

Electronic Phase Delays

- A First Step Towards A Bench-Top Model of LISA -



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Overview



Current Work

- What is Electronic Phase Delay (EPD)?
- Using EPD to make a “Synthetic Interferometer”

Future Work

- Upcoming experiments
- The bench-top LISA model



Introduction I -

A Simple Model of A Single LISA Arm



- Laser field

$$E(t) = E_0 \exp\{i[\omega t + \phi(t)]\}$$

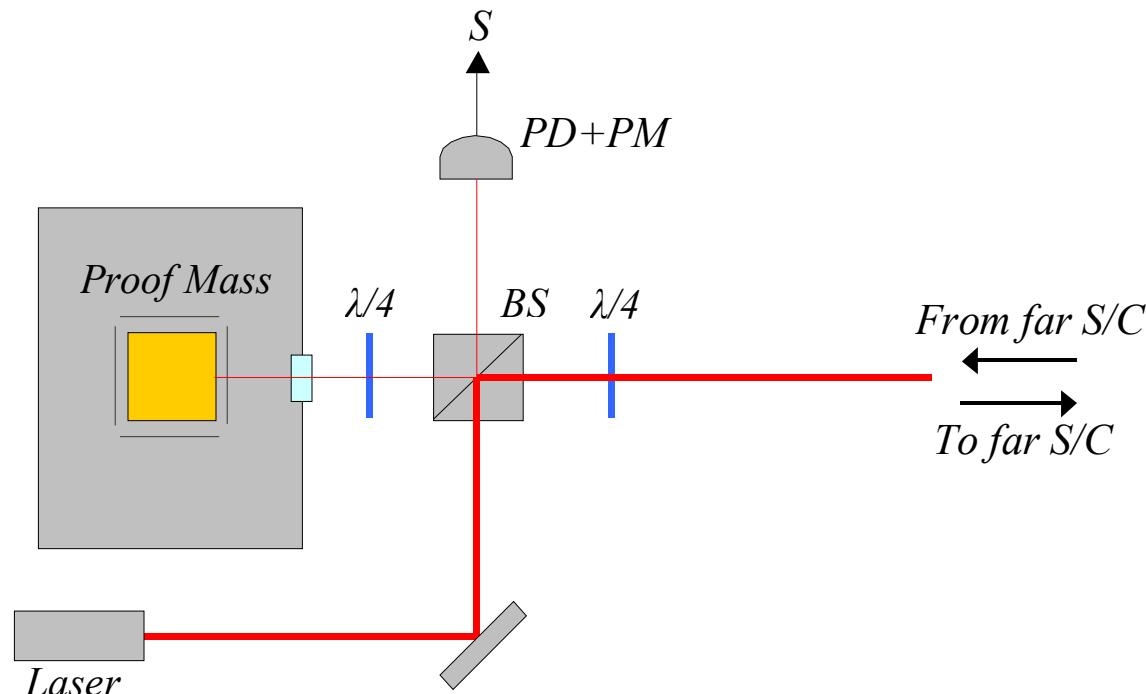
- Phase Meter (PM) Signal

$$S(t) \propto \phi(t) - \phi(t - \tau_{RT})$$

τ_{RT} ⑤ round-trip light
travel time

- Simplifying Assumptions

- far S/C acts as perfect optical transponder (mirror)
- stationary S/C (no Doppler shifts)





Introduction II - The Problem



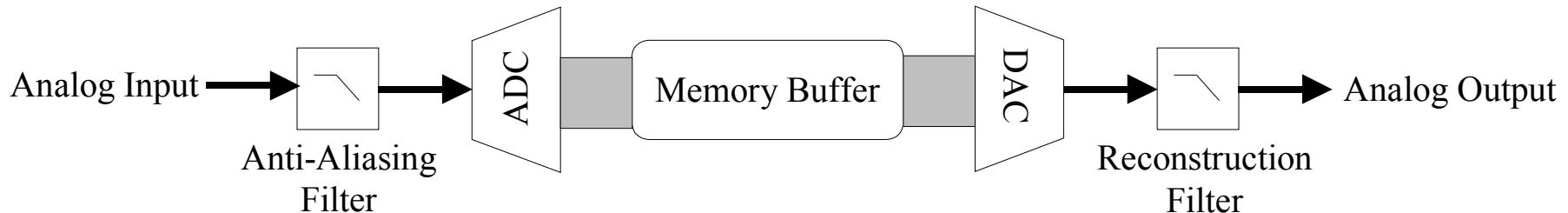
The large Optical Path Lengths (OPLs) in LISA correspond to $\tau_{\text{RT}} \sim 33\text{s}$. It is virtually impossible to create physical OPLs of this size in the laboratory.

Solution: We only need to delay the *phase* of the laser.

