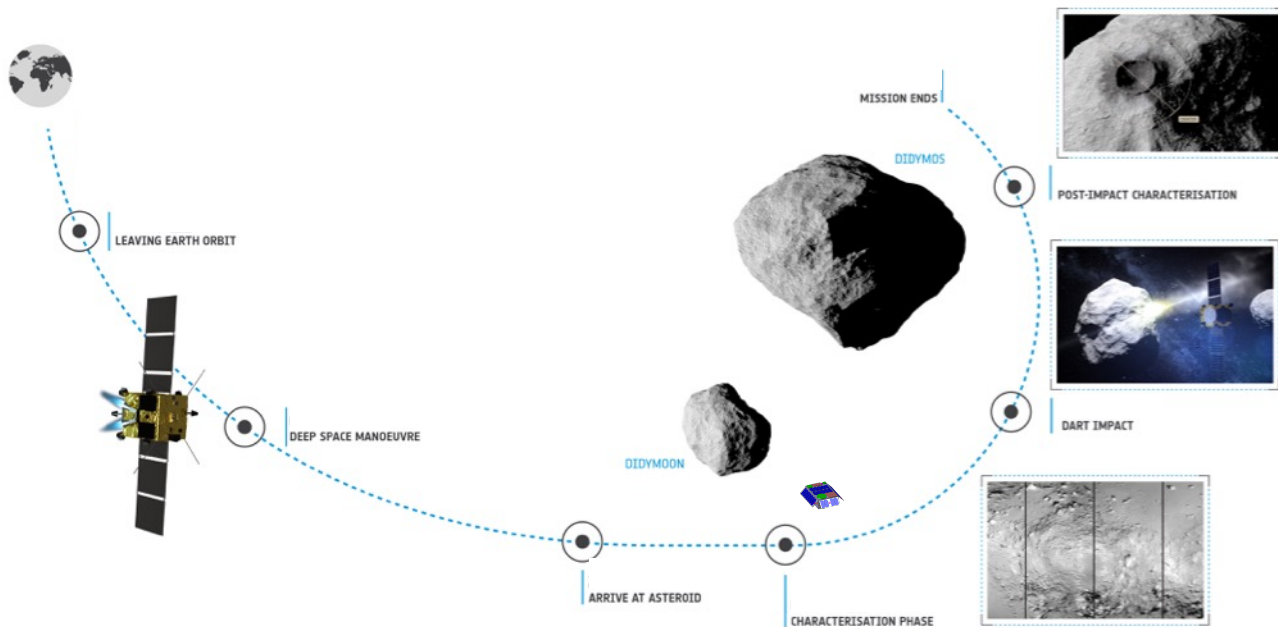


→ HERA MISSION

- (CM16) Schedule criticality for 2020 launch
  - Prepare Asteroid mission with **launch opportunities in 2023** (with **back-up in 2024 and 2025**)
- (CM16) Payload selection unclear
  - **Optimal payload** defined + **JAXA impactor** (option), focus on planetary defense objectives (primary).
- (CM16) DART status not sufficiently clear
  - Maintain cooperation with **NASA** now in **phase B** demonstrating kinetic impactor
- (CM16) **Budget shortage** and **CaC consolidation**
  - Perform **phase B1** in **SSA** + **GSTP** to prepare for CM19. Bilaterals with MS to consolidate interests before ITT in 1Q18. Establish a planetary defense initiative.

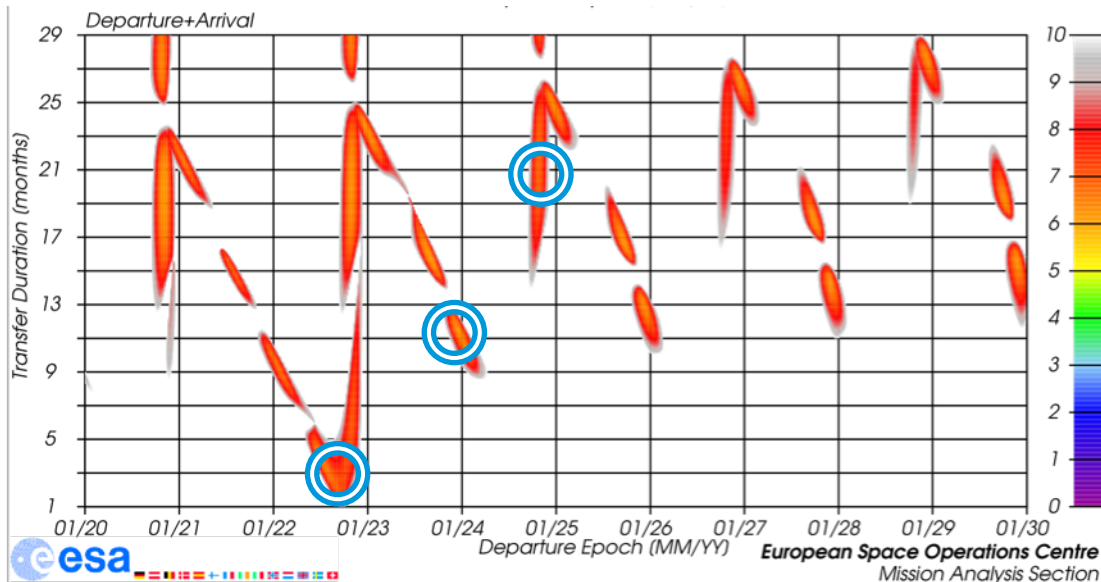
# HERA mission scenario

- First ever investigation of deflection test
- Detailed analysis of impact crater
- First deep-space CubeSat
- First binary asteroid and smallest ever asteroid visited



