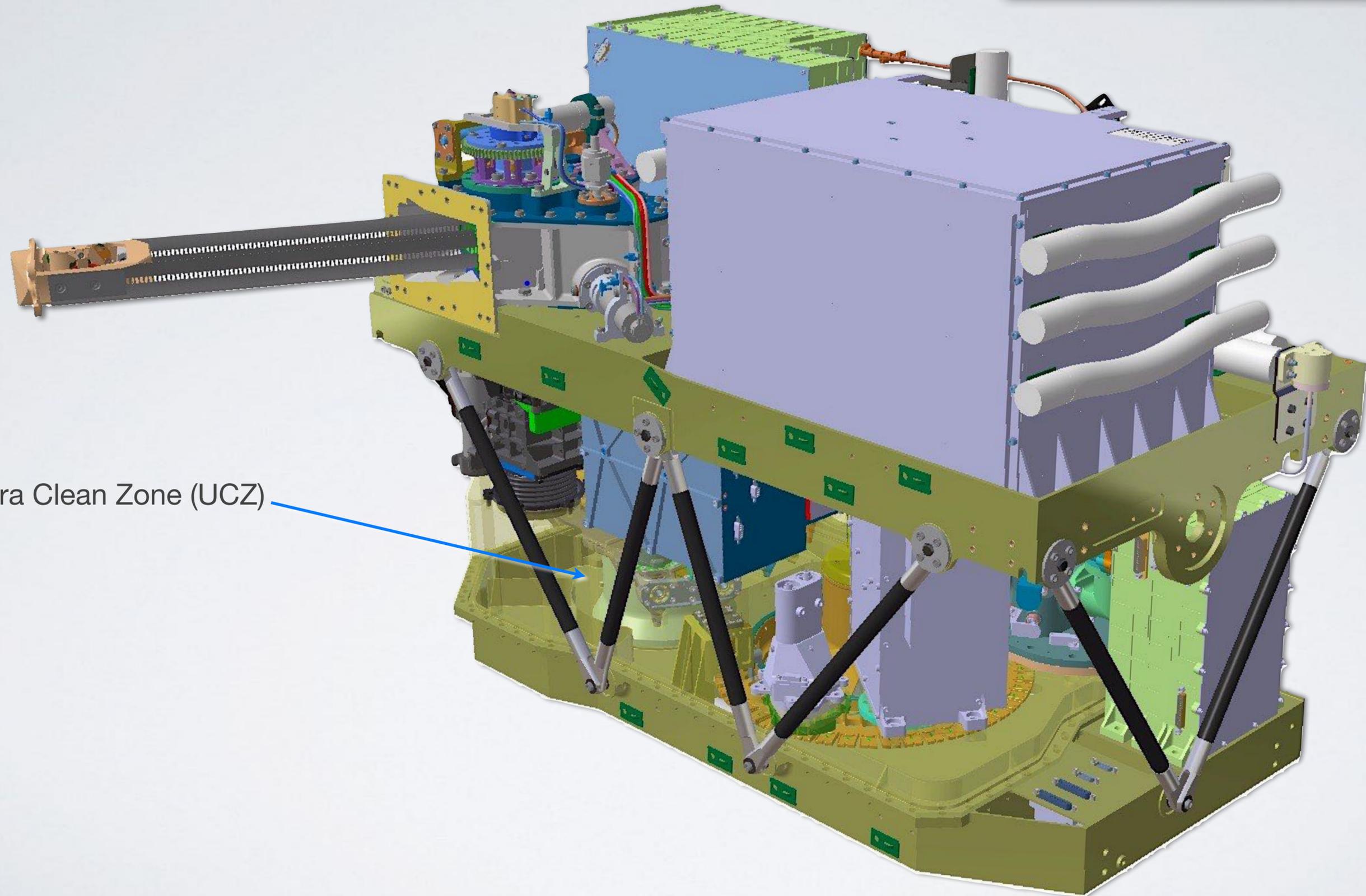


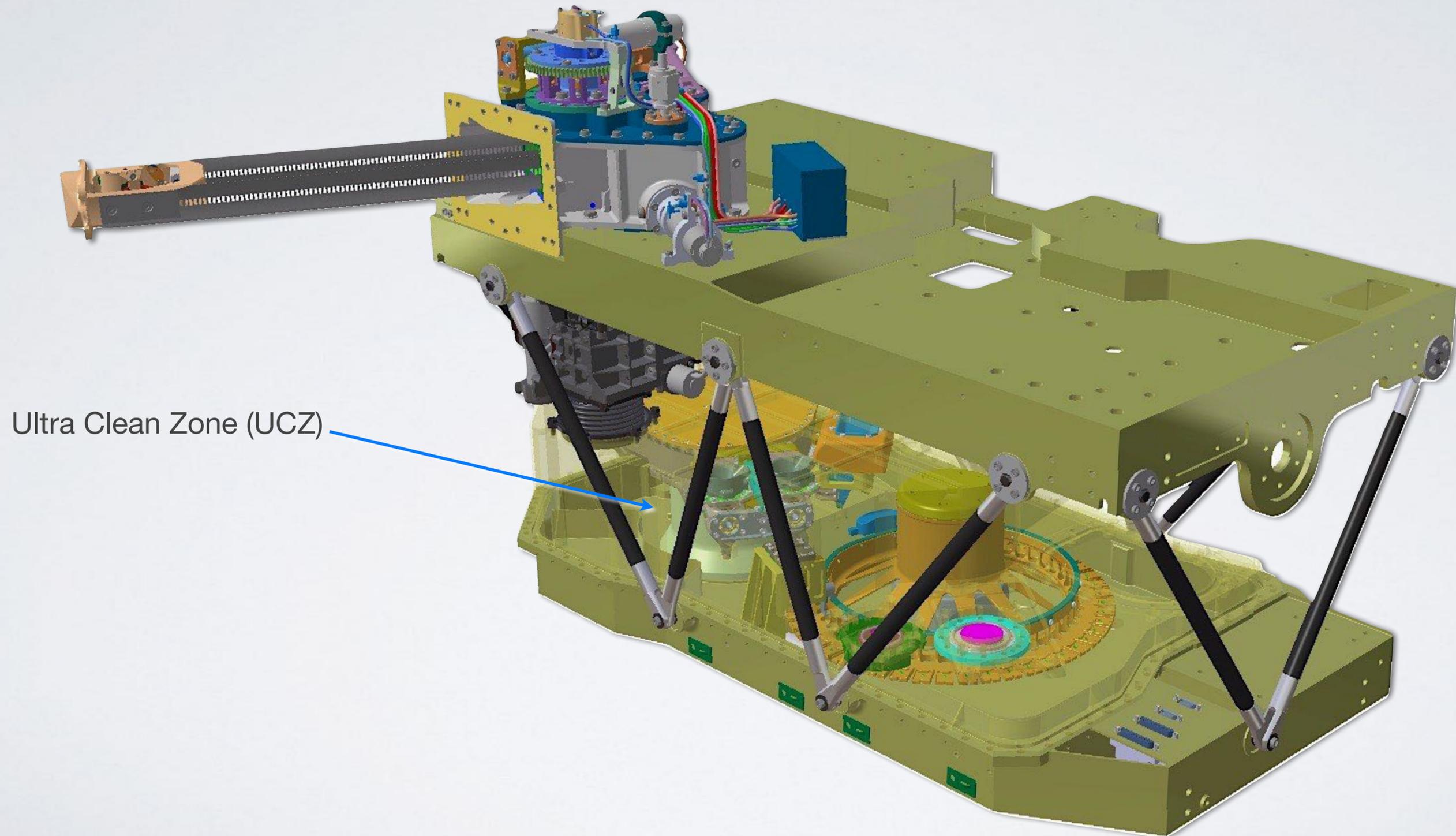
DRILL discharges sample into Core Sample Transport Mechanism (CSTM).
 PanCam HRC and CLUPI image the sample.
 Sample is delivered to Analytical Laboratory Drawer (ALD) — 15 min.