- demodulate it with a stable oscillator (another laser)
 - digitize the difference phase
 - store it in a buffer
 - regenerate the signal
- } Electronic Phase Delay (EPD)



Implementation of Electronic Phase Delay (EPD)



Three Steps

- Digitize input signal
- Store in a FIFO memory buffer for the desired time.
- Regenerate analog signal

Limitations

- Digitization Rate (limits bandwidth)
- Digitization Precision (noise)

Current Iteration

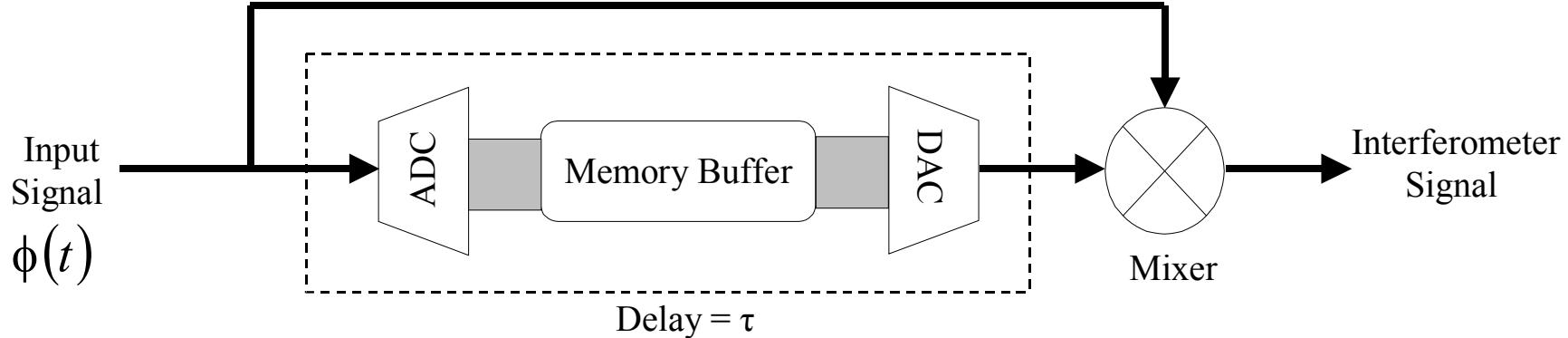
- MicroStar DAP5216a Data Processing Card
- 200kS/s
- 16-bit
- signals \bullet 30kHz are reproduced well

Future Technologies

- Increase digitization rate so that signals up to 20MHz can be delayed.