# Target asteroid

- Assess potential optimal binary asteroids among new discoveries
- Didymos still a good target as of 2Q 2017, later launch opportunities:

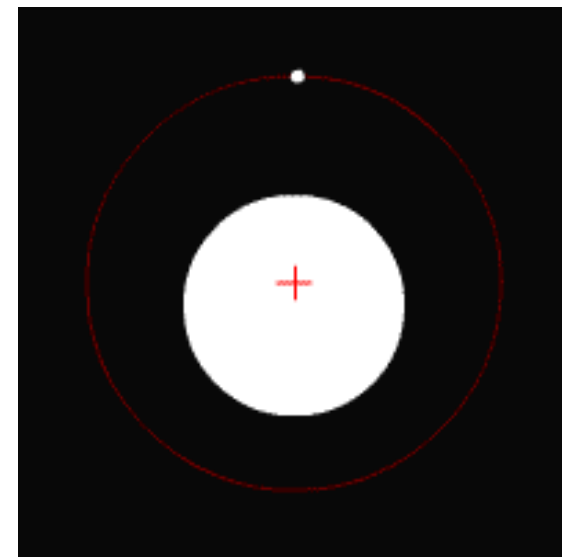
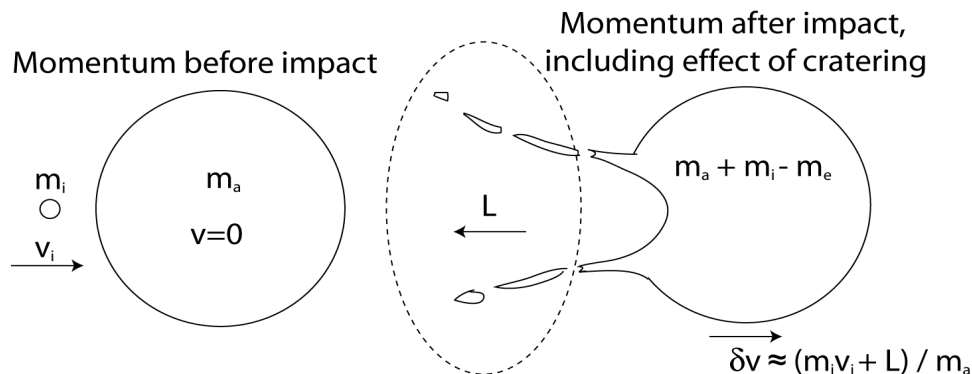


Departure date: **2023/10/22**  
Earth swing-by: 2024/10/26  
Arrival date: 2026/09/02  
Delta-V: 1.405 km/s

Departure date: **2024/10/14**  
Earth swing-by: N/A  
Arrival date: 2026/7/13  
Delta-V: 1.514 km/s

## 1. Measure the momentum transfer from a kinetic impactor on a binary asteroid

- Asteroid mass (*by wobble or radioscience*)
- Asteroid dynamical properties

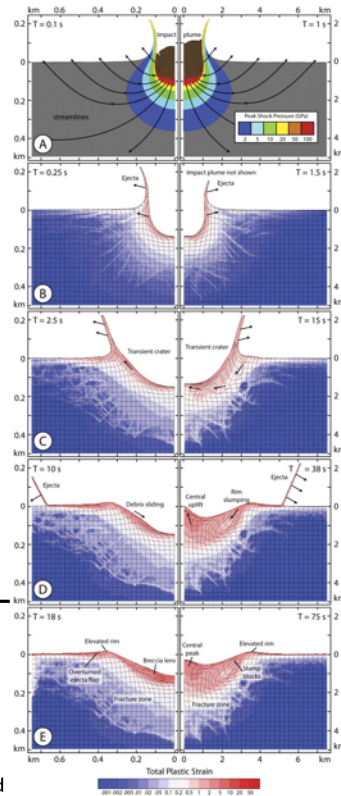
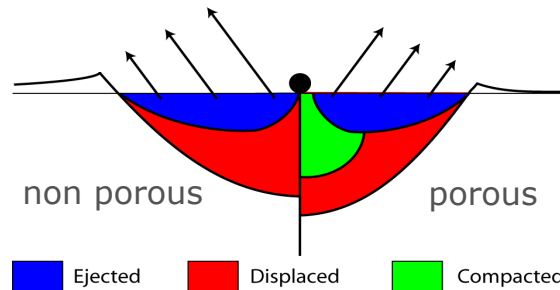
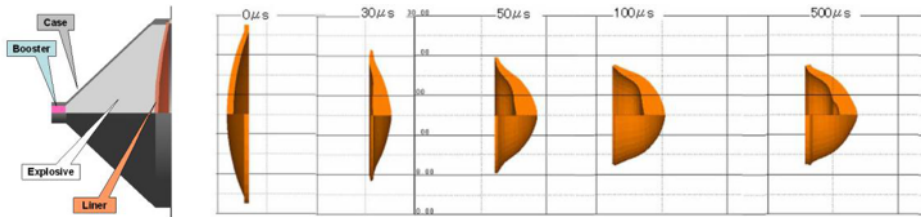




