



*Results from
Torsion Pendulum Ground Testing
of
LISA Gravitational Reference Sensors*

Ludovico Carbone

and the LISA team at Trento University:

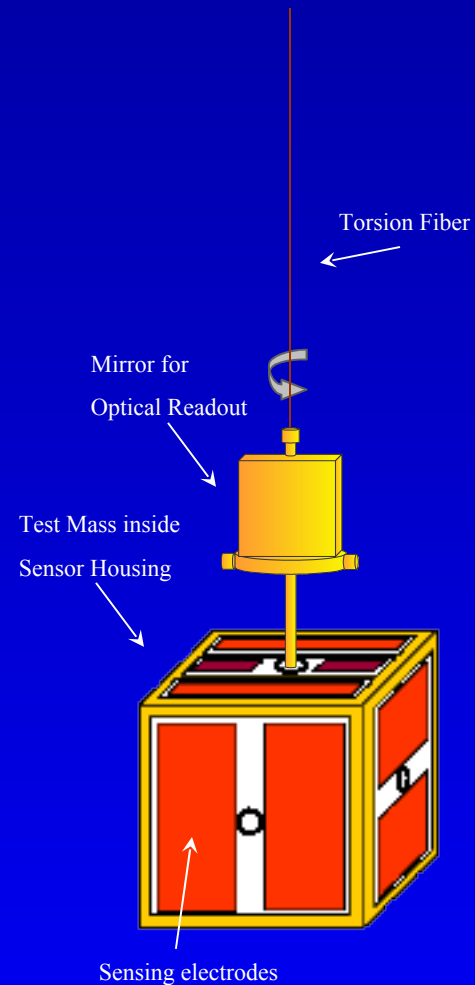
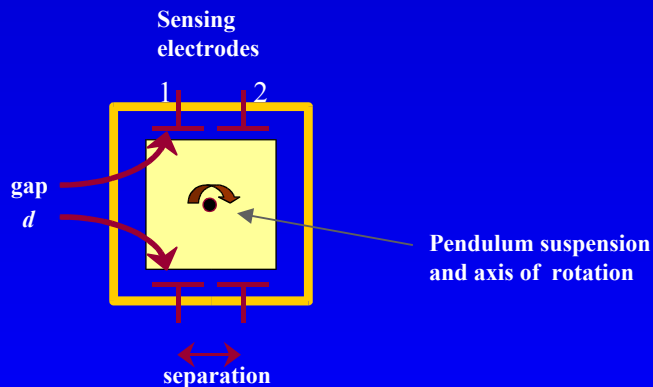
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email: carbone@science.unitn.it

5th LISA Symposium, ESTEC July 12 2004

Torsion Pendulum Ground Testing of GRS

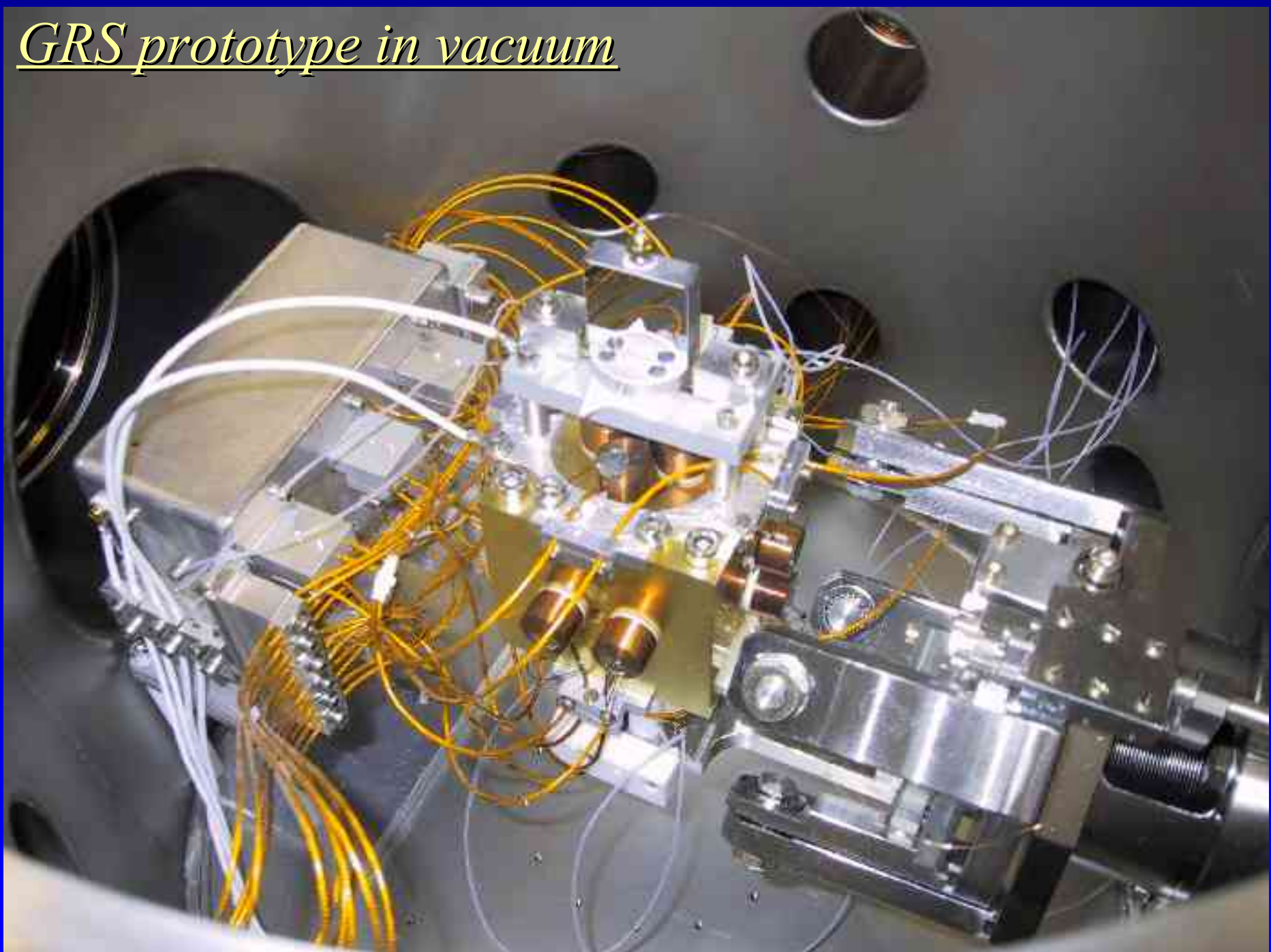
- Light-weight test mass suspended as inertial member of a low frequency torsion pendulum, surrounded by sensor housing
- Measure stray forces as deflections of pendulum angular rotation
- Precise study of residual couplings to sensor and disturbance sources