Using EPD to Make a Synthetic Interferometer

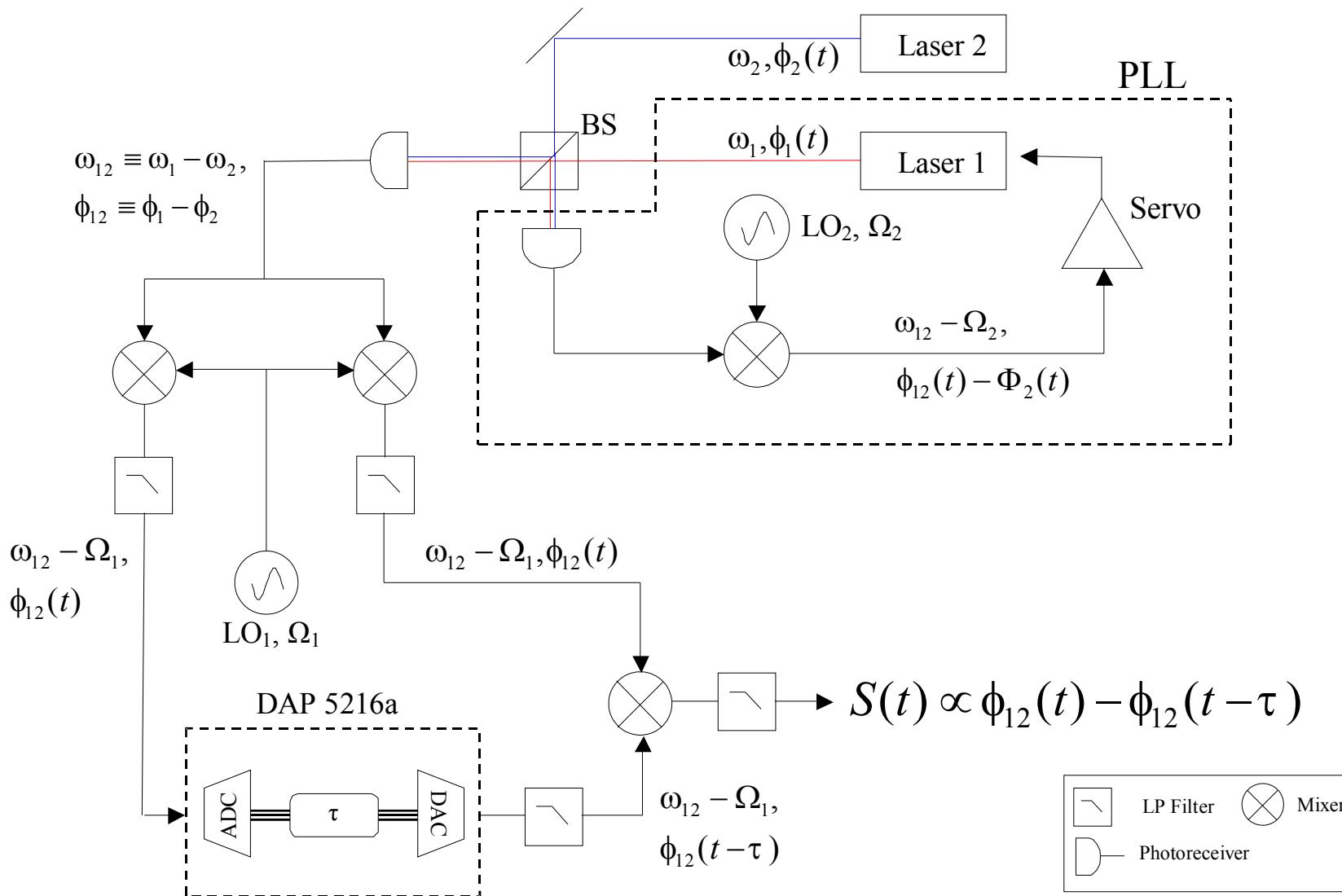


$$\text{Mixer Output, } S \propto \phi(t) - \phi(t - \tau)$$

Equivalent to an interferometer with
one long arm having a delay of τ



Demonstration of a Synthetic Interferometer





Response To Frequency Step



- Time delay

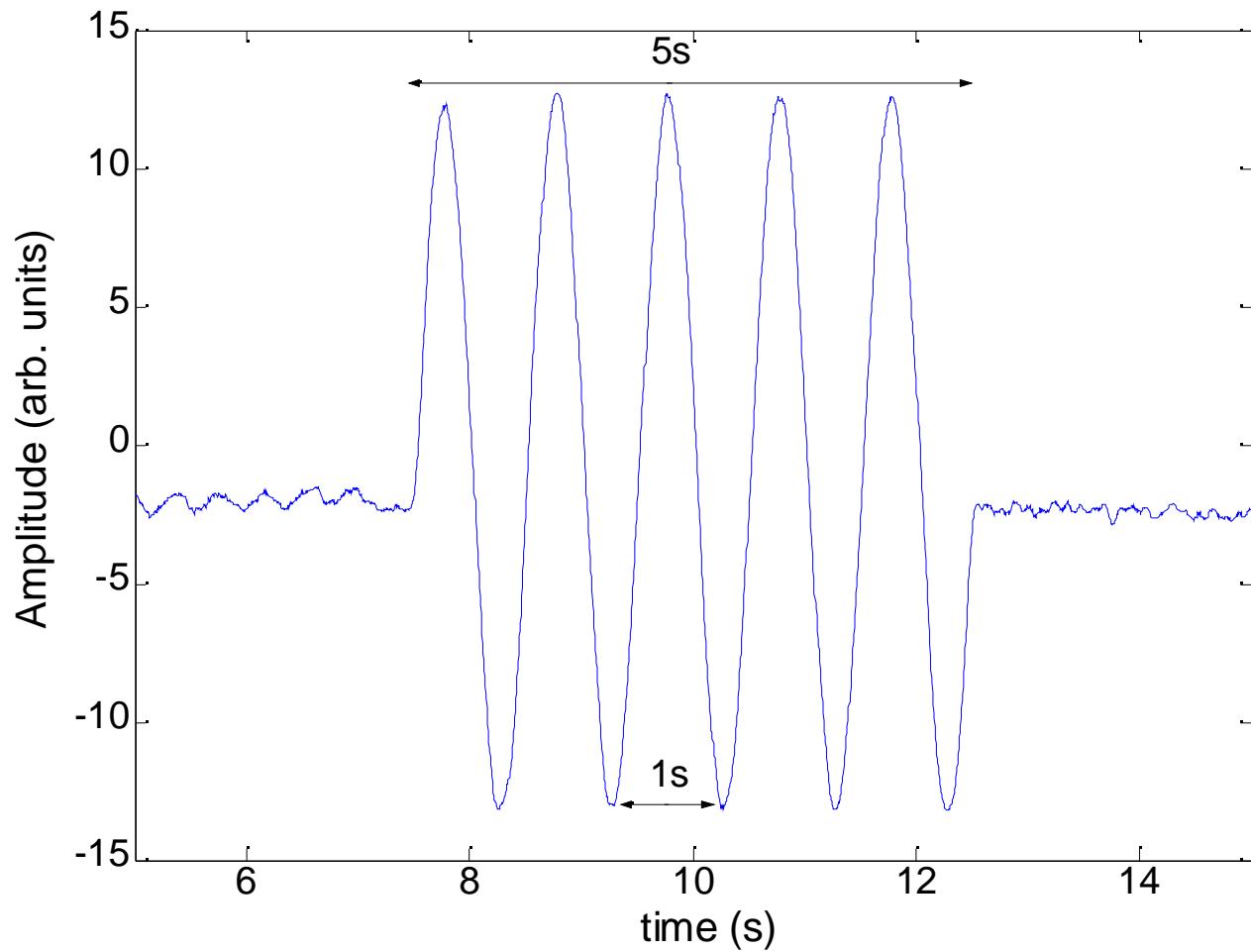
$$\tau = 5s$$

- Step change of 1Hz
on Laser 1

(Achieved by stepping LO₂)

- Observed Response

1Hz oscillation lasting
for 5s.