# HERA asteroid deflection objectives

## 2. Impact models validation and extrapolation to other asteroids

- Density
- Crater size/morphology
- Validate *scaling laws* by performing second impact at different energy level with JAXA's S.C.I. payload (part of B1 study)
  - outside experimental range of experience
  - "Ground truth" for numerical models & scaling theory
- *Ejecta size distribution, ejection velocities (bonus)*
- *Change in the surface material (bonus)*



# Measuring crater properties

- Asteroid physical properties related to deflection test do not change over few years
- No erosion, no atmosphere (wind), no outside process (impact, dynamical) of magnitude allowing any change over few years

Demonstration:

- **NASA Deep Impact** mission: impact cratering on the 6 km-size comet Tempel 1 on July 4th, 2005 (but no possibility to measure the crater's properties)
- **NASA Stardust NEXT**: returned to Tempel 1 in 2011 and could measure the crater's properties, although the comet passed its perihelion between the two moments!

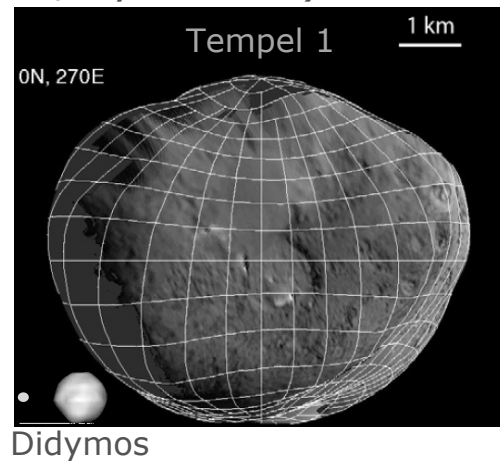


Image taken by Deep Impact  
before its impact on comet  
Tempel 1 (2005)