The Trento Torsion Pendulum Facility



GRS prototype in vacuum



Hardware Upgrades in 2004

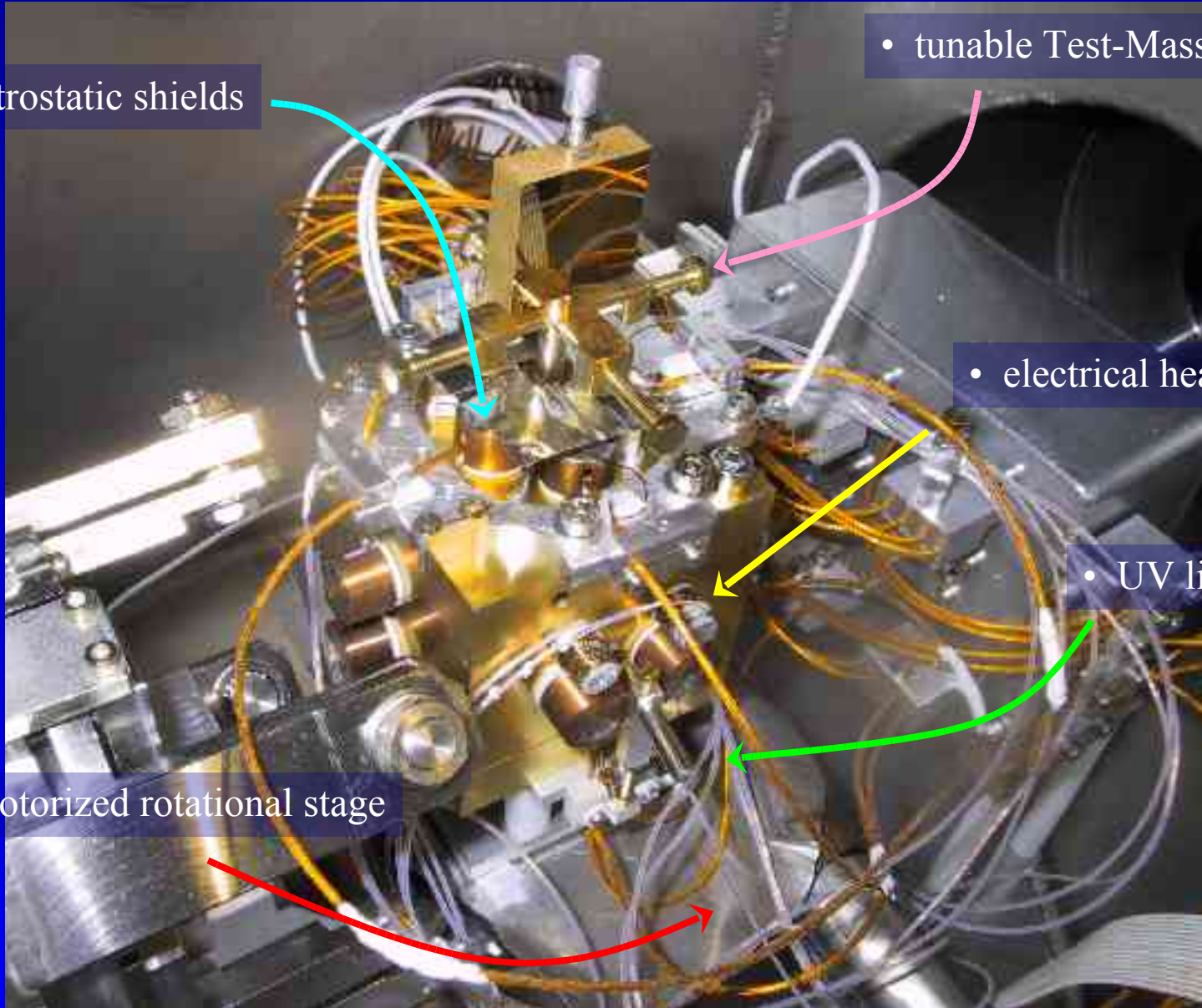
- electrostatic shields

- tunable Test-Mass support

- electrical heaters

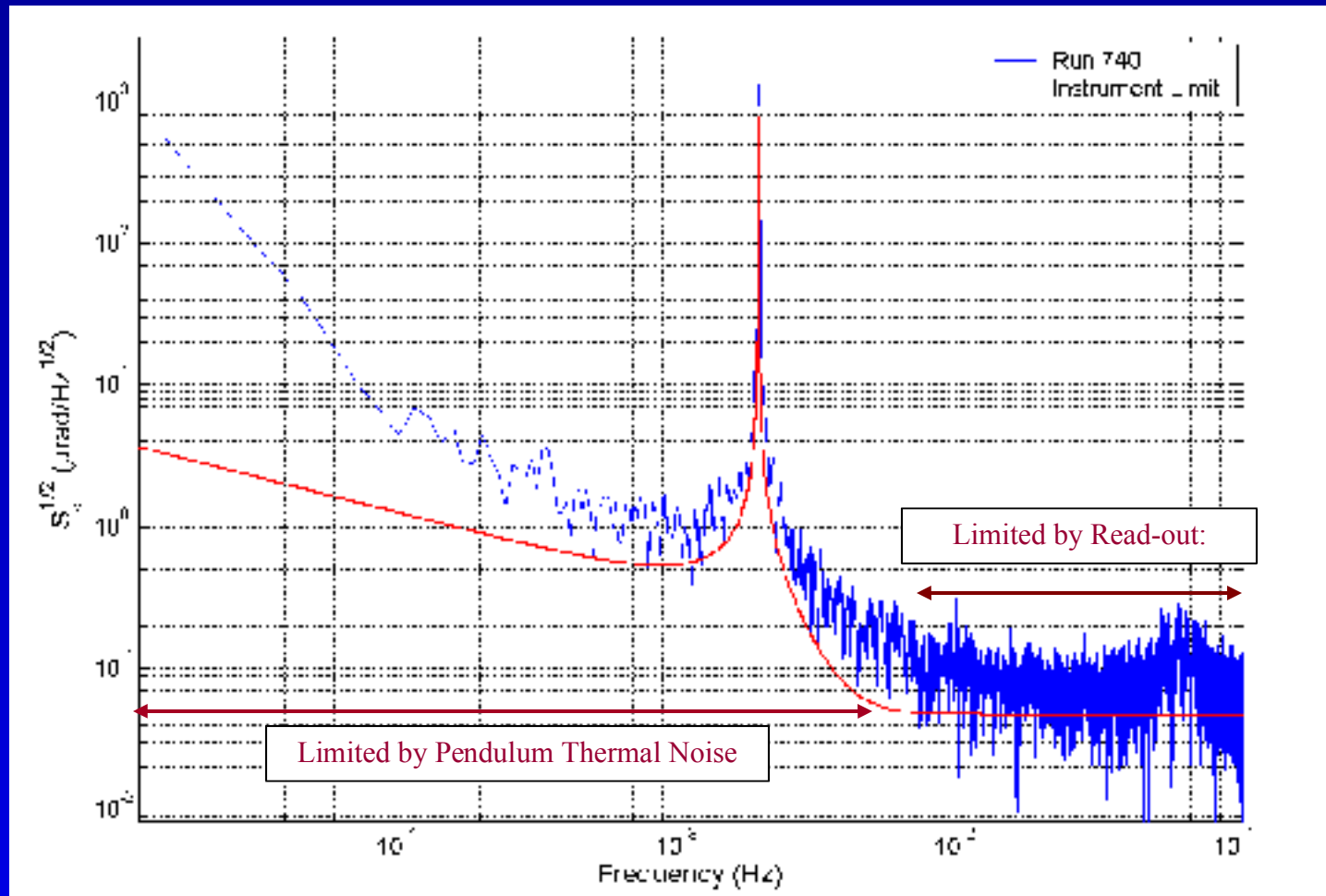
- UV light fiber

- motorized rotational stage



Plus ... bare tungsten fiber, Gold coated torsion member and stronger turbo-pump

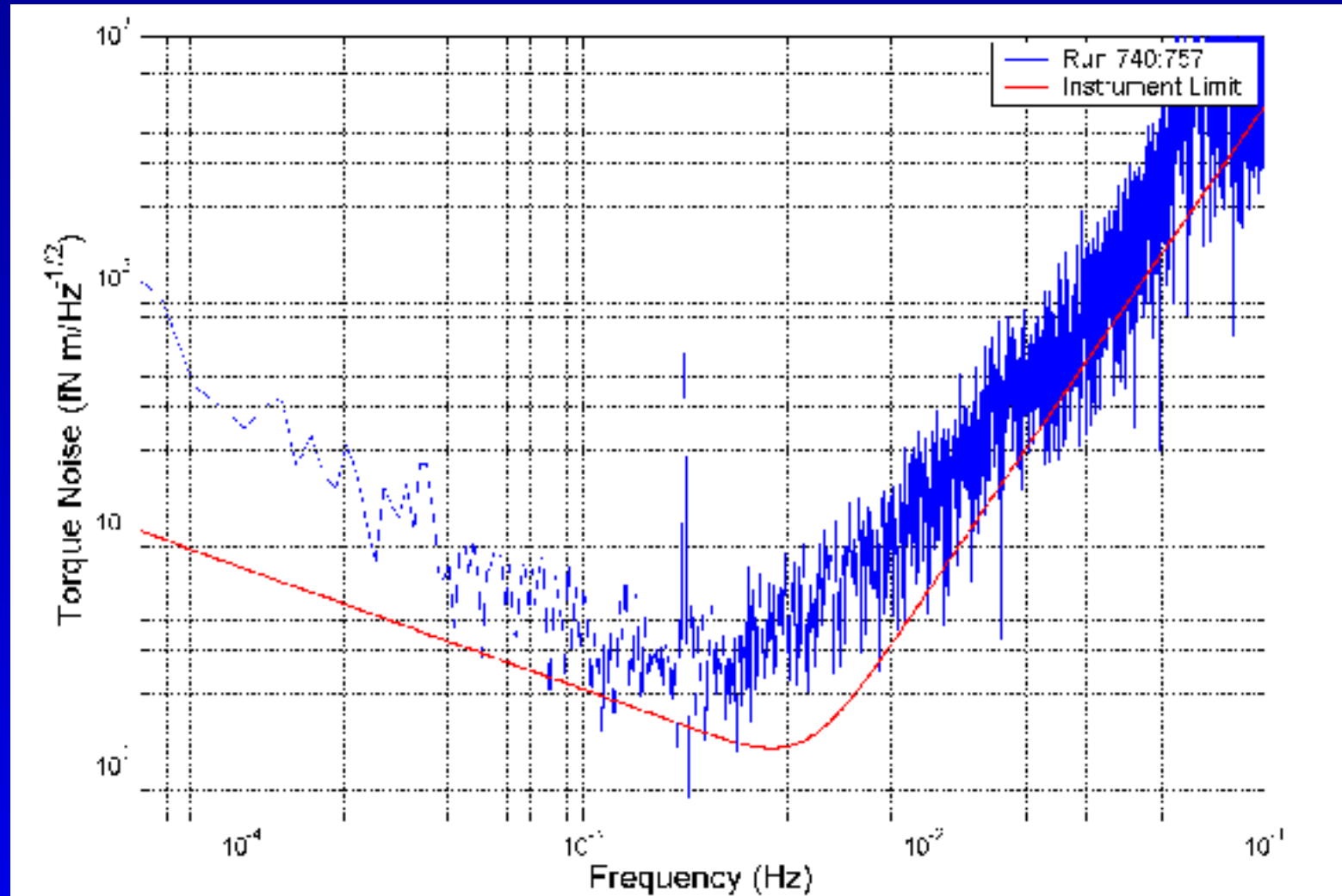
Torsion Pendulum Performances



Typical Torsional Angular Noise Spectrum

- Approaching pendulum thermal noise above 0.2 mHz
- Dominated by temperature stability at low frequencies

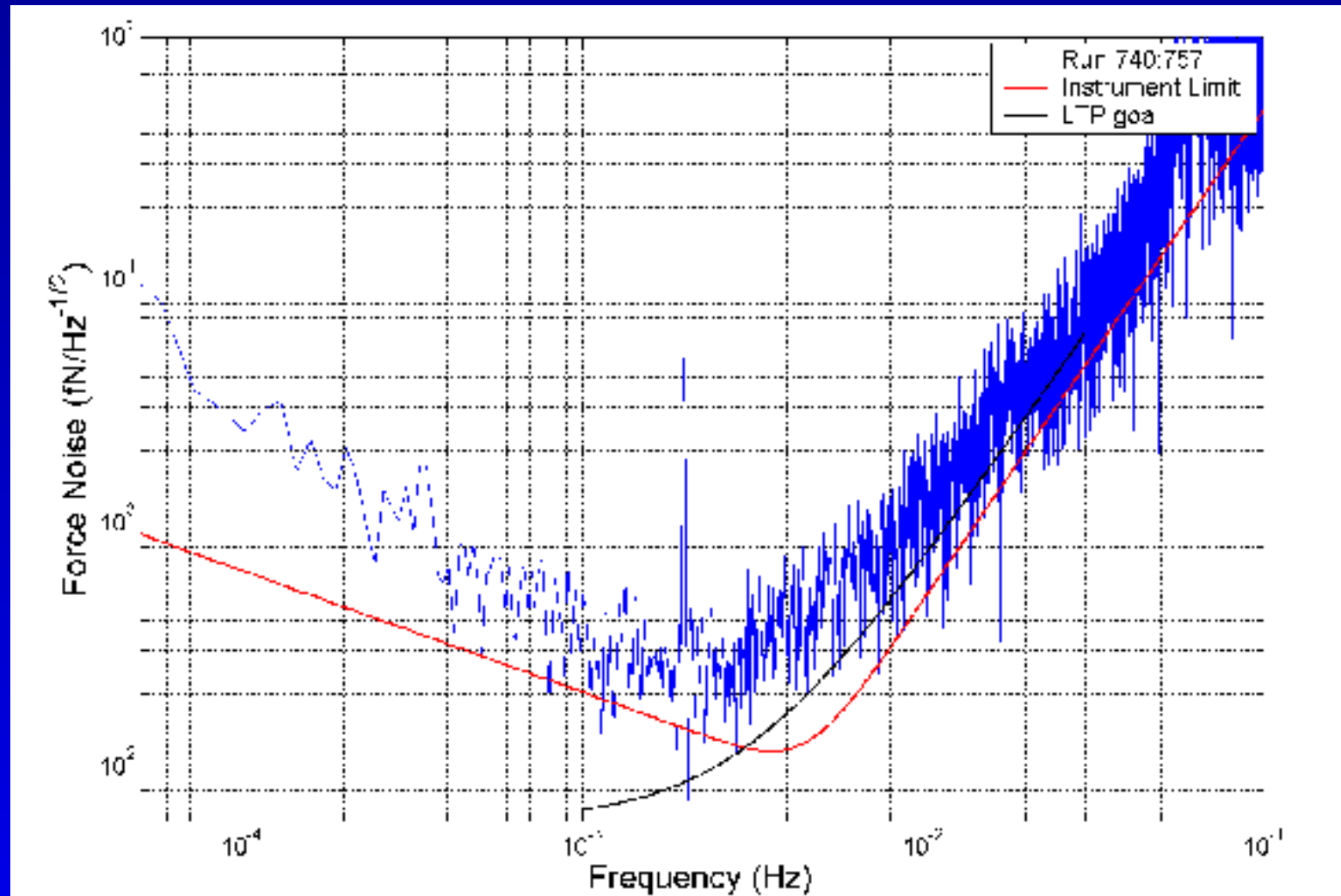
Torque noise measurements:



Torque noise calculated from angular noise and pendulum transfer function

- torque noise below 10 fN m Hz^{-1/2} (0.35mHz - 9 mHz)
- minimum noise at 2mHz: 3fN m Hz^{-1/2}

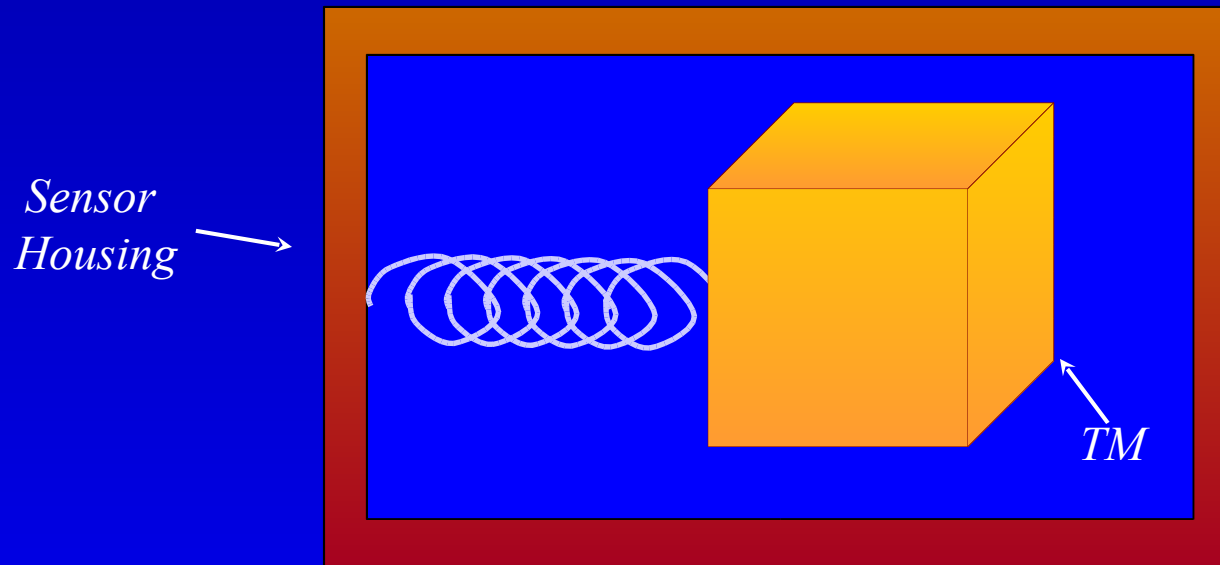
Force noise measurements:



- most stringent torque-force conversion (armlength ≈ 10 mm)
- roughly factor 5 above LTP goal at 1mHz (assuming 2kg TM)
- minimum: 250 fN Hz^{-1/2} (1-3 mHz)

Sensor-Test Mass Stiffness measurements:

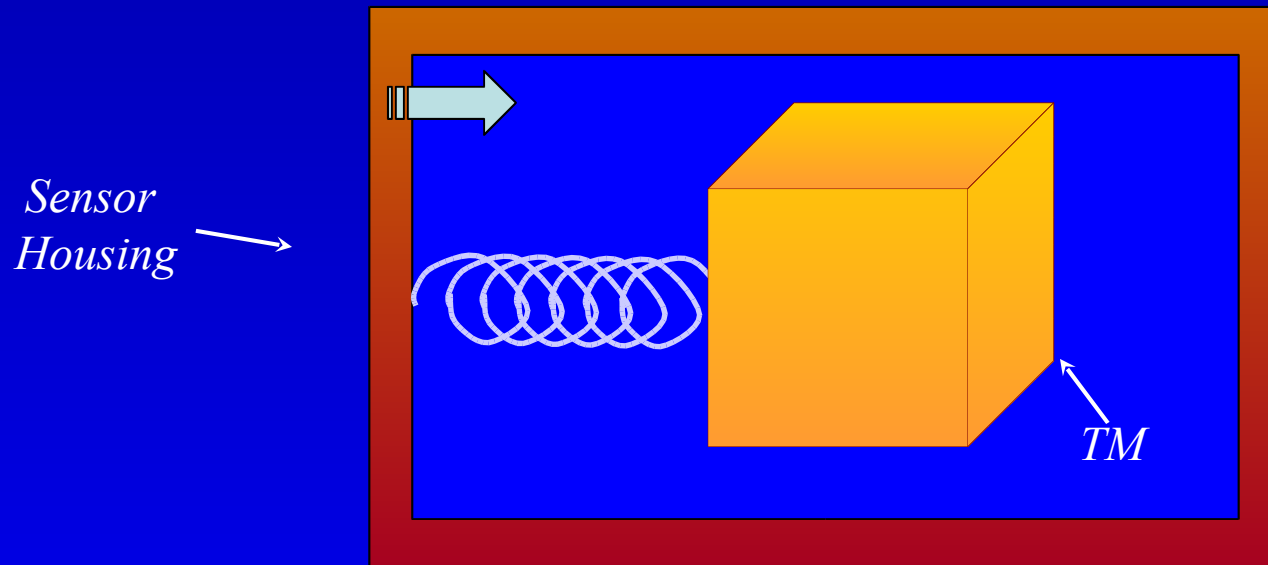
- Search for all sources of force gradients or spring-like coupling between sensor and TM, measure overall coupling
- Major contributions given by Sensing Bias and TM charge



- sources of translational stiffness typically also produce rotational stiffness

Sensor-Test Mass Stiffness measurements:

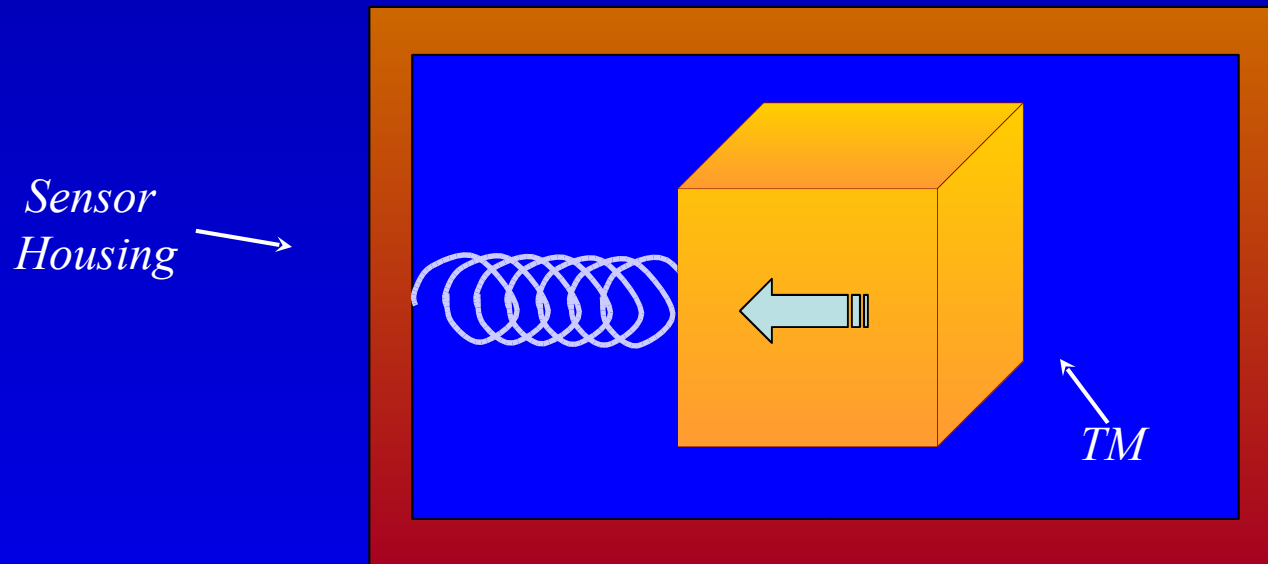
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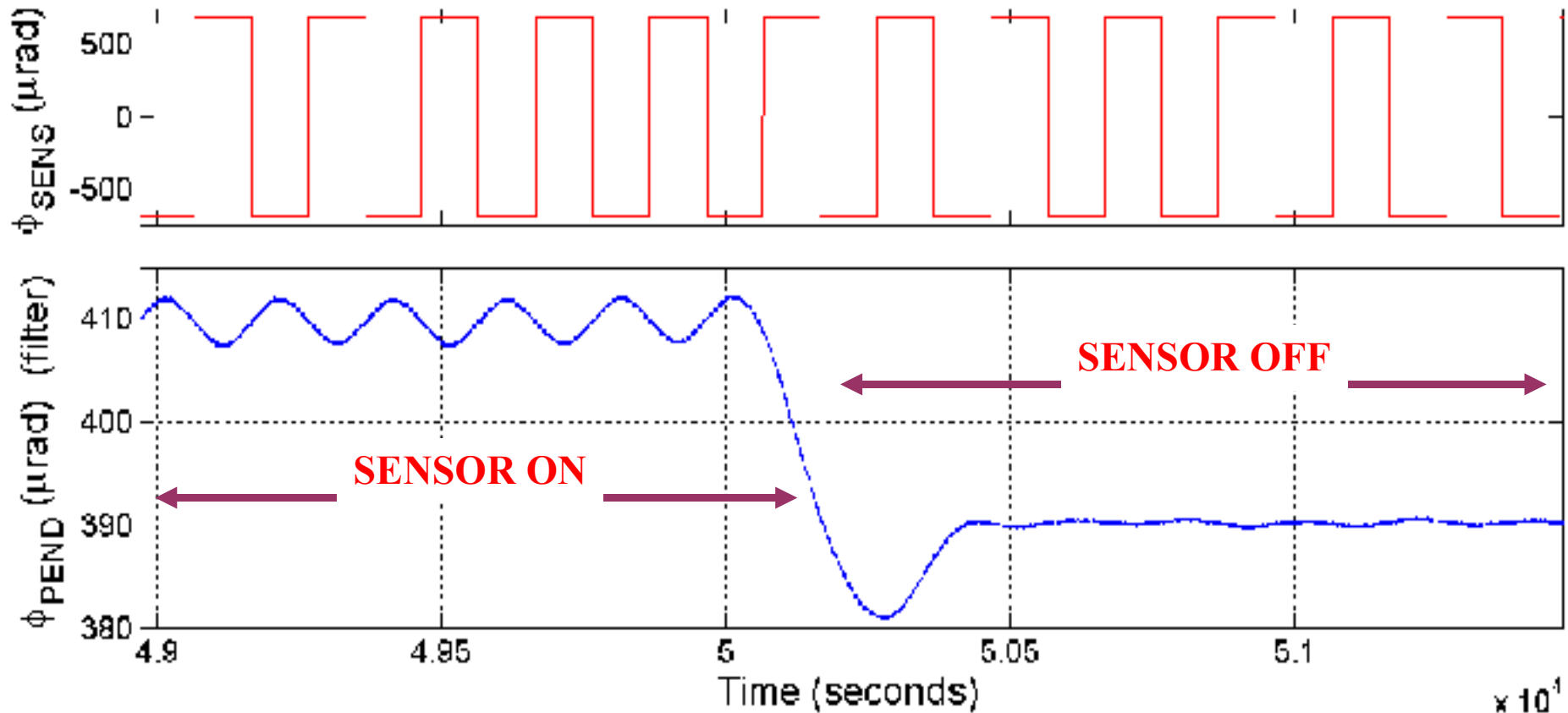
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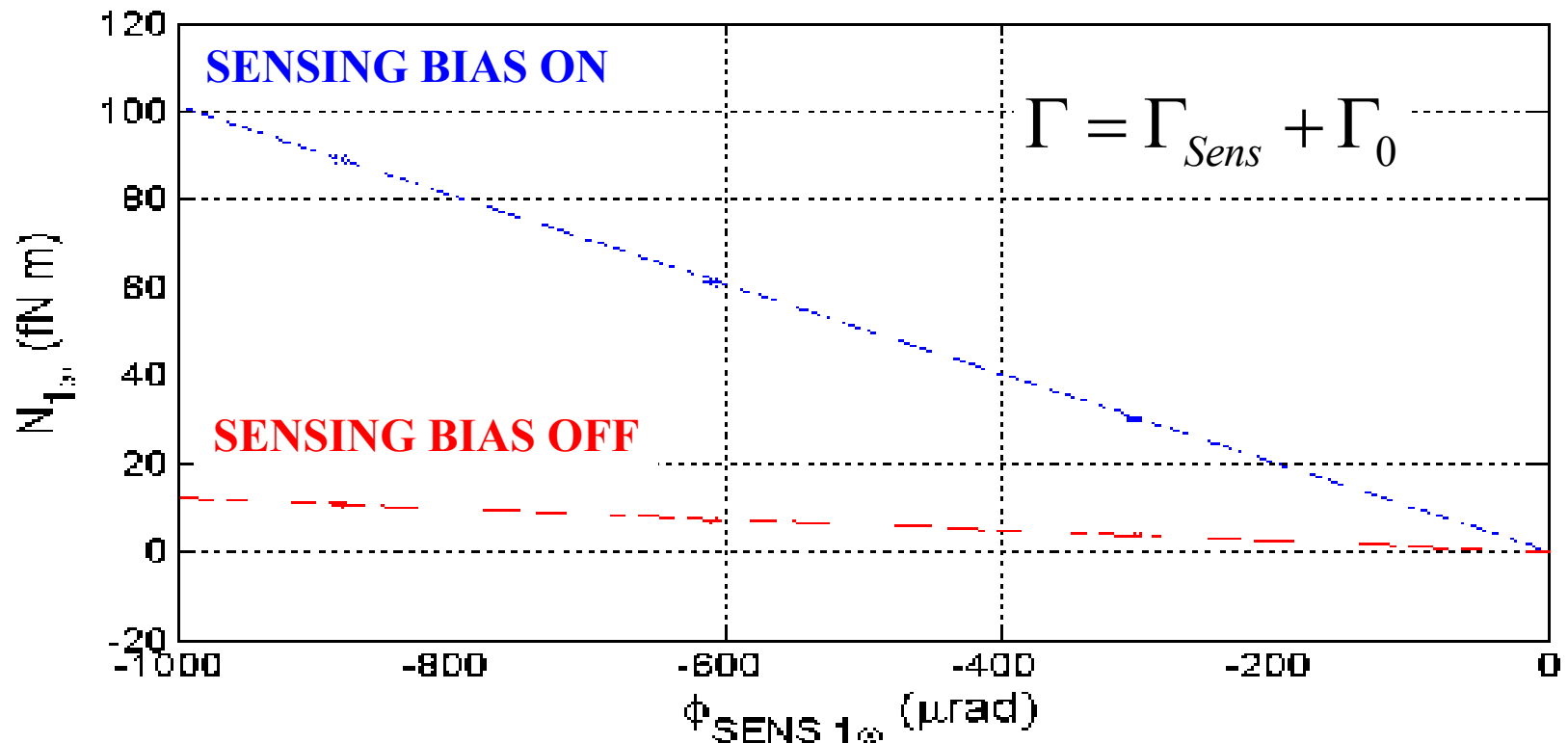