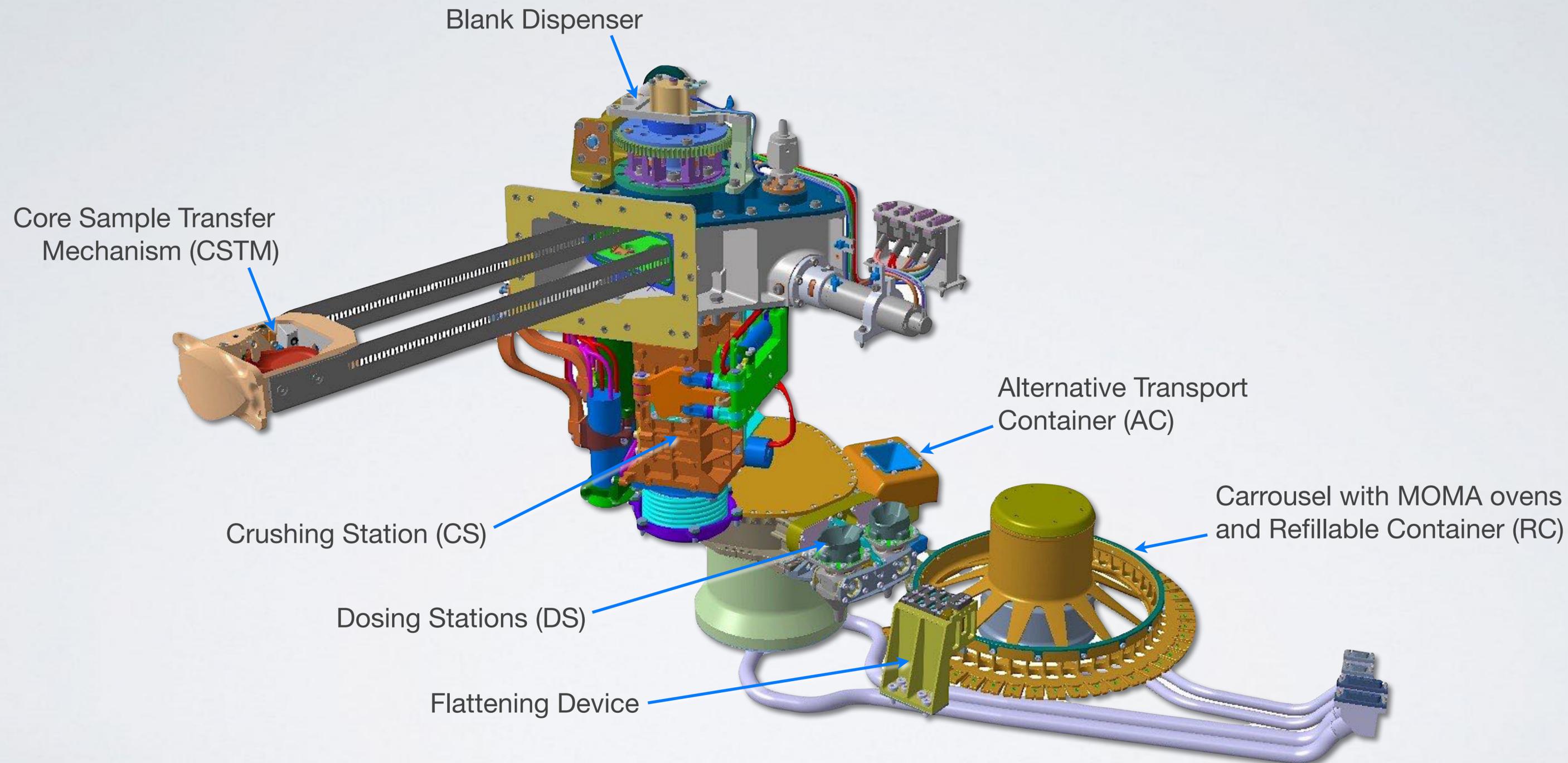


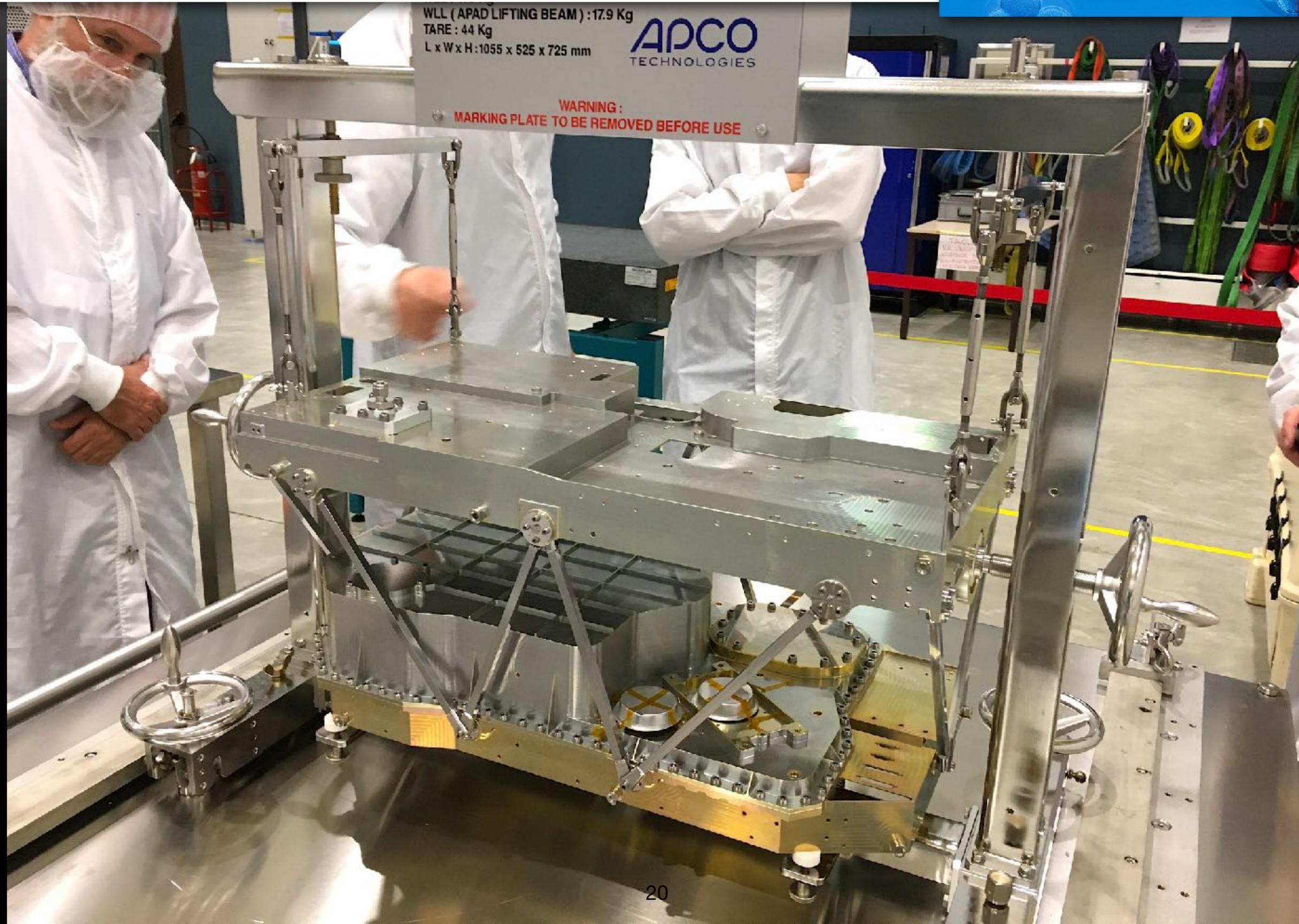