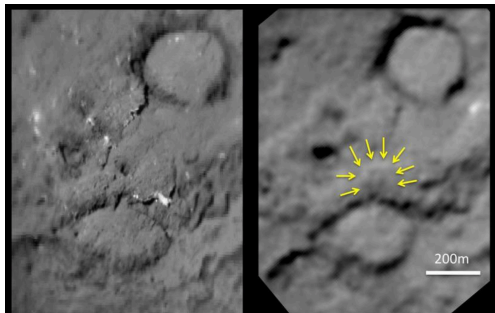


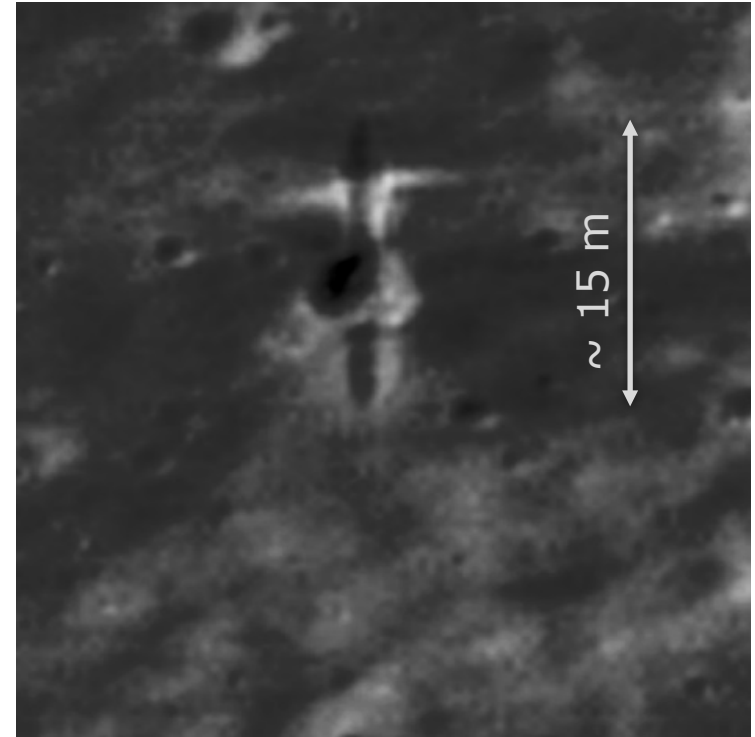
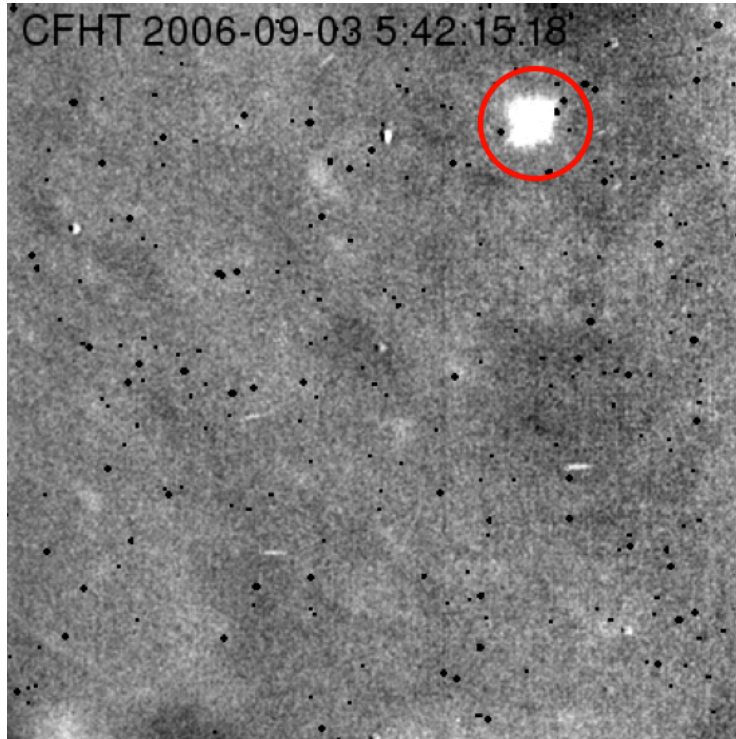
Image taken by Stardust NEXT  
(crater identification) after Tempel  
1 perihelion passage in 2011  
(5 years after the impact)

Credit: NASA/JPL-Caltech/University of Maryland/Cornell

# Measuring crater properties: SMART-1 impact

3 September 2006

Press release 22 September 2017

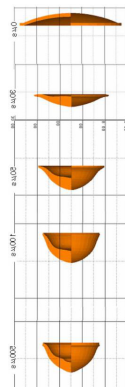
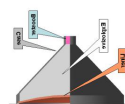
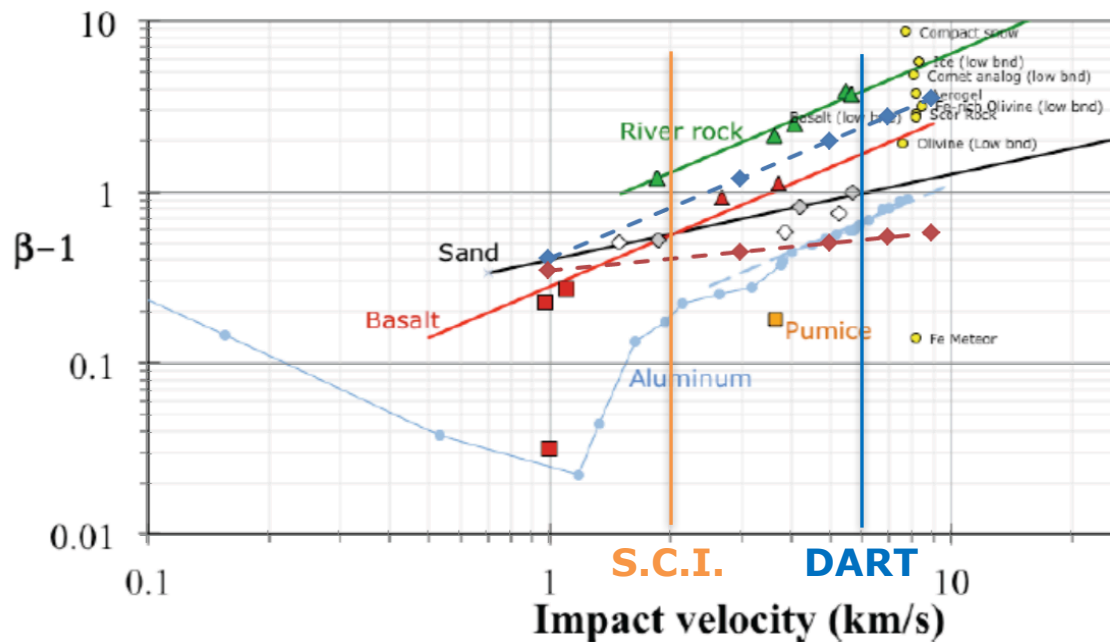