- sources of translational stiffness produce also rotational stiffness

- Coherent torque excited by square wave oscillation of sensor rotation angle, using a rotational motorized stage
- produce a square wave torque proportional to the stiffness

$$N(t) = -\Gamma \cdot \Delta\phi(t)$$





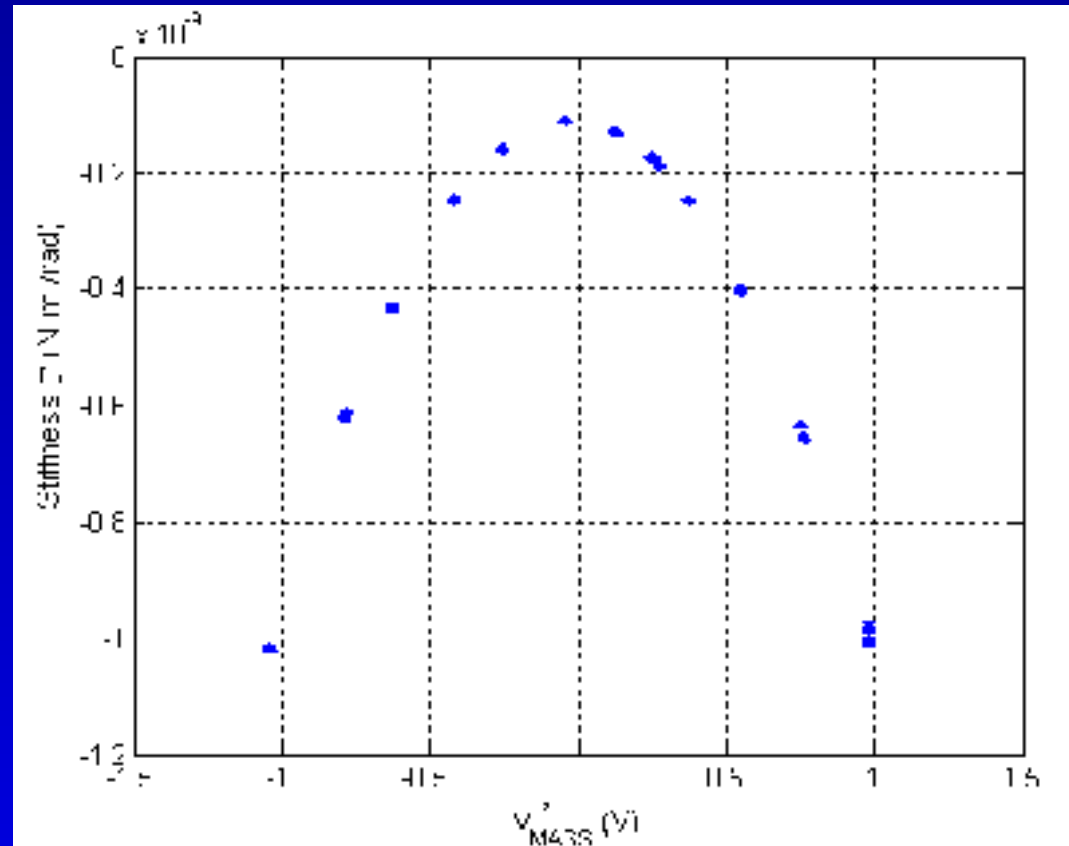
- Sensing Stiffness $\Gamma_{\text{SENS}} = -89.2 \pm .5 \text{ pN m / rad}$
consistent with previously measured value
- Extra stiffness $\Gamma_0 = -12.0 \pm .3 \text{ pN m / rad}$
could be explained by *115 mV* RMS patch voltages
or residual of trans-twist interaction

Confirmation of charge – stiffness model

$$\Gamma_{tot} = (\Gamma_{sens} + \Gamma_0)$$

$$-\frac{1}{2} \left(\sum_i \frac{\partial^2 C}{\partial \phi^2} \right) (V_M - V_{OFF})^2$$

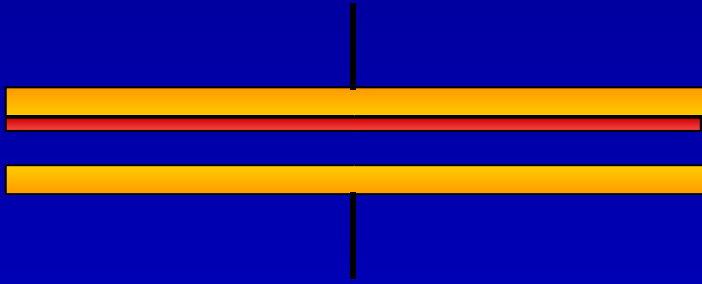
- developed a technique for measuring TM voltage drop to ground
- optical fiber with UV light installed for charge management (with Imperial College - London)



Results: $\Gamma_{SENS} + \Gamma_0 = -111.2 \pm .2 \text{ pN m /rad}$ [sensor plus excess stiffness]

- $\sum_i \frac{\partial^2 C}{\partial \phi^2} = 1.84 \pm .001 \text{ nF/rad}^2$ [ANSYS prediction: 1.77 nF/rad², Diana Shaul]
- $V_{OFF} = -20.2 \pm .3 \text{ mV}$ [likely a patch charge effect between 4 electrodes used in charge measurement and rest of sensor]

Measurement of dielectric loss angle:

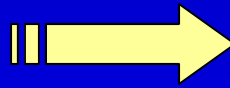


Lossy layer on sensing electrodes

$$C = C_0(1 - i\delta)$$

...adsorbed dipole layer,
electron hopping among
work-function minima...