Frequency Response



- Time delay

$$\tau = 1\text{s}$$

- Frequency Ramp
on Laser 1

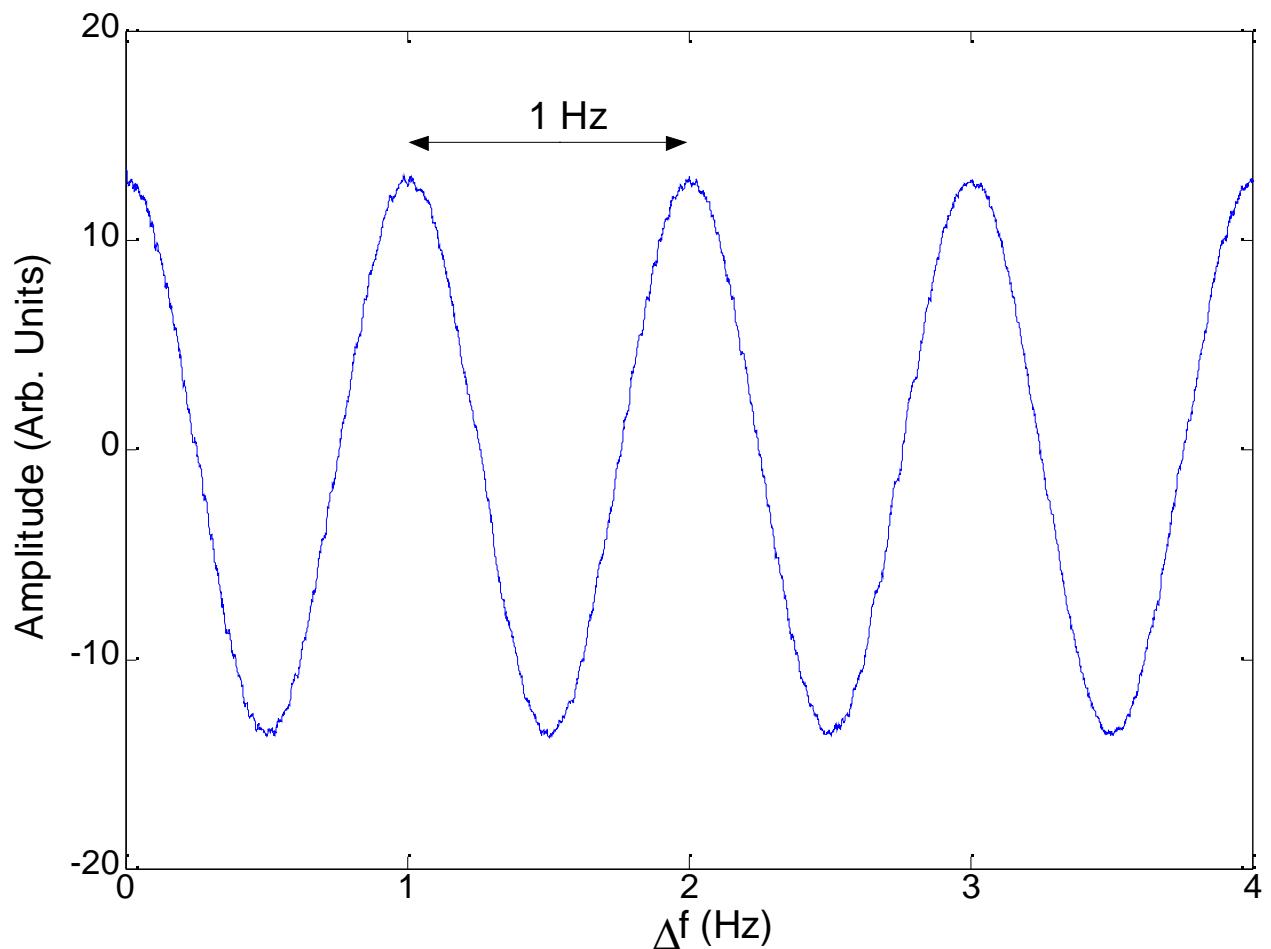
(by modulating LO₂)

$$\Omega_2 = 2\pi(20.03\text{MHz} + \Delta f)$$

$$\Delta f = (100\text{mHz/s}) \times t$$

- Observed Response

Sinusoidal amplitude variations with a frequency spacing of $1/\tau = 1\text{Hz}$





Response to Phase Modulation I - Theory



- Mixer Output

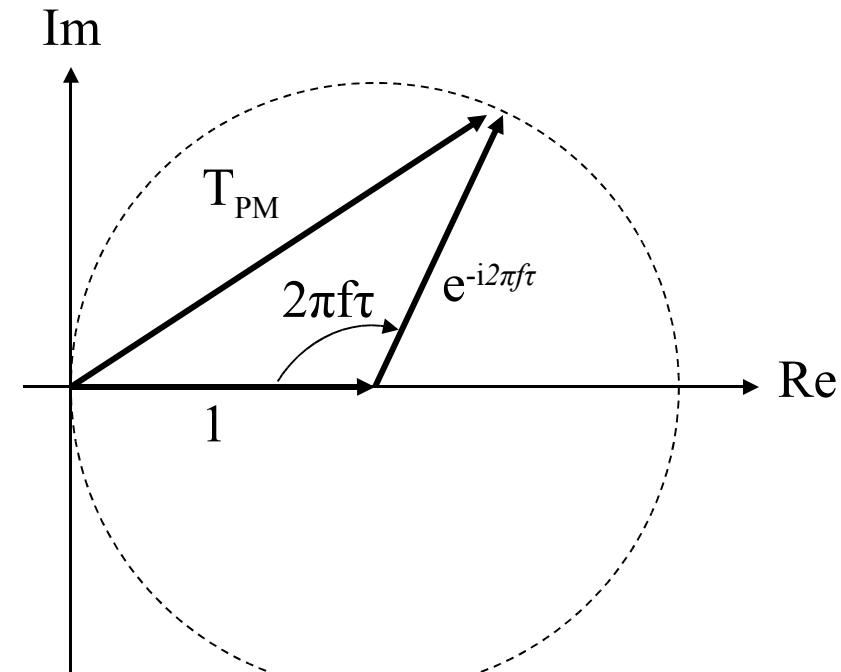
$$S(t) \propto \phi_{12}(t) - \phi_{12}(t - \tau)$$

