ASTRO=F Cesa ASTRO-F Observers' Factsheet V 1.5 (9 November 2005) http://astro-f.esac.esa.int/ helpdesk http://astro-f.esac.esa.int/esupport/

ASTRO-F is an infrared survey mission from the Institute of Space and Astronautical Science (ISAS) of the Japan Aerospace eXploration Agency (JAXA) with the participation of the European Space Agency (ESA).

telescope always pointed

plane perpendicular to the Sun.

with an offset control allowance of only two degrees. Thus the

visibility is a function of ecliptic

latitude. Targets near the ecliptic

poles are observable on a large

number of orbits. Targets on the

ecliptic plane are visible only on a

-40 -20 0

20 40 60 80

in a

ISAS/JAXA's ASTRO-F Satellite, due for launch in early 2006, will perform an all-sky survey in six wavebands between 6 and 180 µm, at higher sensitivity, spatial resolution and larger wavelength coverage than IRAS. The resulting catalogues are expected to contain more than a million sources. Deep imaging and spectroscopic surveys with pointed observations will also be performed in selected areas of the sky.



Mission Phases: The main objectives of the ASTRO-F Mission are legacy observations in the form of Large Area Surveys (LAS) and the conduction of large mission programs (MP). In addition, a significant phase of the mission will be dedicated to pointed observations of astronomical targets. 30% of these opportunities are available to the general astronomical community as **Open Time (OT)**, via the traditional route of Call for Proposals, followed by peer-review. Resulting from ESA's collaboration in this mission, 10% are open to European users, the other 20% are for Japanese and Korean astronomers. These OT observations will be scheduled after the survey prioritised part of the mission, starting at about eight months after launch. Note that OT proposals may not duplicate MP proposals.

Wavelength (µm)

100

10

Wavelength (µm)



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INFRARED SURVEYOR (FIS) The Far Infrared Surveyor (FIS) instrument will carry out an All Sky Survey and deep scans in pointed mode in 4 far infrared bands from 50-180 µm and is also equipped with a Fourier Transform Spectrometer

Basic FIS Capabilities:

The FIS is designed primarily to perform the All-Sky Survey in 4 photometric bands at wavelengths between 50 and 180 μ m (two broad bands and two narrow bands). The instruments are operated such that data acquisition is continuous as the telescope scans the sky, resulting in sets of strip data of sky brightness. This operation can also be used for pointed observations in a slow-scan mode for deeper observations. The FIS is also equipped with a Fourier Transform Spectrometer (FTS) that enables imaging spectroscopy over the full FIS wavelength range with the two wide-band arrays (WIDE-S and WIDE-L) and a resolution of ~0.36 cm⁻¹ (R = 450 – 170) or 2.4 cm⁻¹ (R = 75 – 30). FTS observations are performed in staring pointing mode.



FIS Imaging: 5o detection and saturation limits for a point (left) and an extended (right) source (reset interval = 1.0).



Sky Confusion Estimates: Very likely, FIS observations will be affected by galactic cirrus noise and background source confusion. Users are encouraged to take confusion into account when planning observations, it may save significant amount of observing time. The sky confusion noise due to galactic diffuse emission (cirrus) is a function of Galactic Latitude as shown in the figure.

Sky confusion tool:

http://www.ir.isas.jaxa.jp/ASTRO-F/Observation/Confusion/



FIS Astronomical Observation Templates (AOT):

Three AOTs are available for the FIS pointed observations.

• FIS01: Photometry of point sources and/or mapping of small areas of sky of up to around ~25 x 10 arcmin². All four bands are available. Scan pattern: two round-trip scans with a cross-scan shift. Scan speed is either 8 or 15 arcsec/sec. Two parameters can be specified: the readout mode (Nominal/CDS) and reset interval (0.5, 1.0 or 2.0) if the Nominal mode is selected. The scan sequence of AOT FIS01 is shown in the figure below.

• FIS02: Mapping of large areas (~1 deg x 8 arcmin). All four bands are available. Scan pattern: one round-trip scan with fixed speed of either 15 or 30 arcsec/sec. No cross-scan shift is operated during a pointed observation to maximize the scan length. Sampling mode and reset interval as in FIS01.

• FIS03: Imaging spectroscopy with the FTS. In FULL or SED mode. Pointing mode: staring. For accurate spatialspectroscopic information, the AOT must be repeated with a slightly shifted target position. Observations of a wider area require the repetition of the AOT on diferent orbits. The FTS mode is subject to several constraints, as specified in the Observers Manual and in the Call For Proposal Policies and Procedure document.