- Dielectric losses contribute to voltage thermal noise
- Mixing with DC voltages produces Force Noise



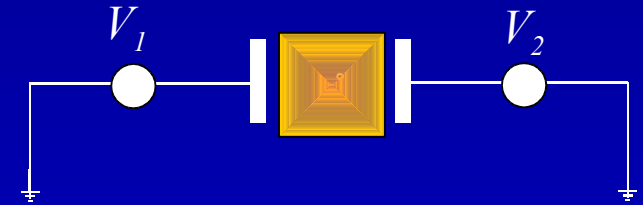
$$S_f = 4k_B T C_0 G^2 \frac{\delta}{\omega}$$

- Pendulum ringdown measurements to date have proved irreproducible at a level which prevents extraction of δ better than 10^{-4}

Measurement of dielectric losses: new direct measurement technique

- Direct measurement technique:

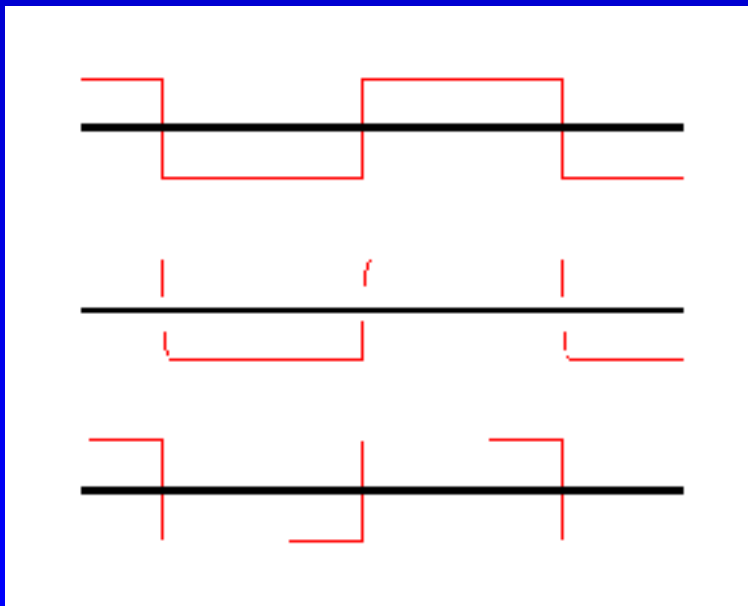
- A square wave voltage passing through the capacitor feels a delay created by lossy elements



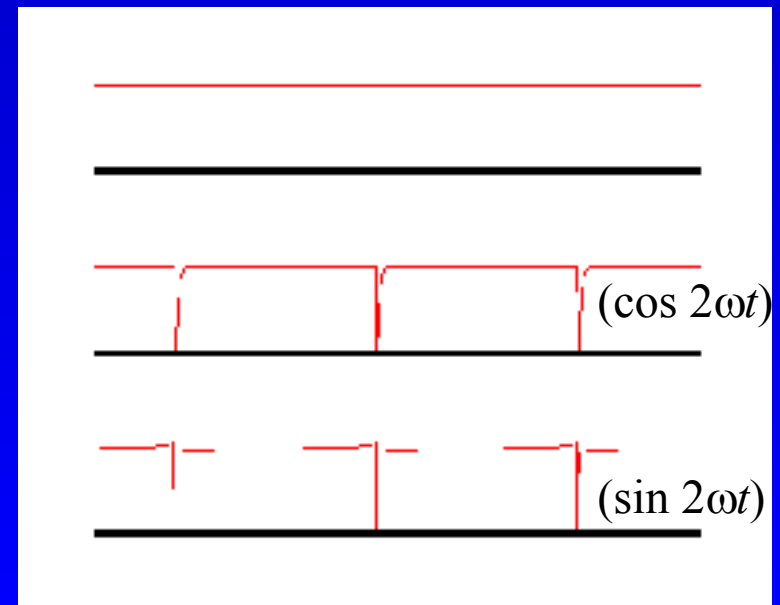
$$C = C_0(1 - i\delta)$$

- Application of perfect square wave yields constant force ($F \sim V^2$)
- Any lossy element creates delays and thus force transients

Electrode voltage:

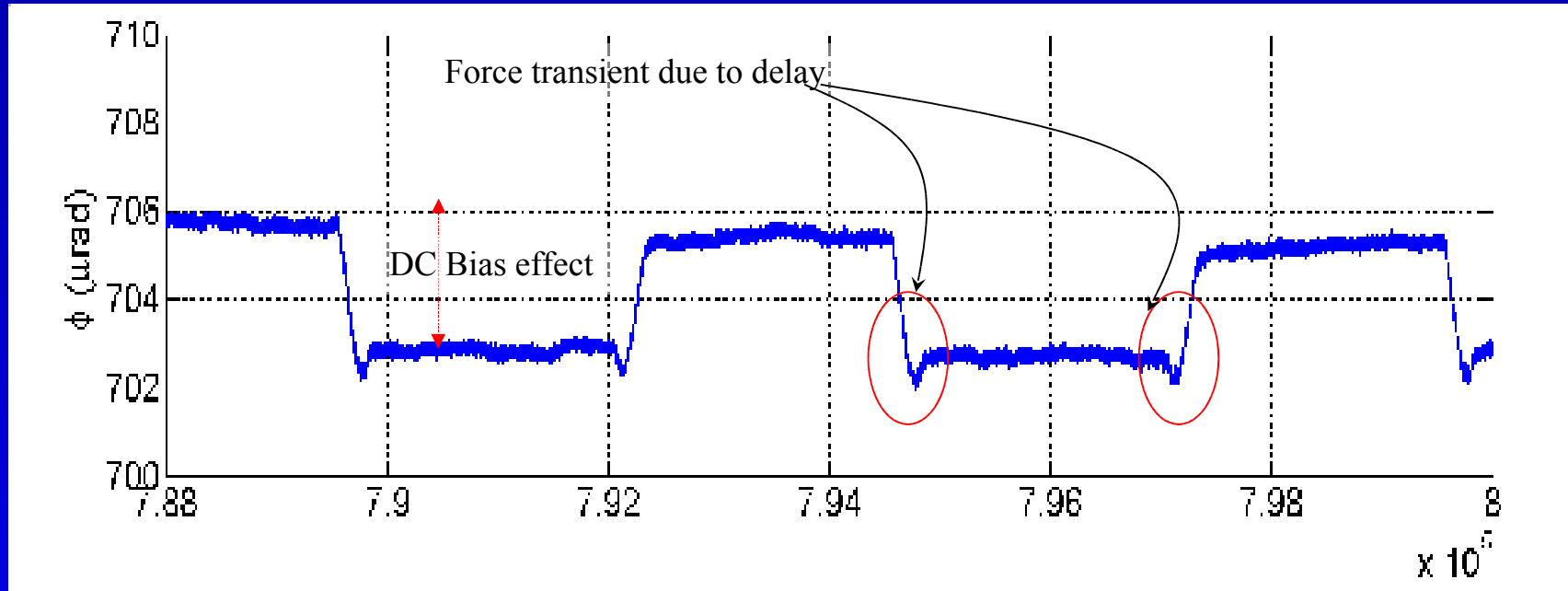


Force

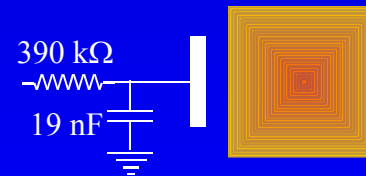


Measurement of dielectric losses: the measurement technique

- Application of perfect square wave yields constant force
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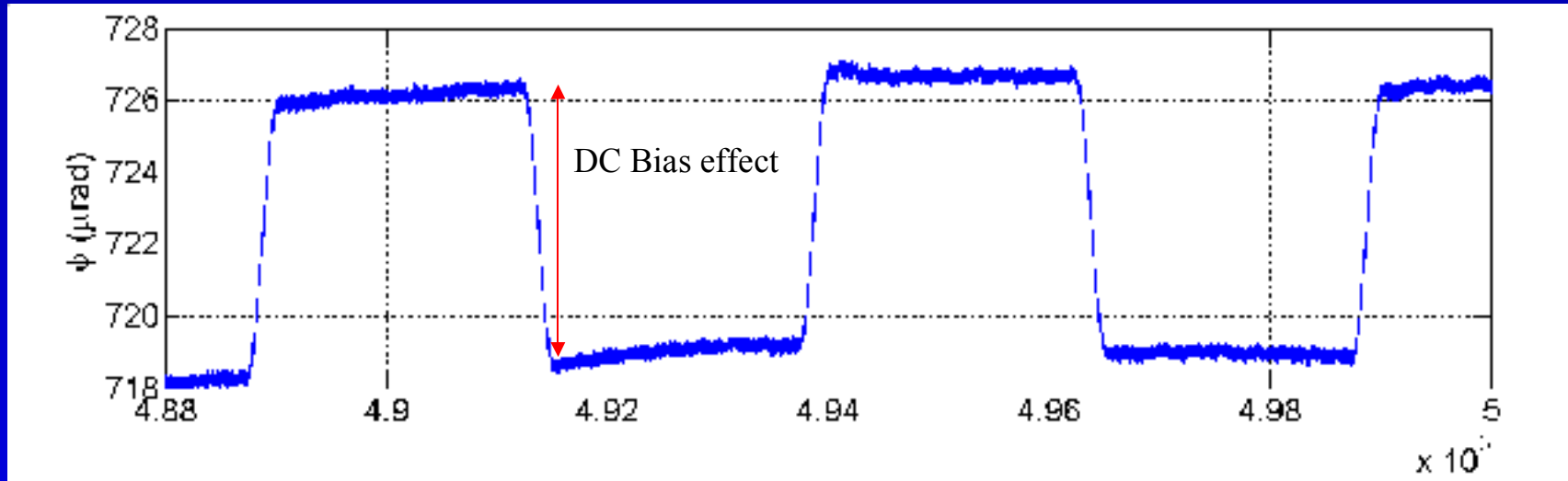


Application through
an ohmic delay
($\tau \approx 7$ ms, $\delta \approx 2 \cdot 10^{-5}$)