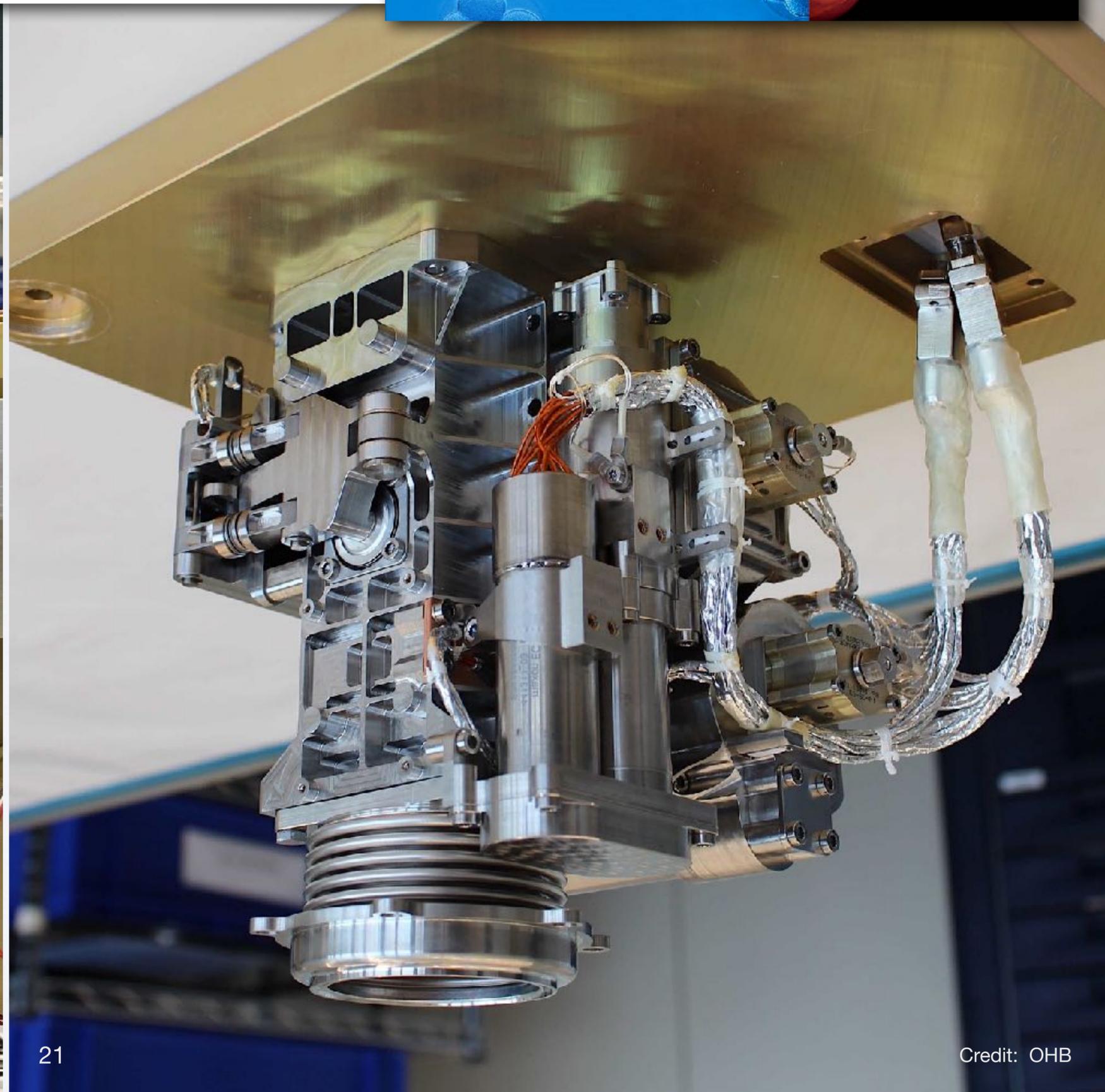
Ultra Clean Zone (UCZ)