- Fourier Transform

$$\tilde{S}(2\pi f) \propto \tilde{\phi}_{12}(2\pi f) \left(1 - e^{-i2\pi f\tau}\right)$$

- Transfer Function

$$T_{PM}(2\pi f) \equiv \frac{\tilde{S}(2\pi f)}{\tilde{\phi}(2\pi f)} \propto \left(1 - e^{-i2\pi f\tau}\right)$$



$$|T_{PM}(2\pi f)| \propto |\sin(\pi f\tau)|$$

$$\angle T_{PM}(2\pi f) = \tan^{-1}[\cot(\pi f\tau)]$$



Zeros at $f_0 \bullet n / \tau$

Phase Discontinuity
from -90° to $+90^\circ$ at f_0



Response to Phase Modulation II - Results



- Time delay

$$\tau = 1s$$

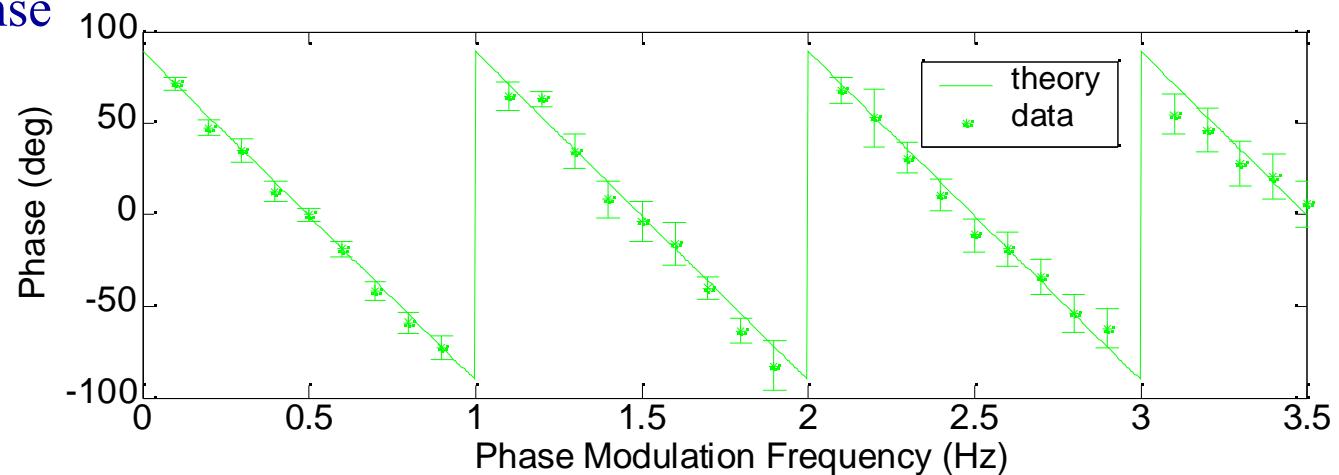
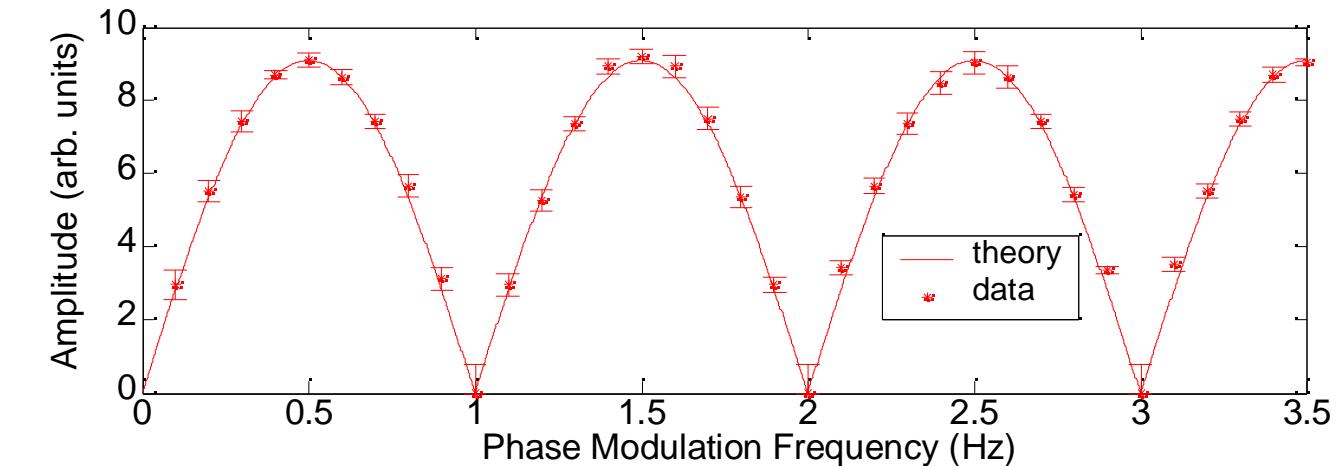
- PM on Laser 1

- Sinusoidal at a frequency of f_{PM} with a modulation depth of 20° .