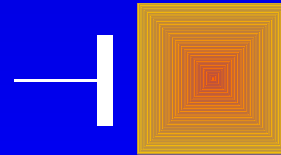


Measurement of dielectric losses: the measurement technique

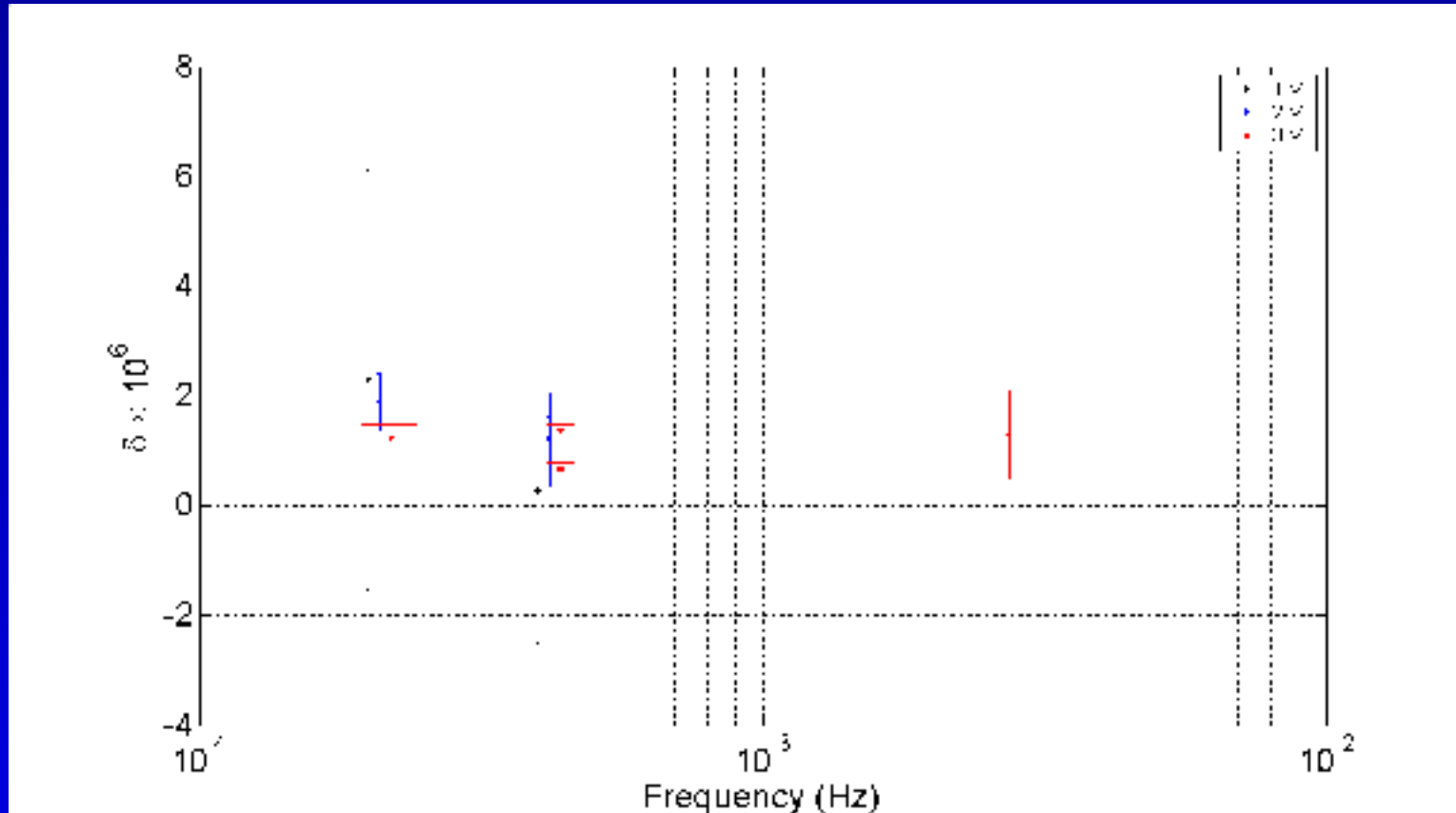
- Application of perfect square wave yields constant force
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Direct application
($f = .4 \text{ mHz}$)



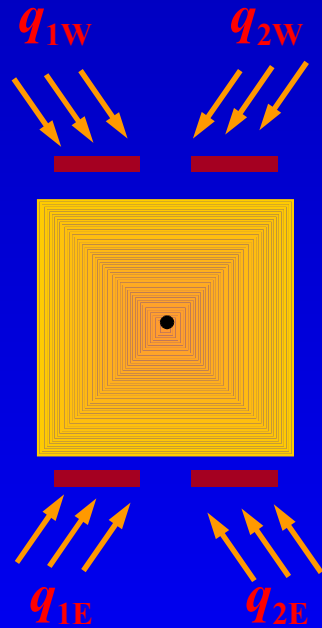
Measurement of dielectric losses: preliminary results



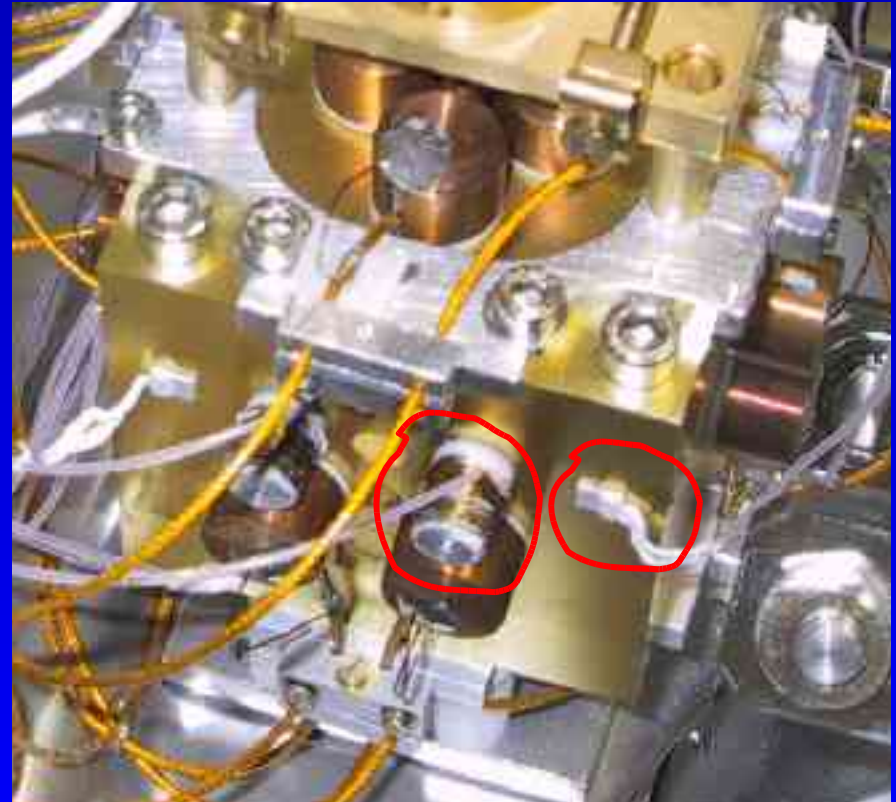
- very sensitive (can resolve $\delta \approx 10^{-6}$)
- preliminary measurements indicate δ of order 10^{-6} (LTP / LISA goal 10^{-5})
- calibrations performed with Ohmic losses
- need to also calibrate for non-Ohmic loss angles (δ independent of frequency),
... currently in progress

Thermal Gradient Related Effects:

- Search for temperature gradient induced torques in excess of that expected for radiometric and radiation pressure effects
- Outgassing effect difficult to predict (virtual leaks, impurities...)