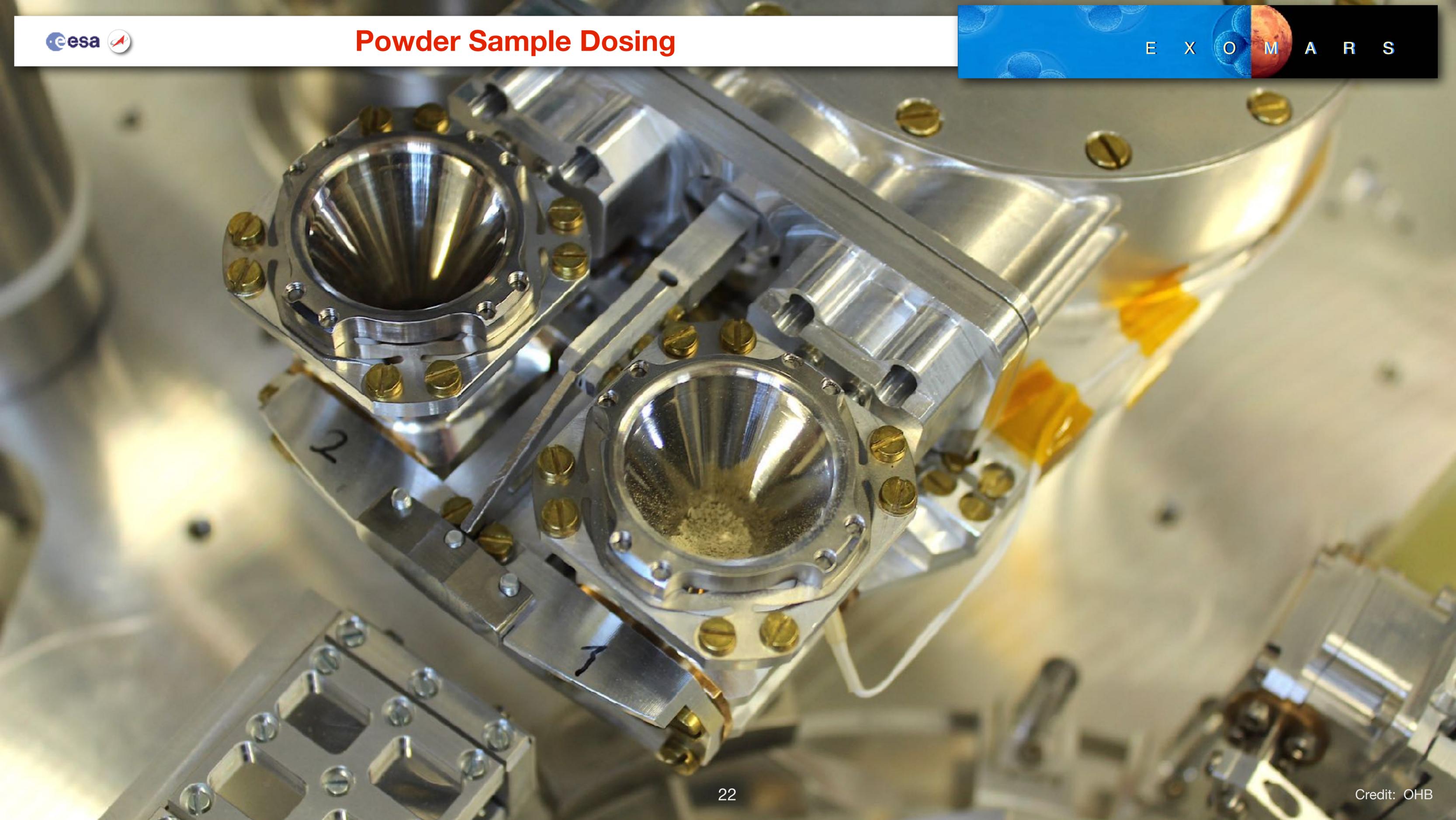






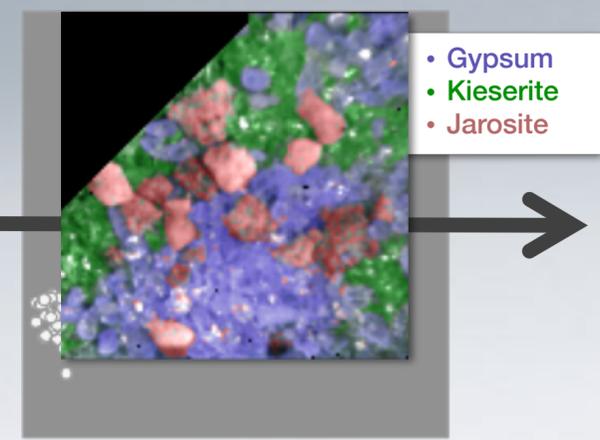
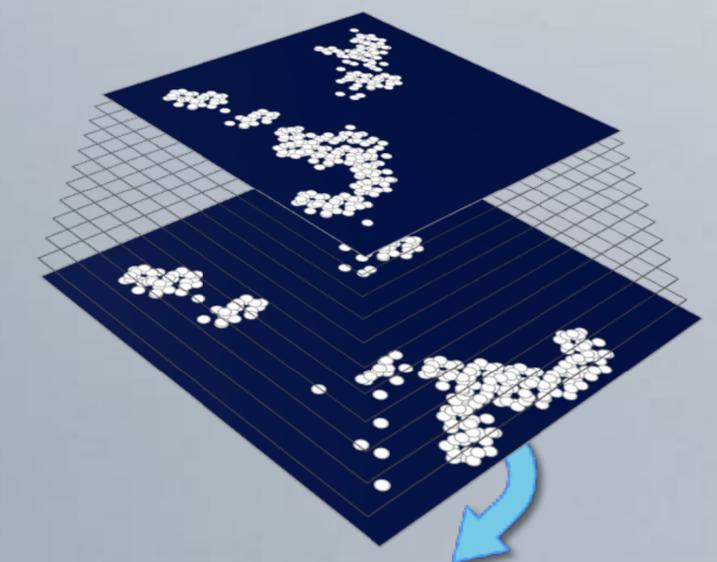






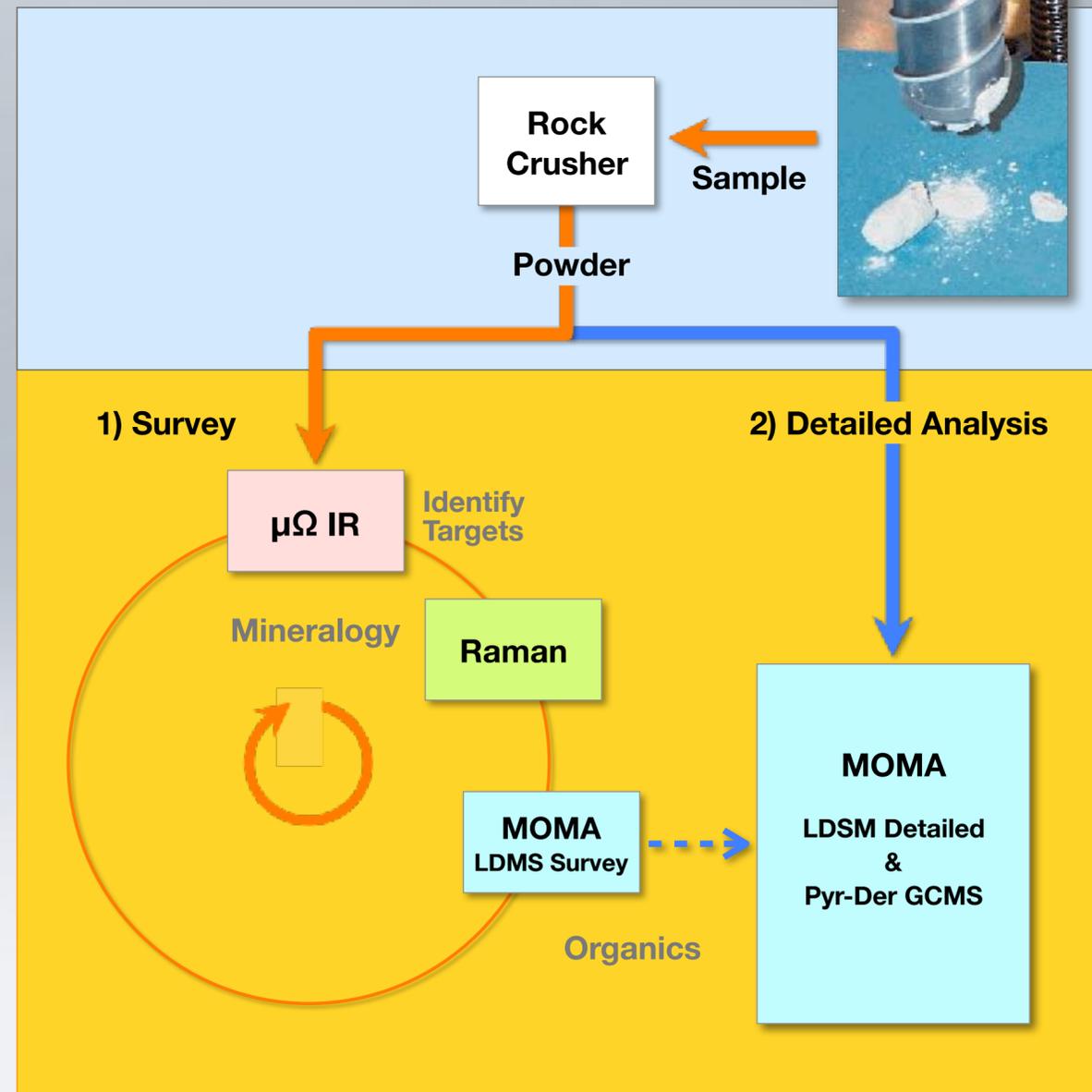
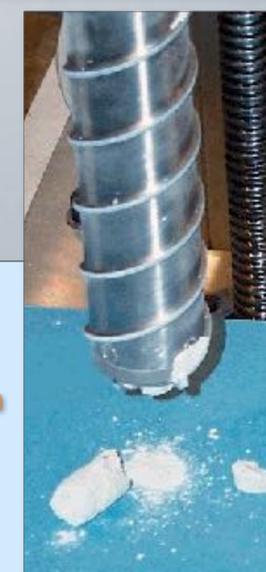
Use mineralogical + image information from $\mu\Omega$ to identify targets for Raman and MOMA-LDMS.