# Validation of scaling laws

Performing second impact at different energy level with JAXA's S.C.I. payload

- outside experimental range of ground laboratories
- "Ground truth" for numerical models & scaling theory



impactor kinetic energy

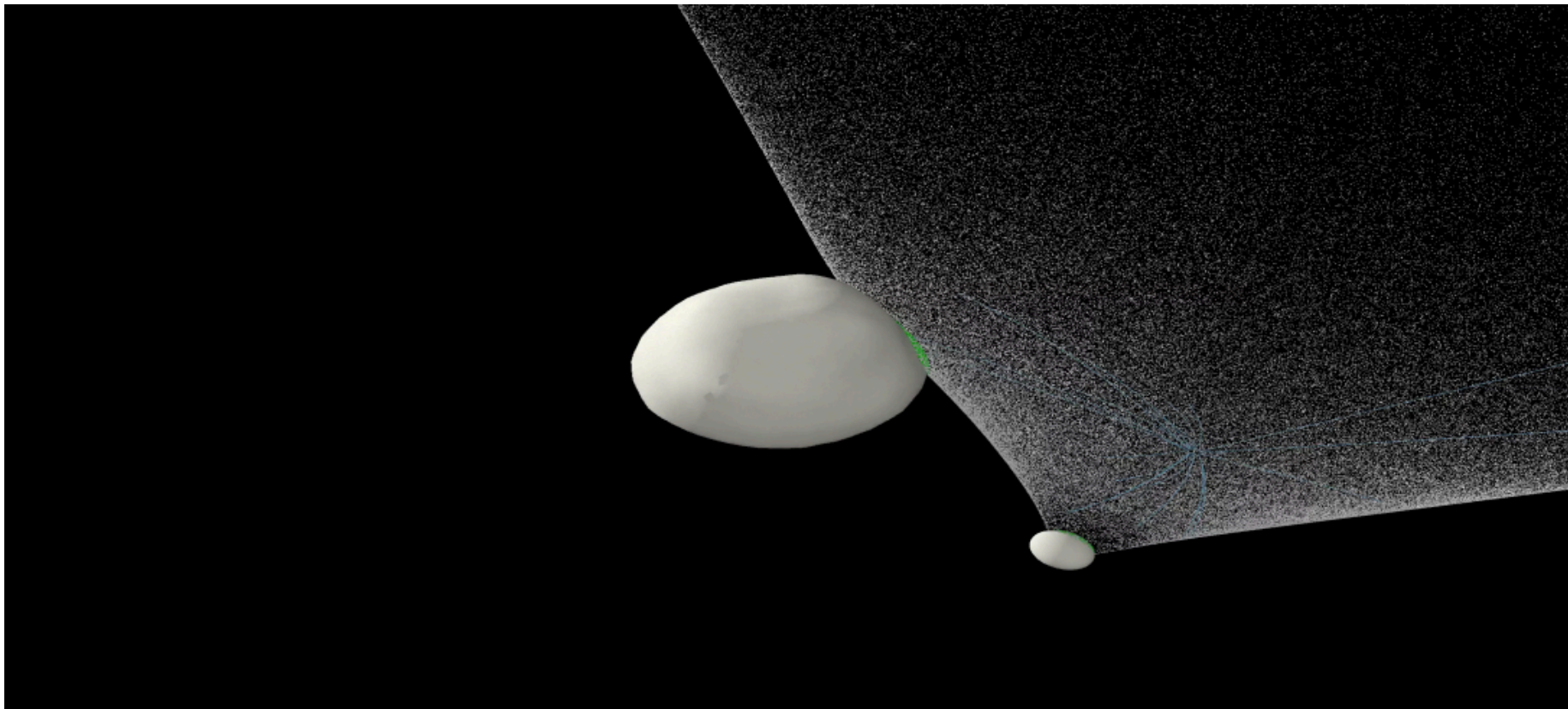
$$\beta \sim \left( \frac{\rho U^2}{Y} \right)^{(3\mu-1)/2}$$

slope of scaling law

$Y = f(\text{crater volume, impactor velocity and density, surface gravity and surface density})$

asteroid strength

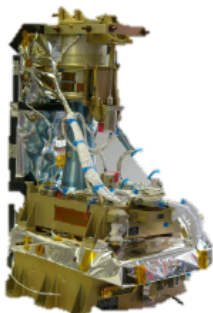
# DART impact modelling and observation



# PAYLOAD BASELINE

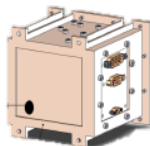


11.6 kg  
17-34 W



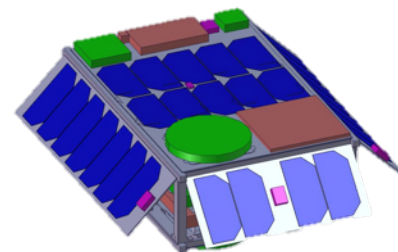
**NAVCAM**  
(In storage)

1.4 kg  
9 W



**μLidar**

14.9 kg (6U)