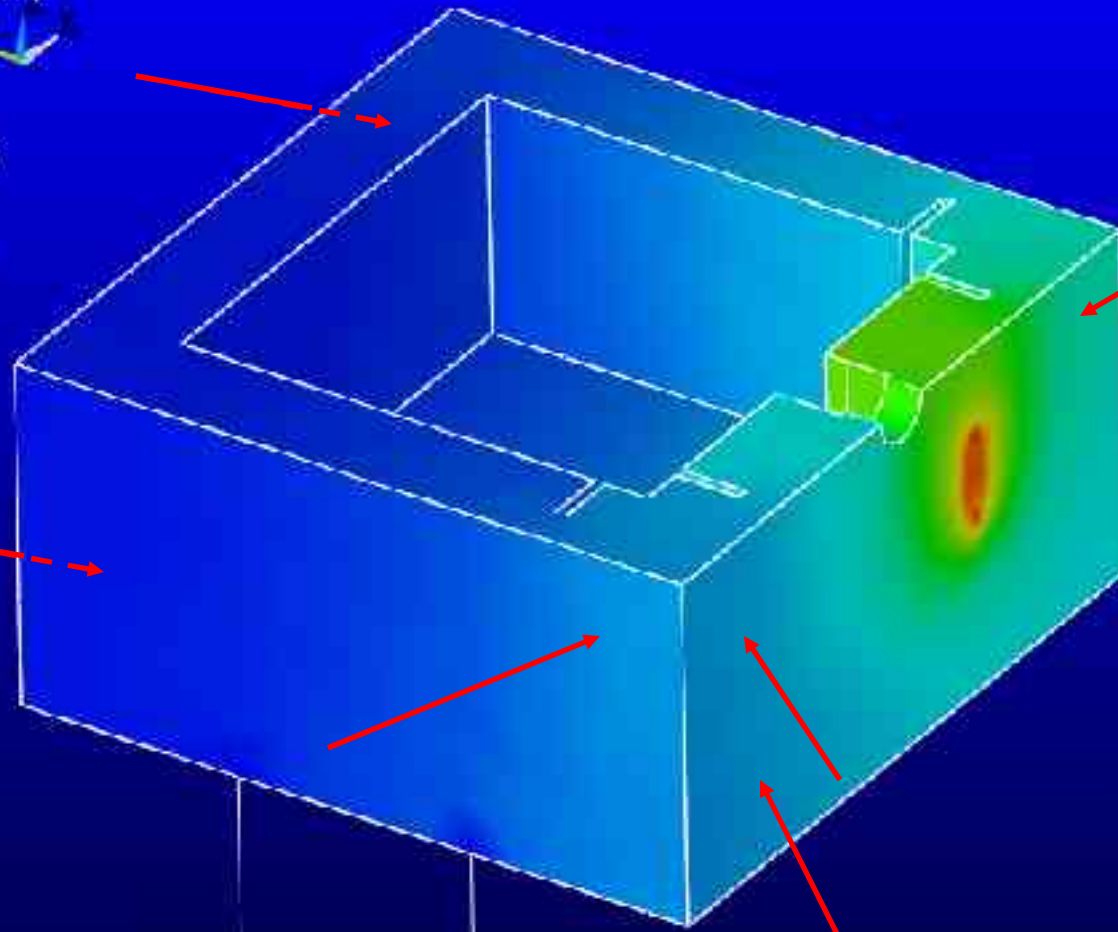


4 independent electrical heaters to apply rotational thermal gradients

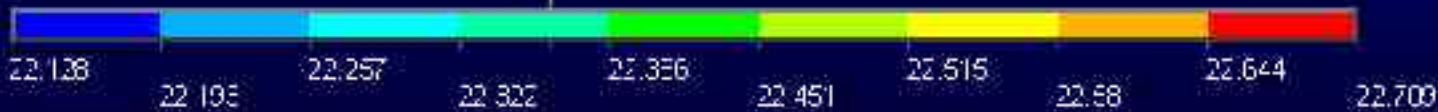


1
NODE SOLUTION

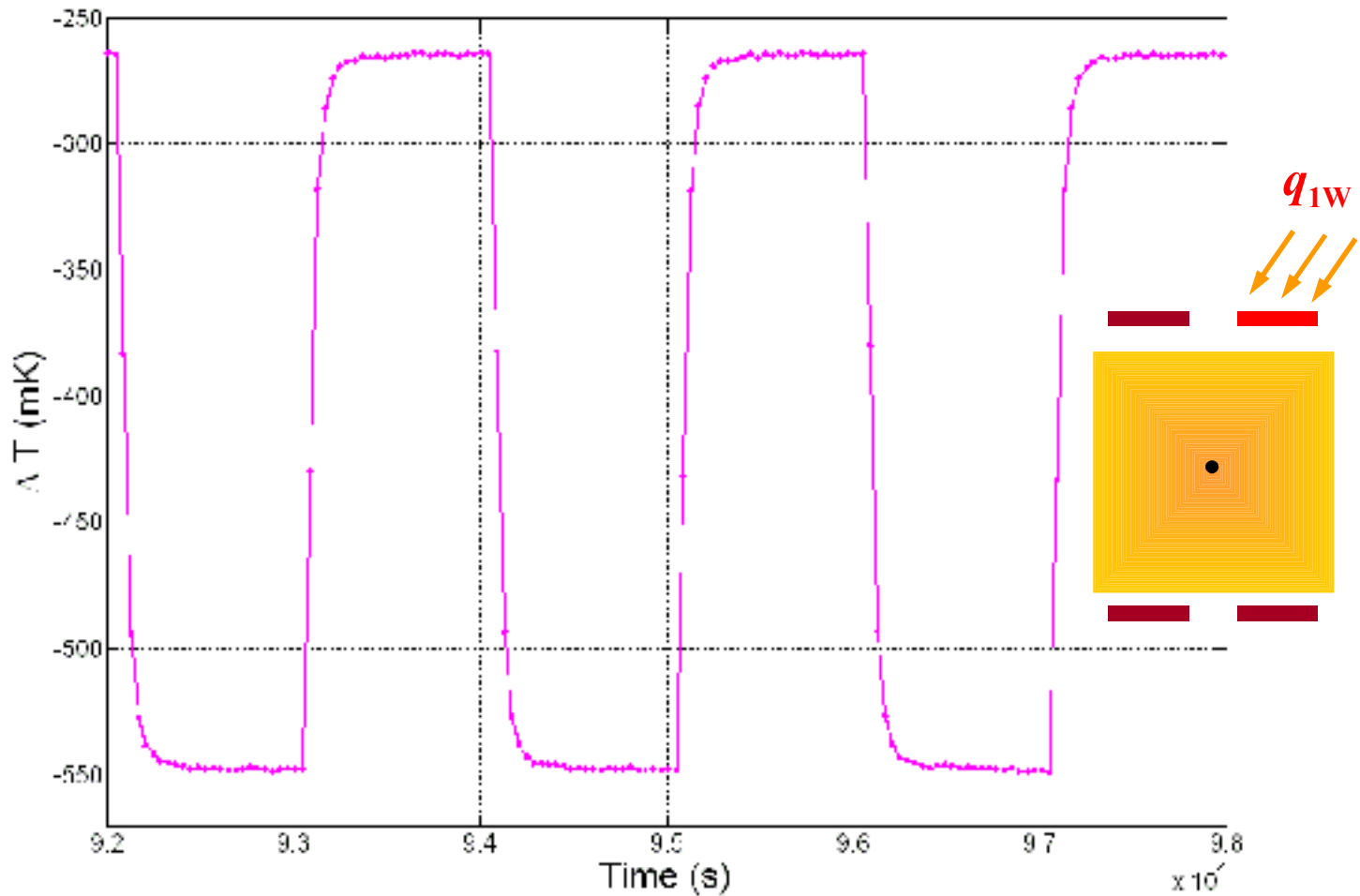
STEP-1
SLE=14
TIME=1000
TEMP (AVG)
REYS=0
HMY=77.17
SMX=22.709