Imaging VIS + IR spectrometer:
256 x 256 pixels, 20 μm /pixel resolution,
0.95–3.65 μm spectral range, 320 steps

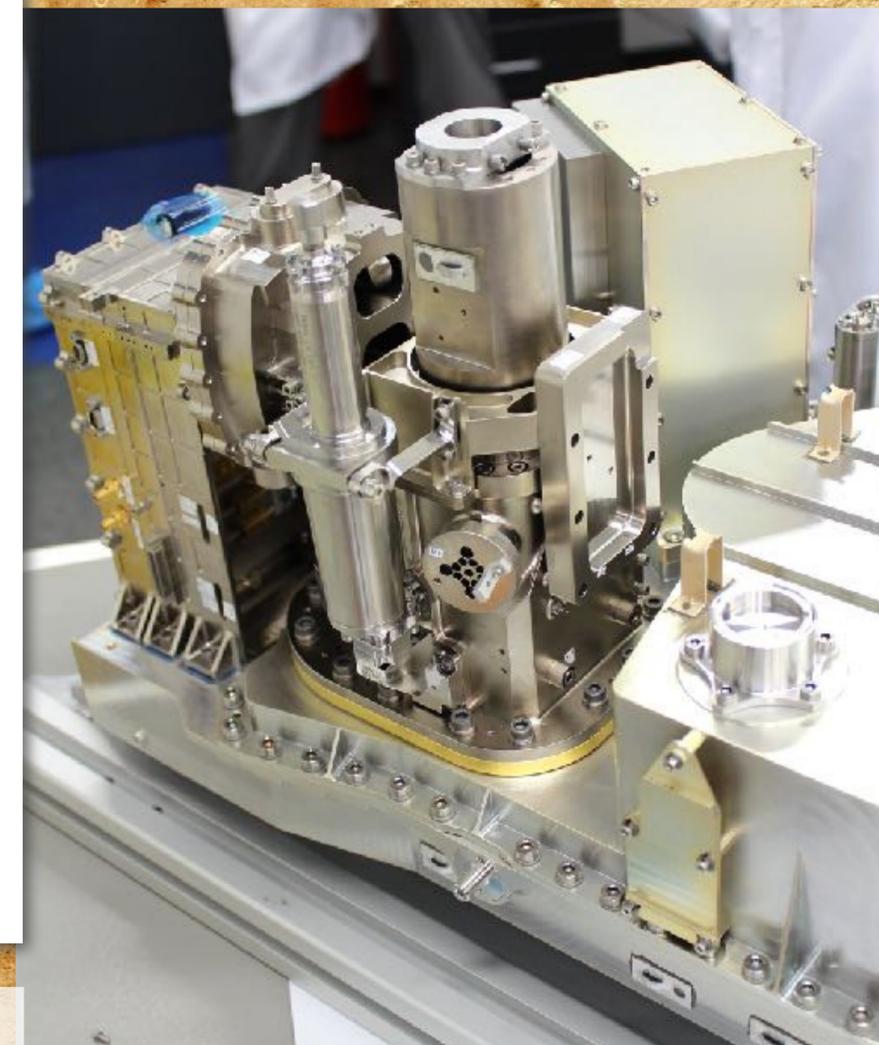
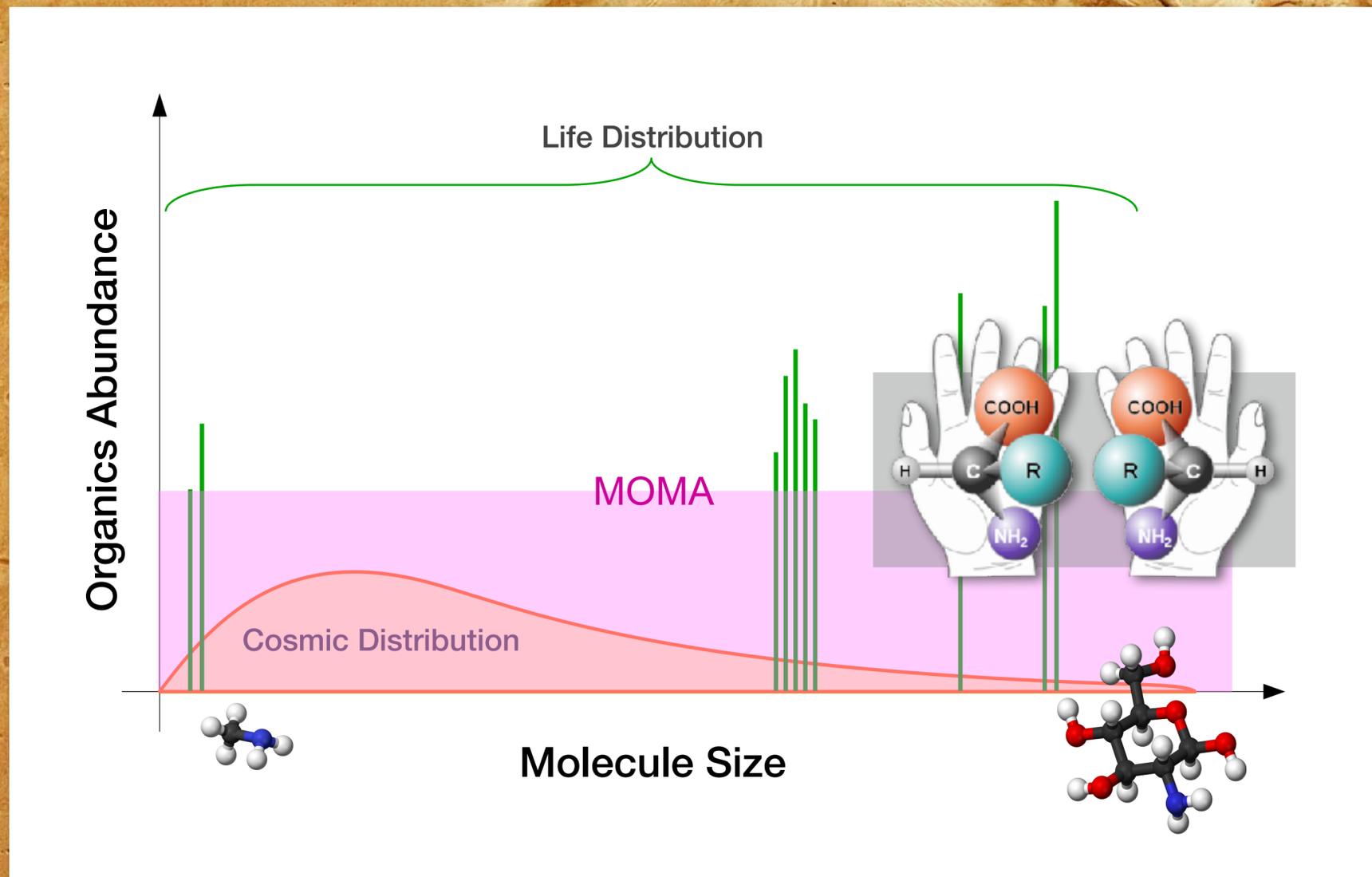


- $\mu\Omega = 20 \mu\text{m}$
- Raman = 50 μm
- LDMS = 400 μm

Raman: Spectral shift range 200–3800 cm^{-1}
Spectral resolution: 6 cm^{-1}



LDMS = Laser Desorption Mass Spectrometry
GCMS = Gas Chromatograph Mass Spectrometer