- Observed Response

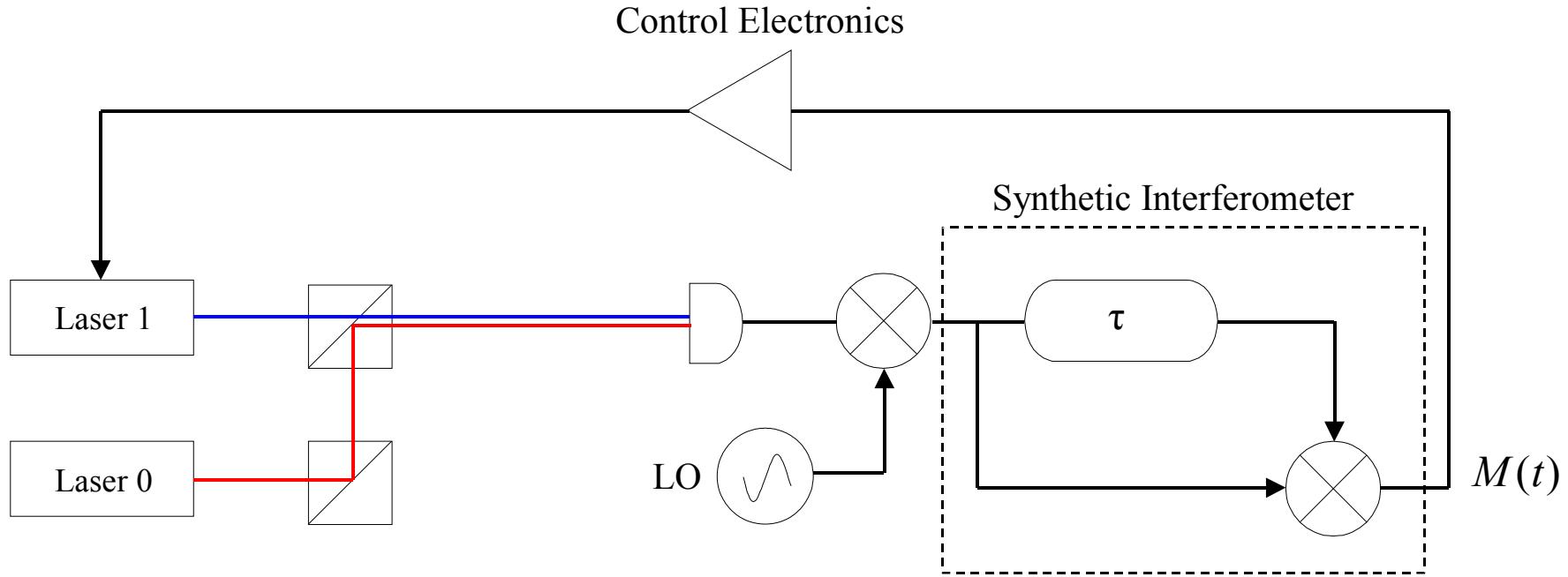
- No response at $f_{PM} = n/\tau$,
 $n = 1, 2, 3 \dots$