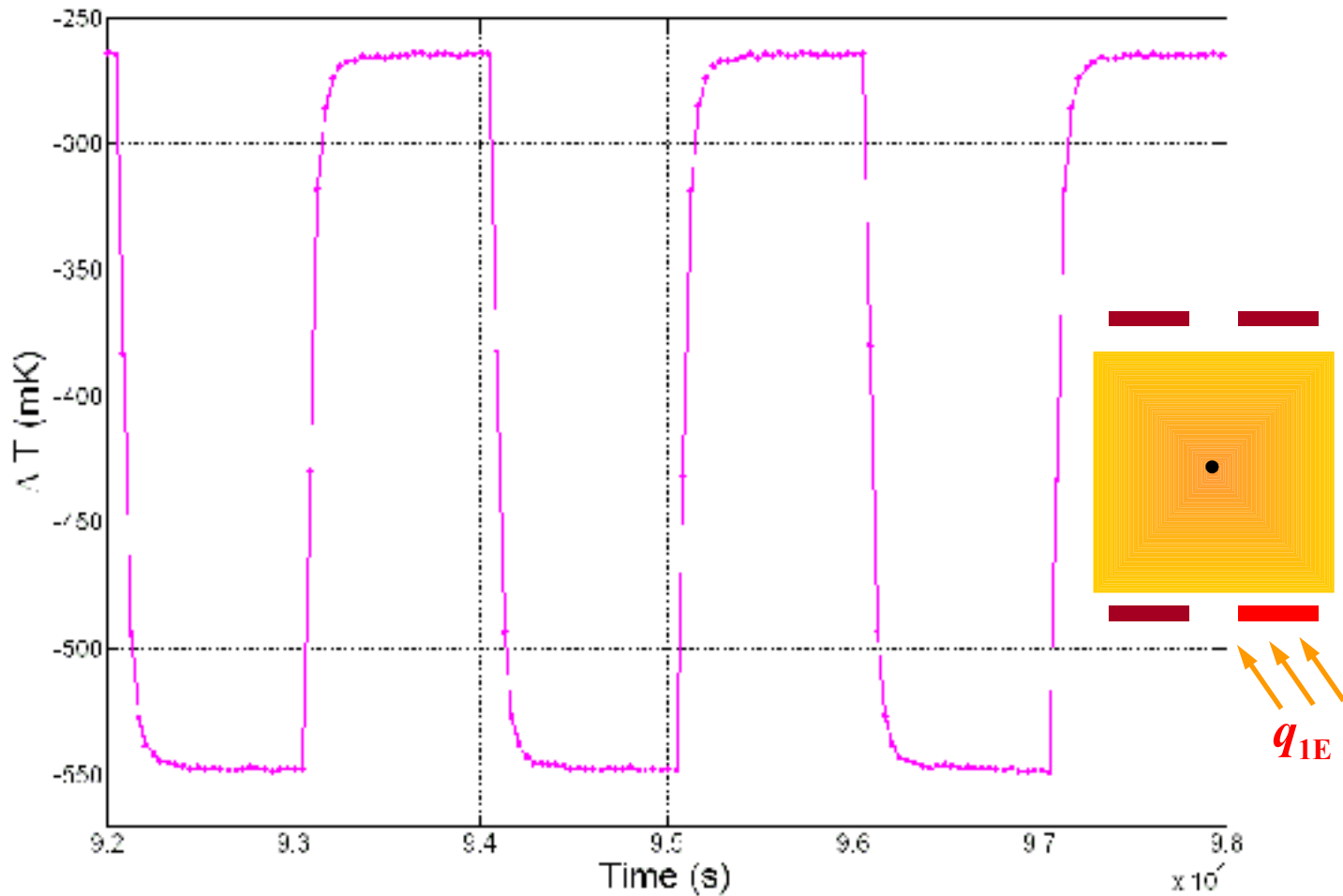
Thermometers



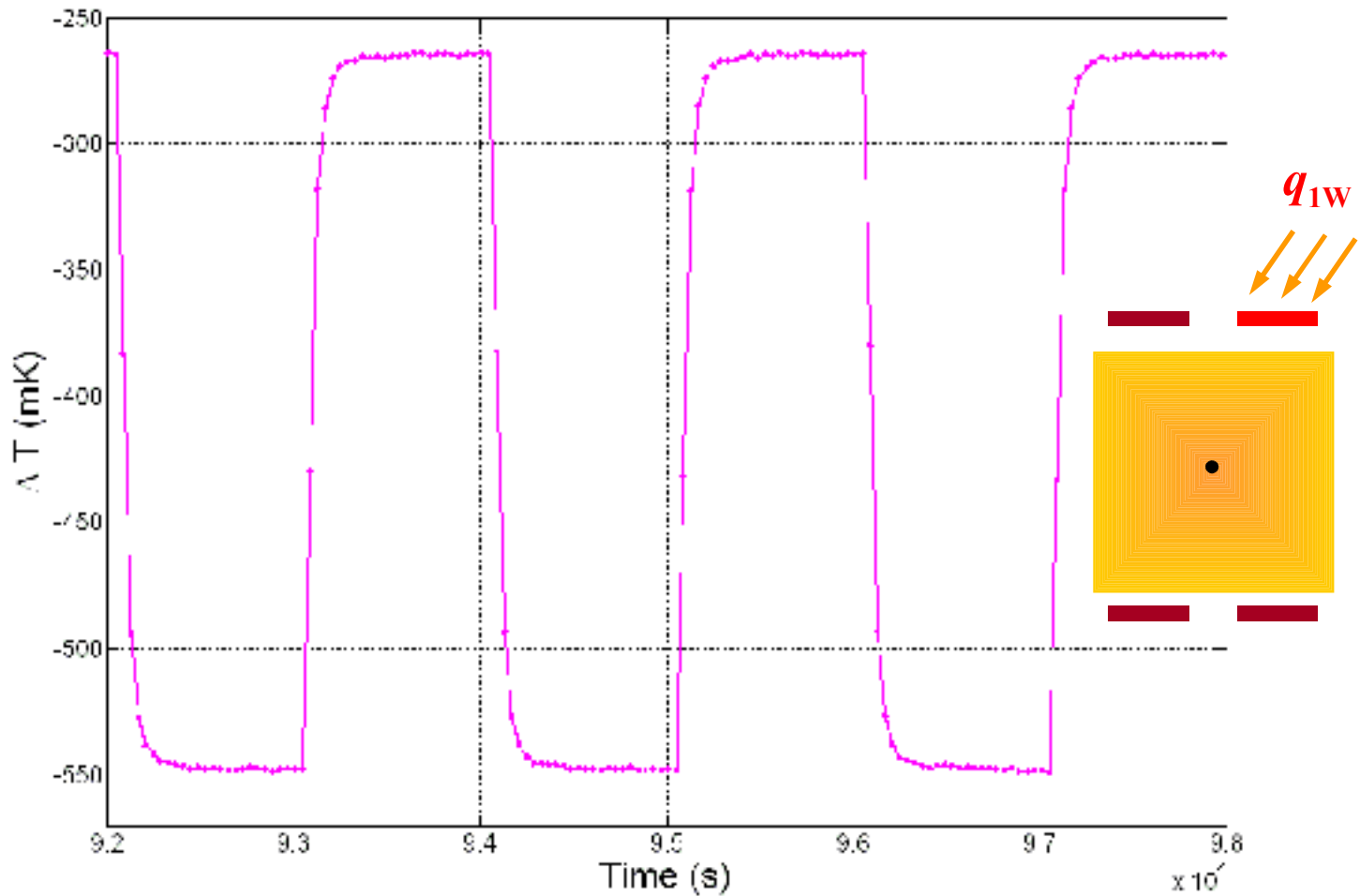
Pendulum sensor



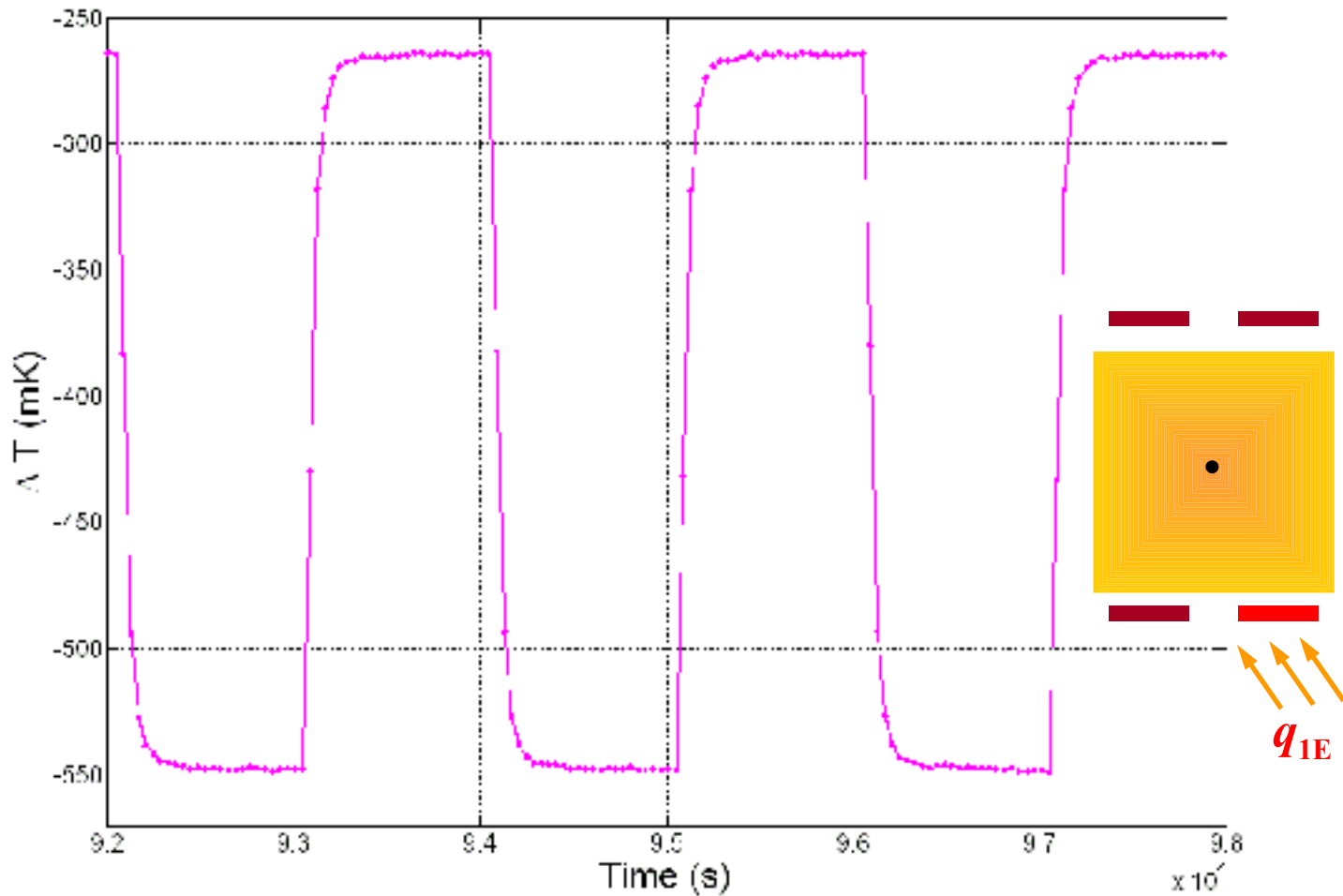
- Alternate 0.2Watts on opposed electrodes (1W-1E) @ 0.5mHz
- Temperature measured in vicinity of heaters
- $T_{ave} \approx 22^\circ\text{C}$



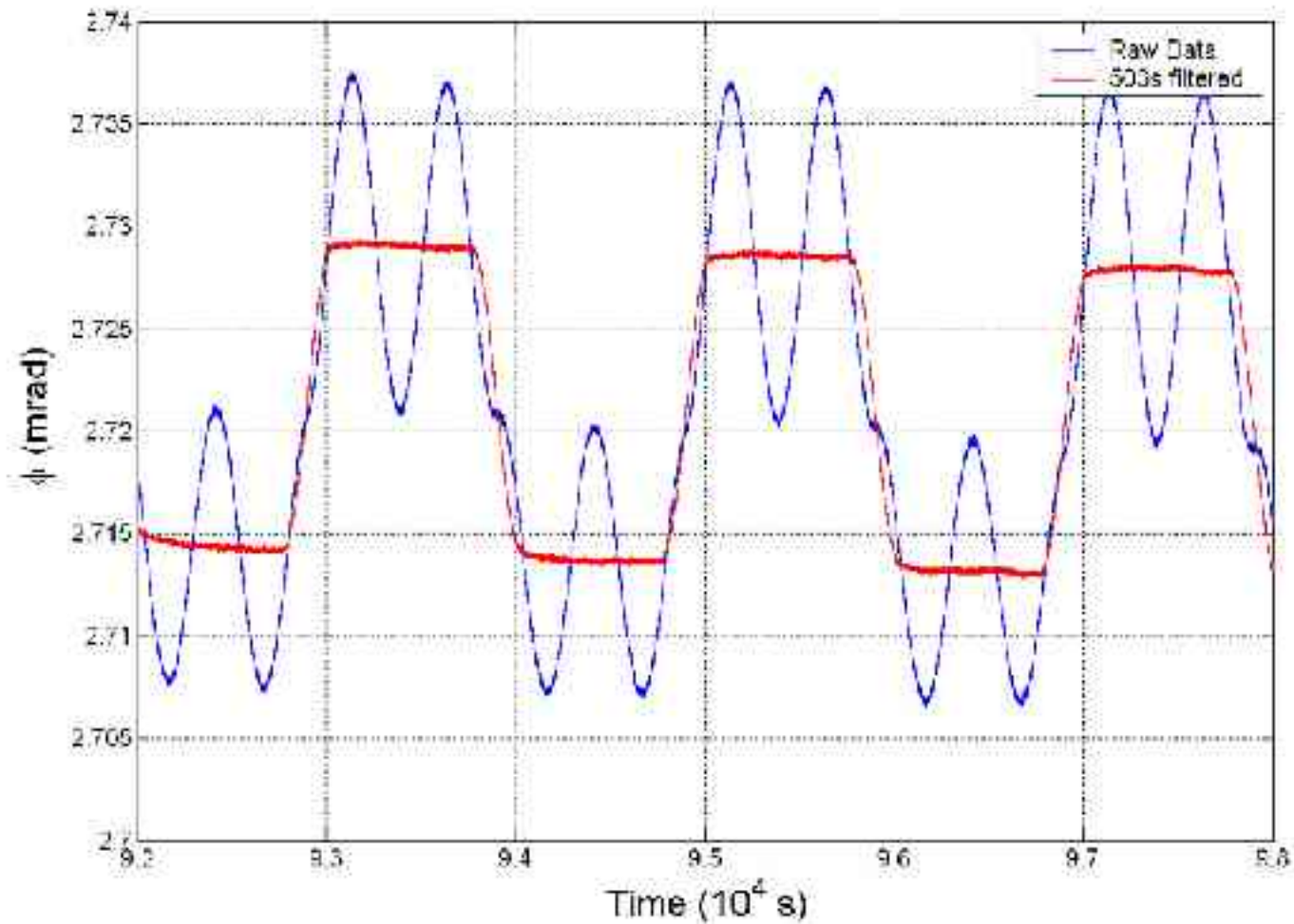
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- Pendulum coherent response:
equilibrium position changes every 1000s
- Vacuum chamber Pressure $\approx 5 \cdot 10^{-8}$ mbar

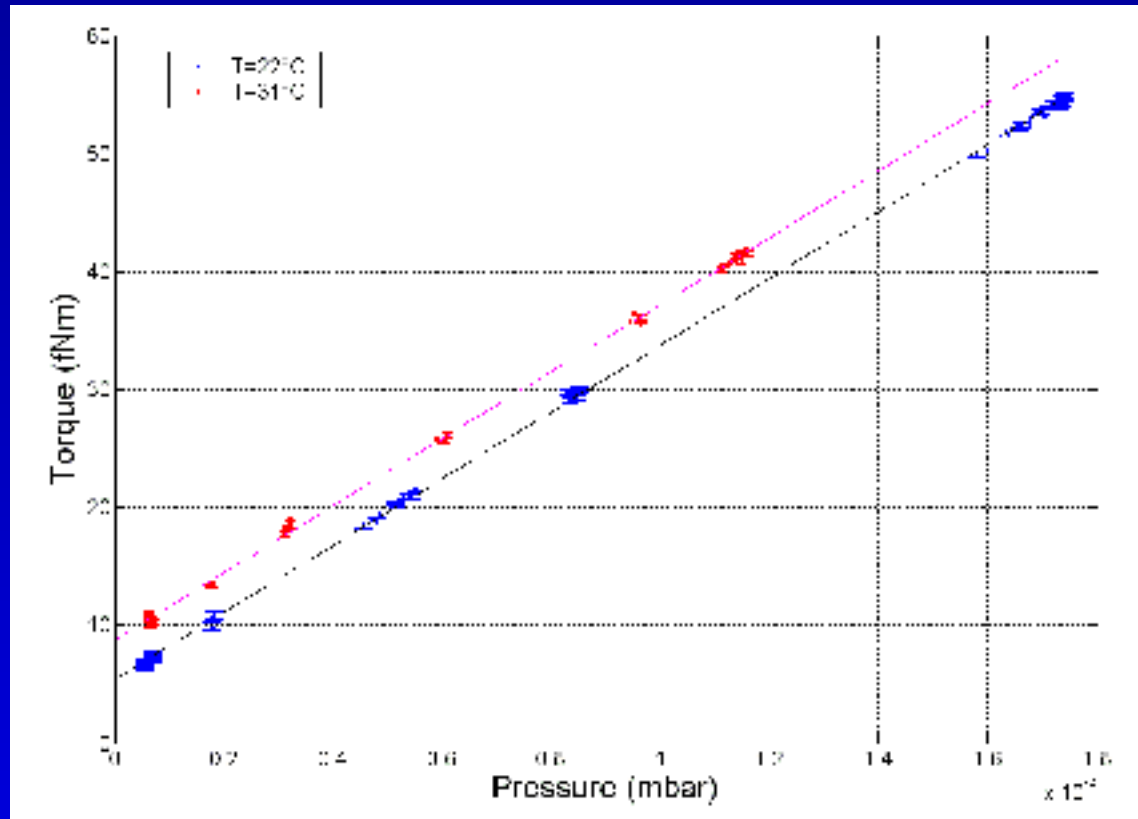
Thermal gradient effects as function of pressure and temperature

Measurement of induced torque
as function of pressure and
temperature

$$N_{radiom} \propto P_{out} \frac{\Delta T_{eff}}{T_s}$$

$$N_{outgas} \propto \frac{\Delta T_{eff}}{T_s^2} \Theta Q_{outgas}$$

$$N_{rad\ press} \propto T_s^3 \Delta T_{eff}$$



Preliminary results:

- measured torque is consistent with radiometric+radiation pressure effects (factor ≈ 2 uncertainty in effective temperature gradient)
- no evidence of huge temperature dependent outgassing effects!

Investigation needed:

- pressure and temperature interpretation
- applied effective thermal gradient modeling

Summary of main results:

- More stringent upper limits to stray forces (extending to lower frequencies)
- Measured Overall Spring-like coupling
- New technique for measuring dielectric loss angle
- Thermal gradients induced effects under investigation

- Charge measurement technique successfully demonstrated
- Charge Control based on UV light demonstrated
- Stray DC bias voltage measurement and compensation improved