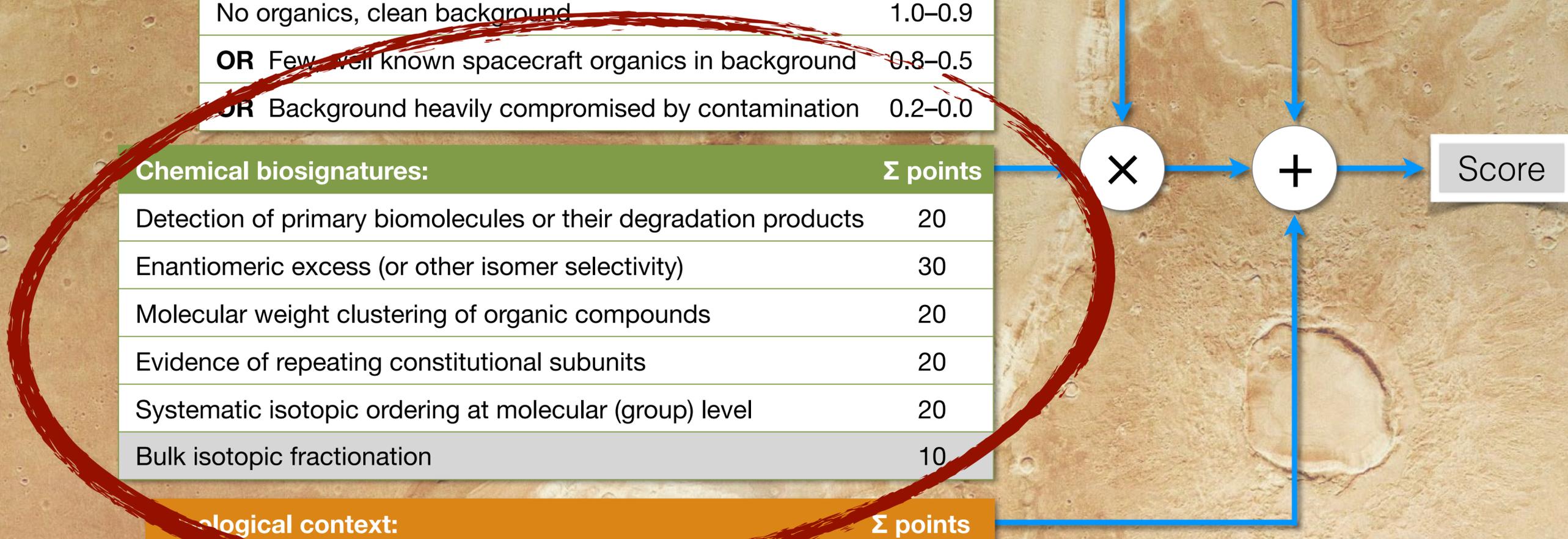
Broad identification range (50–1000 Da), including distribution, and chirality.
 High sensitivity (≤ 1 pmol/mol in TV-CGMS, ≤ 1 pmol/mol/mm² in LDMS).
 Resolution ≤ 1 Da over 50–500 Da range, ≤ 2 Da thereafter.
 Ability to perform MS-MS analysis on trapped fragments.
 LDMS mode appears not to be disturbed by perchlorates.

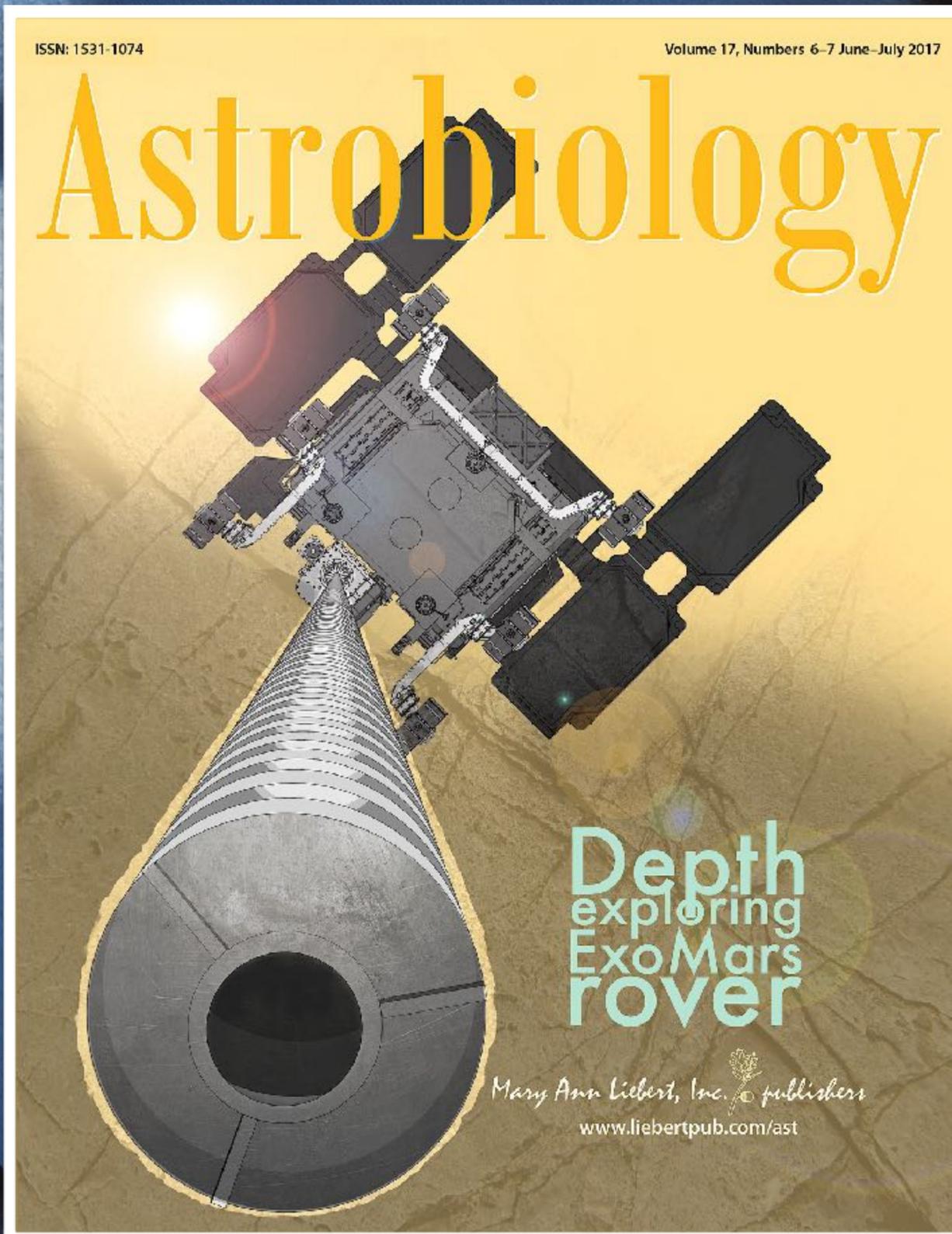
Morphological biosignatures:	Σ points
Multilayer organosedimentary structures (e.g. stromatolites)	20
Other candidate biomediated textures (e.g. MISS)	10
Features suggestive of (fossil) microorganisms	20

Result of first blank chemical check: (prior to beginning sample analysis)	Factor
No organics, clean background	1.0–0.9
OR Few well known spacecraft organics in background	0.8–0.5
OR Background heavily compromised by contamination	0.2–0.0

Chemical biosignatures:	Σ points
Detection of primary biomolecules or their degradation products	20
Enantiomeric excess (or other isomer selectivity)	30
Molecular weight clustering of organic compounds	20
Evidence of repeating constitutional subunits	20
Systematic isotopic ordering at molecular (group) level	20
Bulk isotopic fractionation	10