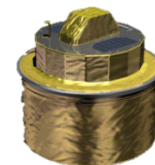


Interested MS



- Two payload among:
- Hyperspectral imaging (ongoing)
  - Volatiles
  - Radioscience
  - Seismometry
  - Minearology
  - Dust environment

**Option:** study accommodation and release of JAXA's Small Carry-on Impactor



# Mission measurements

(for background info)



Parameter	Required accuracy	Associated payload
<b>Size, mass, shape, density</b>	<ul style="list-style-type: none"><li>▪ Mass: 10%</li><li>▪ Density: 20%</li><li>▪ Shape accuracy of 6% or few meters</li></ul>	Mass from binary orbit, spacecraft tracking (camera, cubesat, radioscience)  Shape model (camera), Lidar
<b>Dynamical state</b> (period, orbital pole, spin rate, spin axis)	<ul style="list-style-type: none"><li>▪ Period already known to better than 0.1%</li><li>▪ Orbital pole: 5°</li><li>▪ Spin rate: 1%</li><li>▪ Spin axis: 1°</li></ul>	camera
<b>Geophysical surface properties, topology, DART crater's properties</b>	<ul style="list-style-type: none"><li>▪ Global surface resolution: 1m</li><li>▪ Local surface resolution (10% of the surface): 10cm</li></ul>	Camera (surface features) Cubesat (2 meter resolution)
<b>Chemical and mineral composition of Didymoon and Didymos</b>	Spectral resolution: 45nm or better	Camera, cubesat
<b>Impact ejecta</b>	No accuracy required	Camera, cubesat

## 1. demonstrate deep-space (6U) cubesat relayed via an inter-satellite link with ranging capability:

- Very high-resolution close up asteroid (hyperspectral) imaging
- Provide complementary measurements to main spacecraft (e.g. spacecraft-CubeSat radioscience, seismology, end-of-life landing for surface properties characterization...)
- Close-by imaging of DART impact (if delayed)

## 2. Validate far-range navigation and close-range feature-tracking navigation increasing on-board autonomy

- *Synergies with technologies under development for in-orbit servicing, including novel FDIR based on sensor data fusion.*



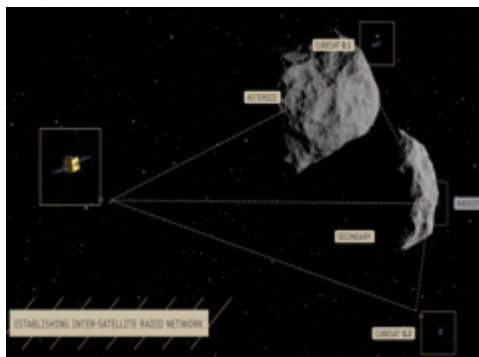
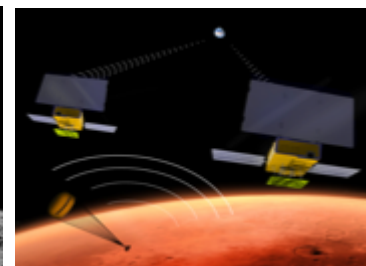
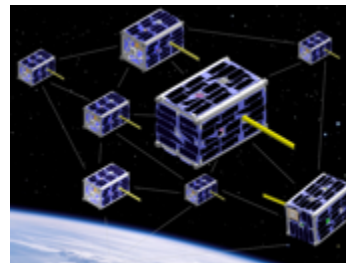
# CUBESAT and INTER-SATELLITE LINK

(for background info)

**6U CubeSat** allows for:

- higher resolution imaging
- Provide additional complementary information (e.g. mineralogy, volatiles, high-res information on porosity...)
- reducing risk to the main mission

**Synergies with current CubeSat and microsat miniaturization technologies**



## Future applications

- In-orbit inspection
- Distributed systems for exploration mission (in-situ characterization, remote sensing)
- Swarm architectures for future EOP missions



# Far range navigation

(for background info)