- 180° phase discontinuity at $f_{PM} = n/\tau$





The Next Step I – Arm Locking



Interferometer Signal

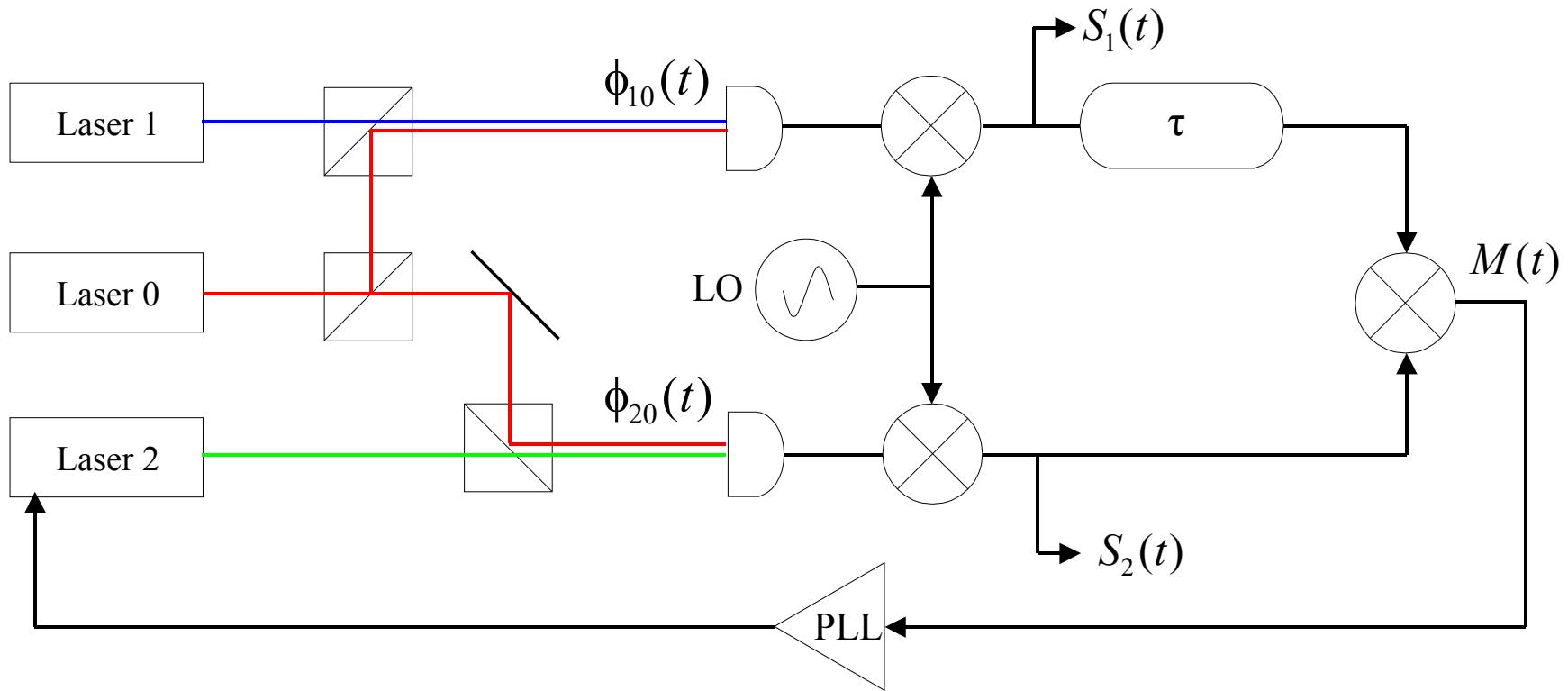
$$M(t) \propto \phi_{10}(t) - \phi_{10}(t - \tau)$$