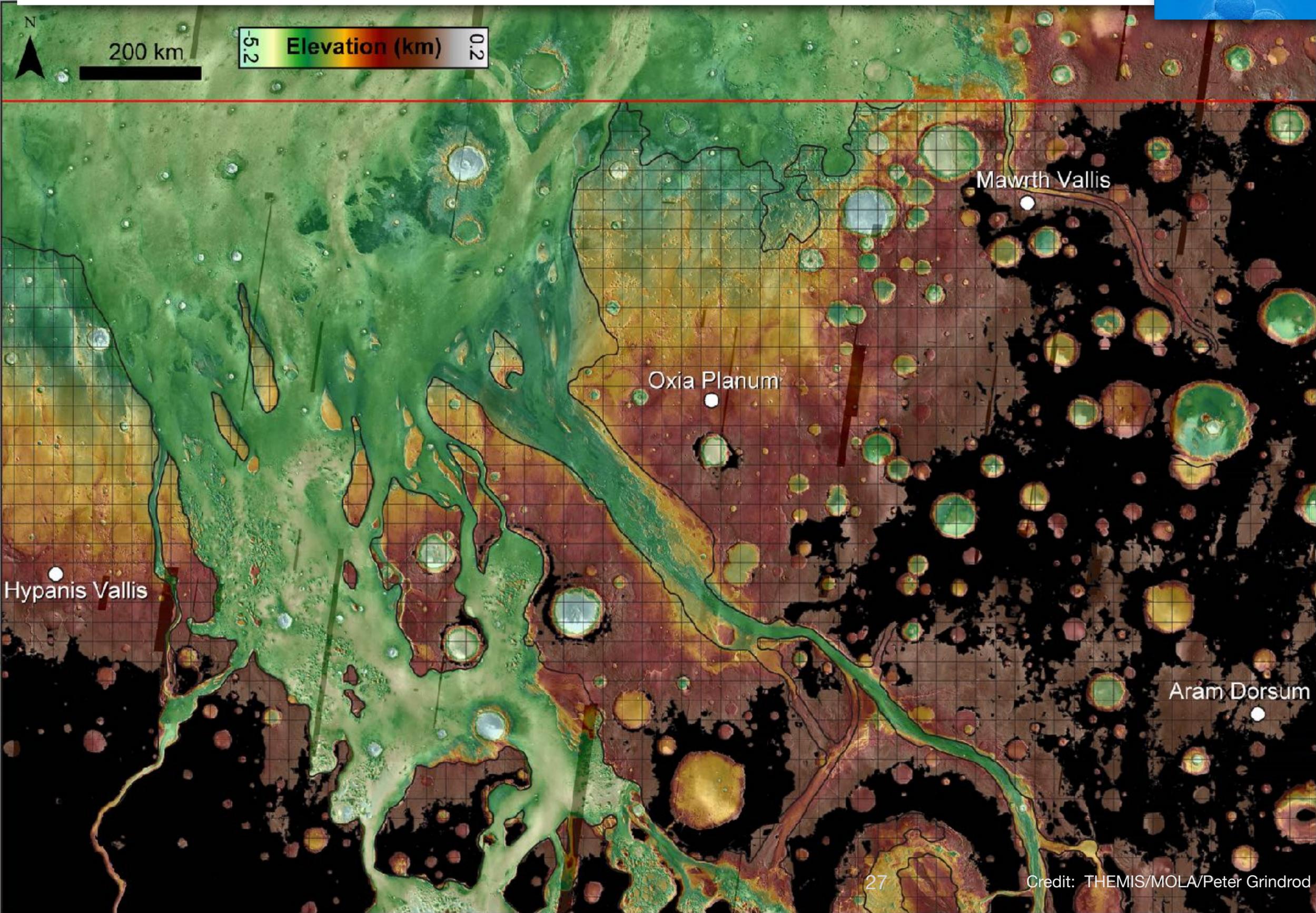
Geological context:	Σ points
Long-lived water or hydrothermal setting (morphology)	15–10
Long-lived water or hydrothermal setting (mineralogy)	15–10





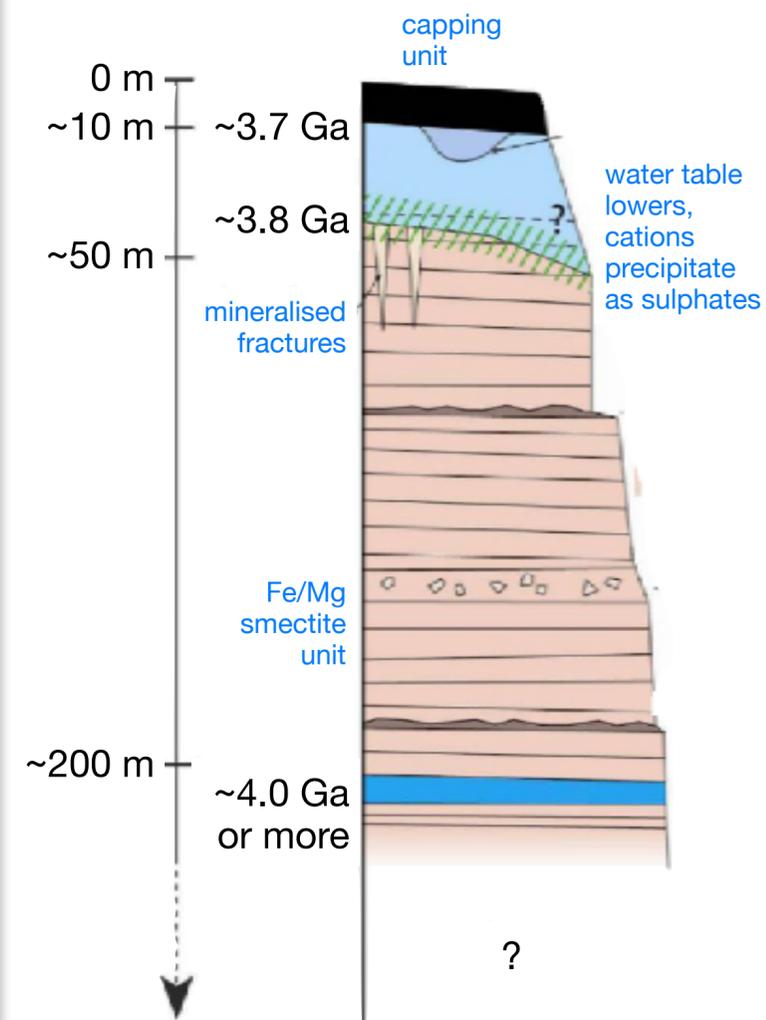
ExoMars Rover Issue

- ▶ *Astrobiology*, June–July 2017
- ▶ Introduction paper describing the ExoMars rover science and mission.
- ▶ A dedicated paper for each of the nine instruments.