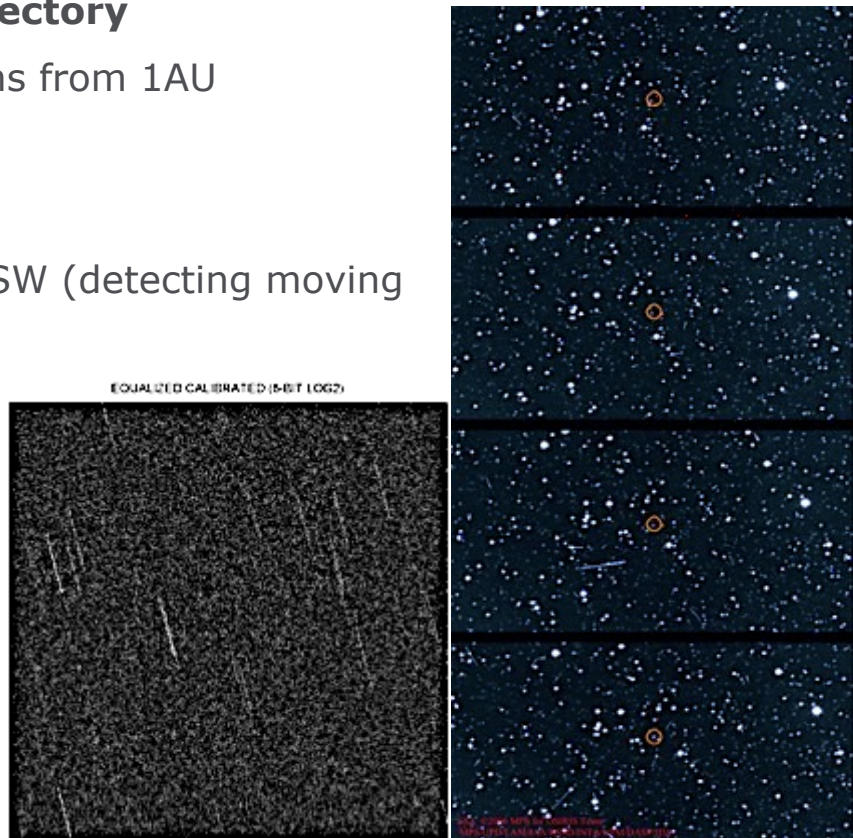
## Identify faint object and determine relative trajectory

- Background: ROSETTA detection of asteroid Steins from 1AU
- HERA application: arrival to small asteroid

**Synergies with in-orbit servicing:** same HW and SW (detecting moving object against star background)

## Future applications

- Active Debris Removal (localization of non-responding satellites/debris)
- Mars Sample Return (precursor technology activity for GNC of the Orbiting Sample rendezvous)



# Close-range vision-based navigation

(for background info)

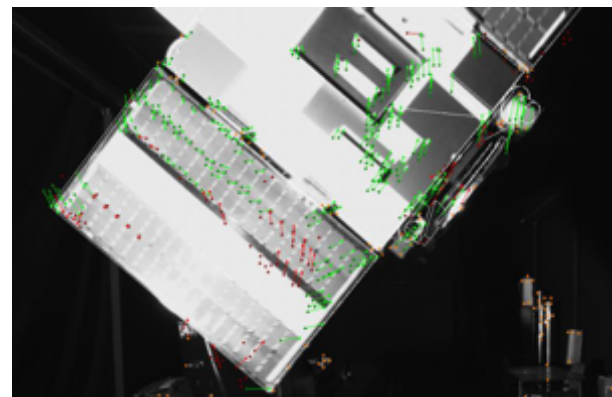
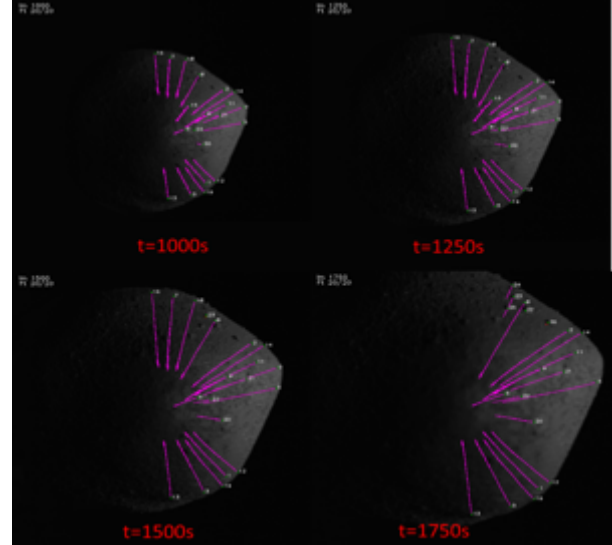
## Track unknown features on the surface to estimate relative trajectory

- Background: NASA Mars lander, ESA TRP & CTP activities
- HERA application: proximity operations around asteroid