> Instrument Performance tool: http://astro-f.esac.esa.int/tools/IPT.shtml

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The Infrared Camera (IRC) instrument will carry out an All-Sky Survey at 9 and 18 µm and will perform pointed observations in 9 photometric bands and 5 spectroscopic elements in the $2 - 26 \mu m$ range.

Basic IRC Capabilities: The IRC consists of three cameras: NIR, MIR-S & MIR-L. Each camera is equipped with a set of filters and dispersion elements. The filters can be chosen from a limited number of pre-determined combinations defined in each AOT. Only NIR and MIR-S share the same FoV. This means that at least two pointed observations in different revolutions are needed to observe a particular position with all three cameras.

An IRC pointed observation consists of an n times repeated exposure cycle and various operations between them (micro-scan and filter changes). One exposure cycle takes about 70 s in the current design, during which NIR carries out one short and one long exposures, and MIR cameras carry out one short and three long exposures.

Channel	FoV (arcmin²)	Array size (pixel²)	Pixel size (arcsec²)	
NIR	9.5x10.0	512x412	1.46x1.46	
MIR-S	9.1x10.0	256x256	2.34x2.34	
MIR-L	10.3x10.2	256x256	2.51x2.39	

Instrument Performance tool: http://astro-f.esac.esa.int/tools/IPT.shtml

IRC & Pı

11 Slow-Scan

IRC00 N3

IRC02

IRC03

IRC11 N/A

NIR

N2

N4

N/A

N/A

N3&N4

N2&N3&N4

CAMERA (IRC)

IRC Imaging: 50 detection and saturation limits for a pointed observation in imaging mode (IRC 00-02-03 and 11), computed at the ecliptic pole and at the ecliptic plane.

RED

IRC11 values correspond to two different scan speeds (15 and 30 arcsec/sec).

Point source detection limits are given in µJy and extended source detection limits in MJv/sr.



or	Channel	Filte	Filters		λ (μm)		
2- าย		N2	N2		1.7-2.7		
an	NIR	N3	N3		2.7-3.7		
nd		N4		3.7-5.5			
iu		S7	S7		5.8-8.4		
	MIR-S	S9W	S9W		6.5-11.6		
		S11		8.6-14.1			
		L15	L15		12.4-19.4		
	MIR-L	L18V	L18W		13.9-25.3		
		L24	L24 2		0.4-26.5		
IMAGING AOTs & FILTER SELECTION							
IRC AOTs & Purpose &		Filters/ channel	Dithering Pos/filter		Requested #pointing		
00 Deep imaging		1	No		≥ 3		

2

3

S9W

S7

S11

S9W

S7

S11

S7&S11

S7&S9W&S11

OPTIONS (one of the three sets)

MIR-S

OPTIONS (one of the tree sets)

3

2

N/A

L18W

L15

L24

L18W

L15

L24

L15&L24

 ≥ 1

 ≥ 2

≥ 1

MIR-I

L15&L18W&L24

IRC Spectroscopy: The MIR-S and MIR-L cameras always observe with the available dispersion elements (2 GRISM for MIR-S and one for MIR-L), while only one of the NIR dispersion elements (NP: PRISM; NG: GRISM) can be selected at a time. A short exposure image will be taken for pointing alignment.

A slit is provided in each camera in order to observe diffuse radiation. The NIR camera has also an entrance aperture (slit) for point source confusion-less spectroscopy.

Channel Dispersion elem.		λ (μm)	Resolution $(\lambda/\Delta\lambda)$
NIR	NIR NP		22@3.5µm
	NG	2.5-5.0	135@3.6µm
MIR-S	SG1	5.5-8.3	47@6.6µm
	SG2	7.4-13.0	34@10.6µm
MIR-L	LG2	17.7-25.0	27@20.2µm

SPECTROSCOPIC AOT &
DISPERSION ELEMENT SELECTION

	IRC AOT	F	Filters/ channel		ithering os/filter	Requested #pointing
	04	1(NIR&MIR-L) 2(MIR-S)	No		≥2
1	NIR MIR-S			MIR-L		
	NP (N	P (N3) SG1&SG2 (S9)		W)	/) LG2 (L18W)	
	NG (N3) SG1&SG2 (S9W		W)	/) LG2 (L18W)		



 5σ detection limits for a pointed observation, in the ecliptic pole and the ecliptic plane. Line detection limits are given for integrated line fluxes. Continuum detection limits are given per pixel. Integrating over the area of the resolution bin and over the image size can improve the detection