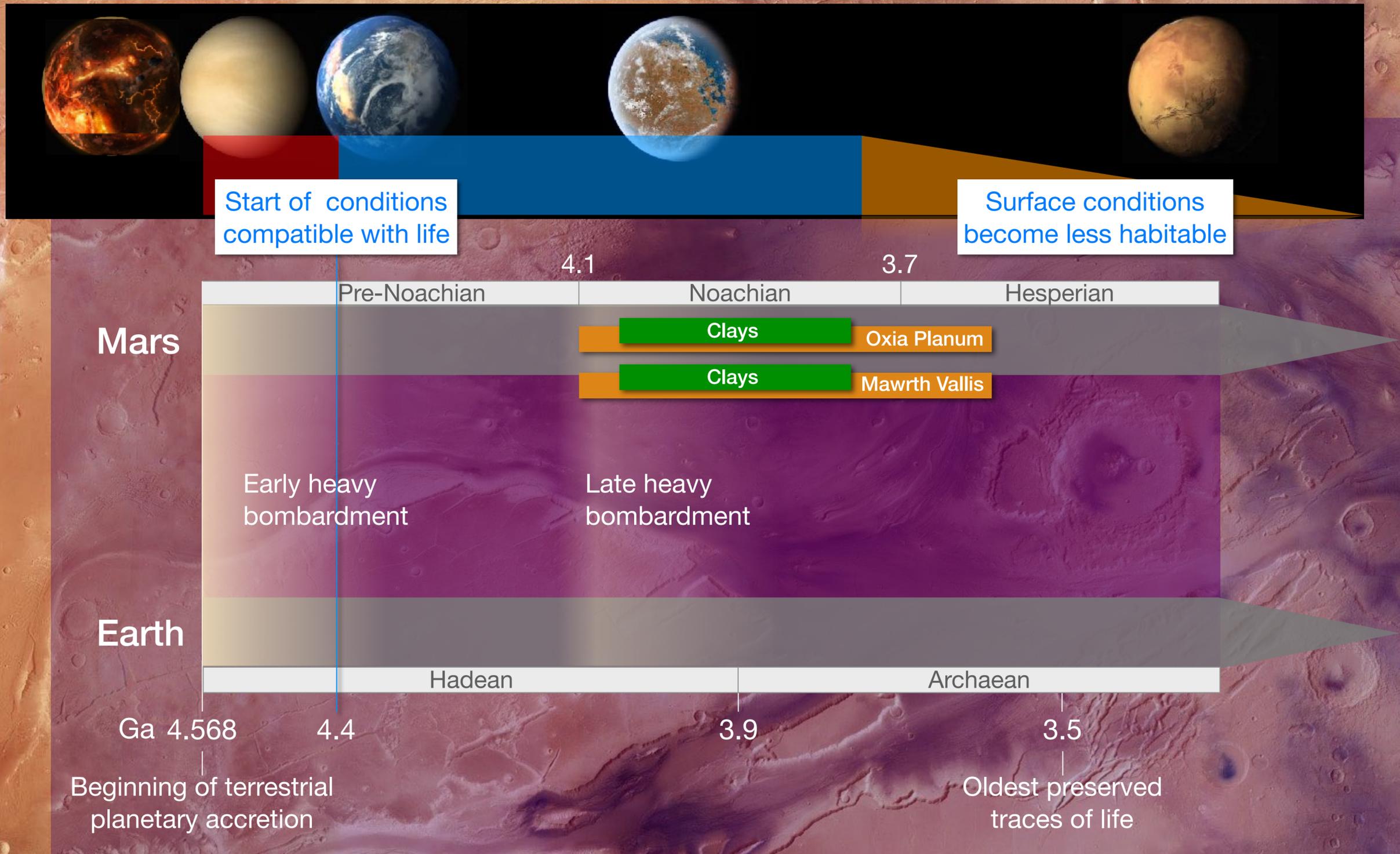


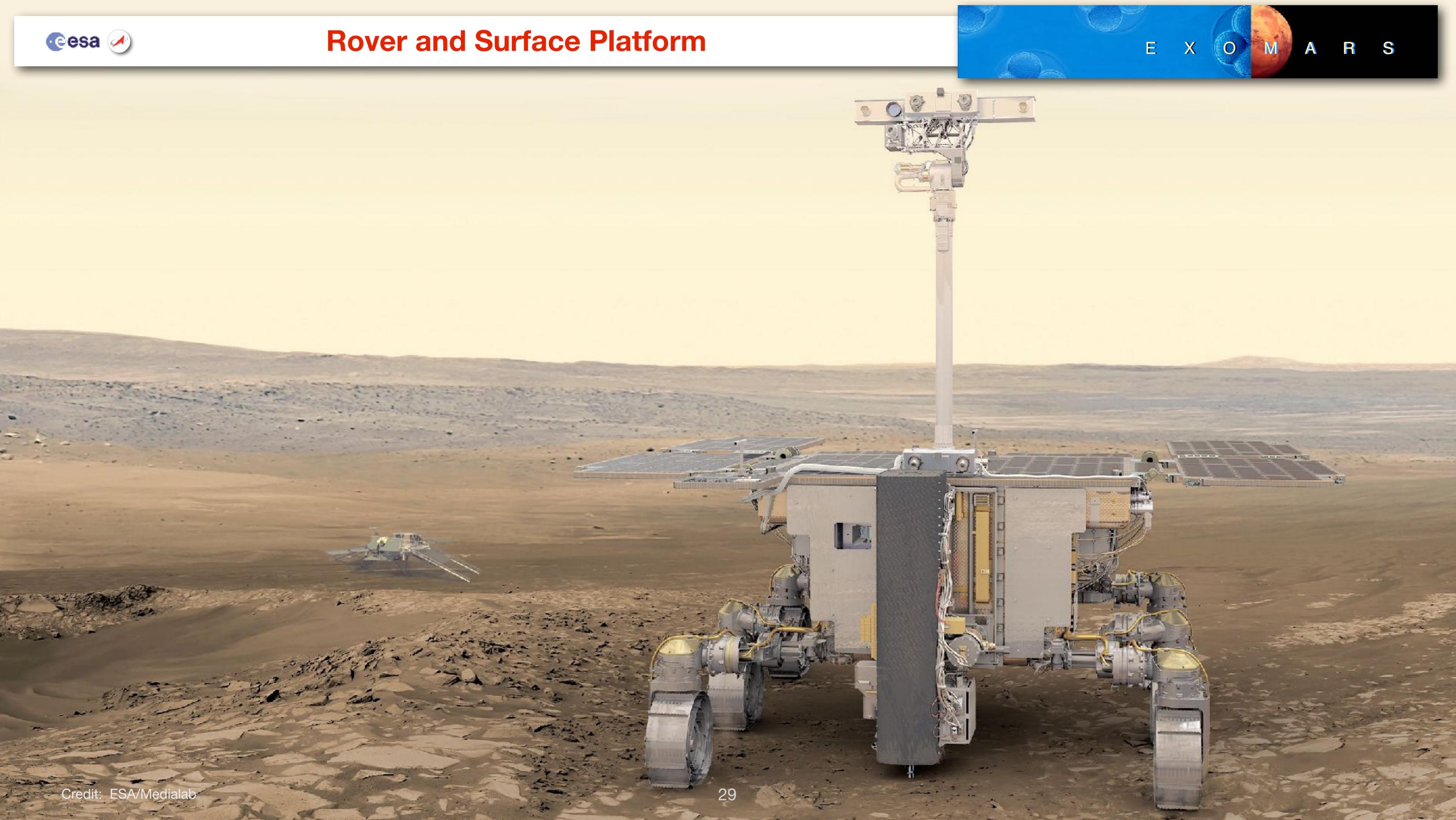
Candidate landing sites:

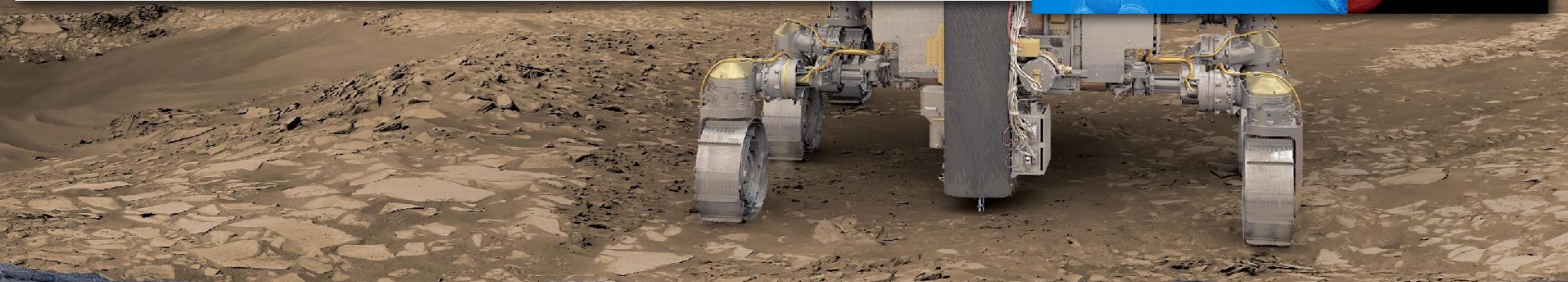
Oxia Planum
Mawrth Vallis



Oldest terrains to be targeted







▶ **2020: ExoMars Rover and Surface Platform**

- Travel back in time 4 billion years to explore the bottom of a Mars ocean.
- Drill deep to penetrate below the organics degradation horizon.
- Look for traces of life beyond Earth.
- Study the surface geology and environment.
- Obtain results that may make MSR and astronaut missions possible.

2-m depth