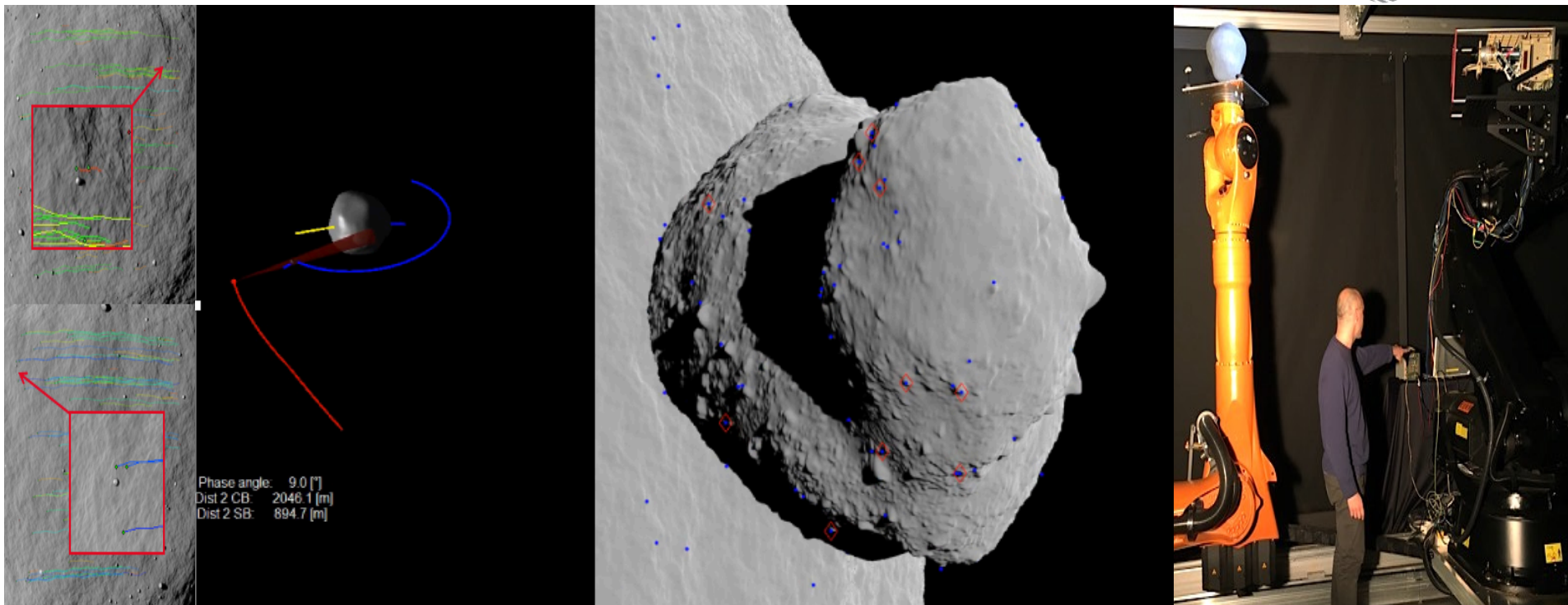
**Synergies with in-orbit servicing:** same HW and part of SW  
(track features between frames)

## Future applications

- ADR, SpaceTug, In-Orbit Servicing, In-Orbit Assembly (pose estimation algorithms before capture)
- Earth Observation or telecomm satellites (autonomous tracking of targets on the surface)

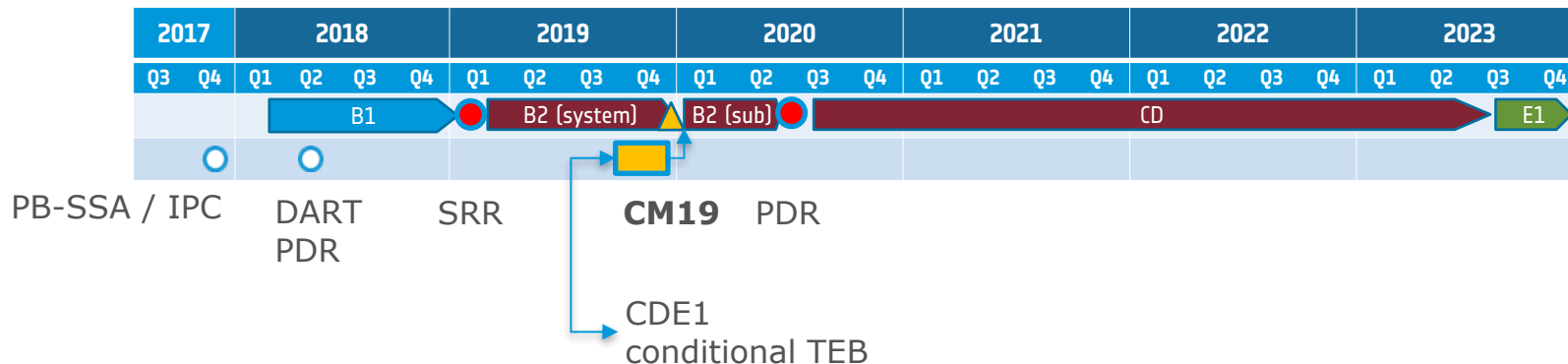


# Preliminary GNC tests results



Capable of performing autonomous close asteroid fly-by both with feature tracking and centroid measurements

# HERA schedule



START	END	PHASE
Mar-18	Dec-18	<b>Phase B1</b>
Jan-19	Feb-19	<b>SRR</b>
Feb-19	Dec-19	<b>Phase B2-A</b>
Dec-19		<b>CM19</b> *Sep-Nov 19: PhB2CD Conditional TEB
Jan-20	May-20	<b>Phase B2</b>
May-20	Jul-20	<b>PDR</b>
Aug-20	Aug-23	<b>Phase CD</b>
Aug-23	Oct-23	<b>Margin/Launch Campaign</b>
Oct-23		<b>Launch</b>





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