Lock laser phase difference to interferometer zero

$$\phi_{10}(t) = \phi_{10}(t - \tau)$$



The Next Step II – “TDI” With a Single LISA Arm

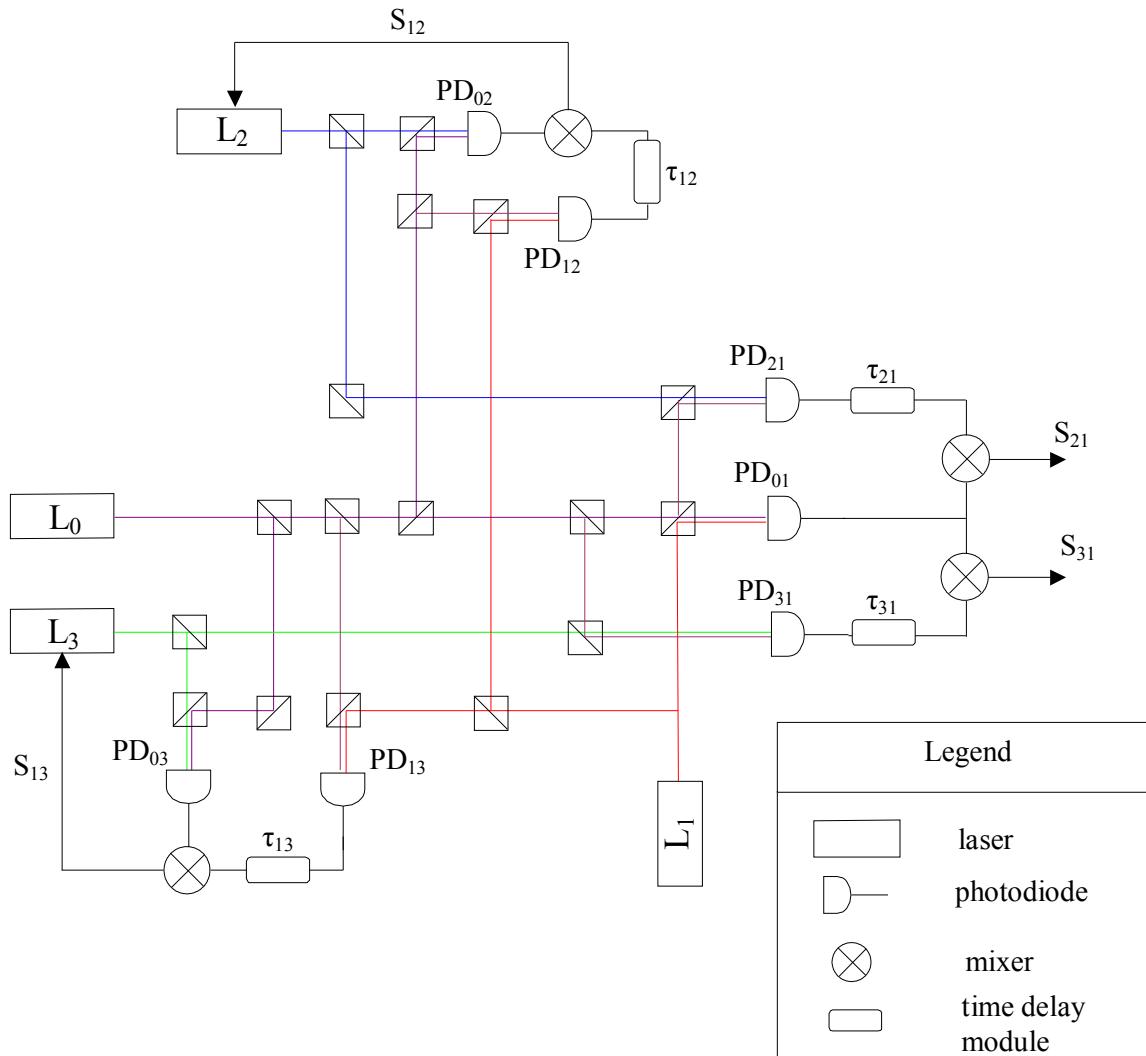


$$\text{Phase Lock} \quad M(t) = 0 \Rightarrow \phi_{20}(t) = \phi_{10}(t - \tau)$$

$$\text{Experimental Test} \quad \angle S_2(t) = \overset{?}{\phi_{20}(t)} = \angle S_1(t - \tau) = \phi_{10}(t - \tau)$$



The Next Step III – TDI with Two Arms



Interferometry Signals on S/C 1

$$S_{21}(t) \& S_{31}(t)$$

Experimental Test of TDI

$$\begin{aligned} & S_{21}(t) - S_{21}(t - \tau_{13} - \tau_{31}) \\ & - S_{31}(t) + S_{31}(t - \tau_{12} - \tau_{21}) \\ & = 0? \end{aligned}$$

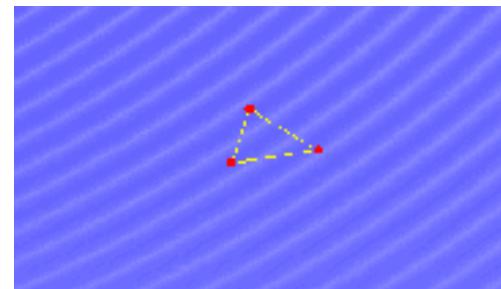


Long Term – Getting to a model LISA



- Incorporate additional features
 - clock noise
 - Doppler shifts
 - bench motion
- Add 3rd arm
- Add GW signals
- Incorporate data reduction algorithms
- ...?

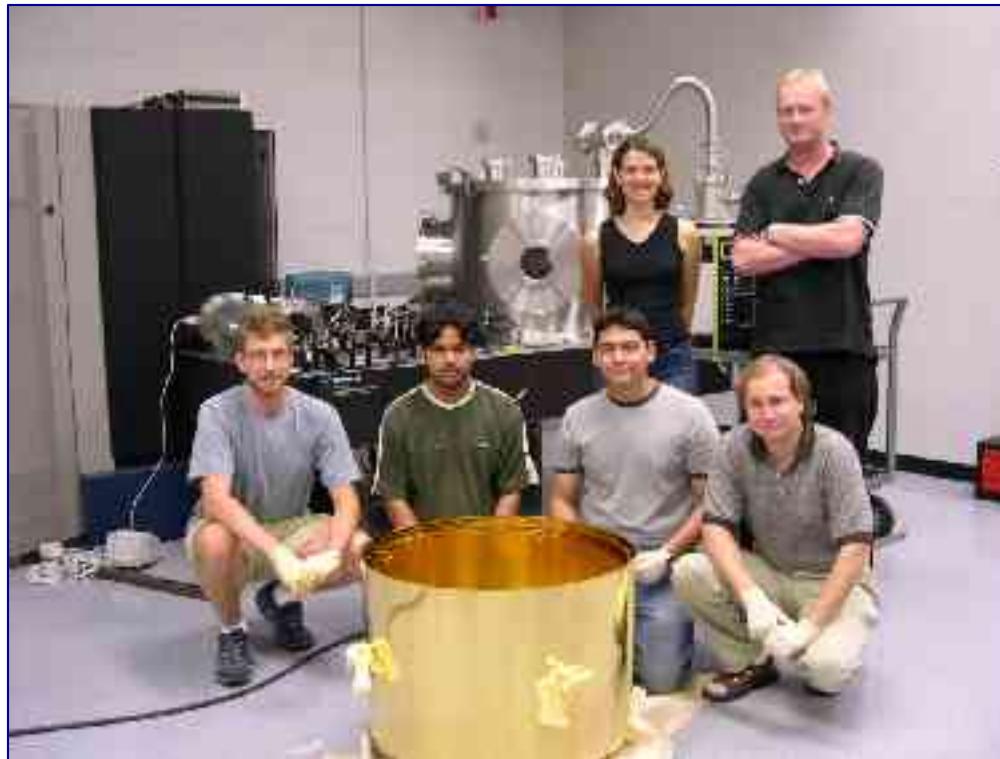
Take it for a test drive!



Host a “Mock Data Challenge” in which we inject a GW signal and then attempt to extract it.



Thanks/Questions



The LISA crew at UFL

(front row, left to right) Ira Thorpe, Shannon Sankar, Rodrigo Delgadillo, Derek Mulder (standing) Rachel Parks, Guido Mueller



Frequency Response - 2



- Time delay

$$\tau = 5\text{s}$$

- FM on Laser 1

(by modulating LO₂)

$$\Omega_2 = 2\pi(20.03\text{MHz} + \Delta f)$$

$$\Delta f = (100\text{mHz/s}) \times t$$

