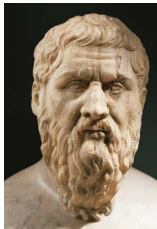


Update on inversion methodologies

D. R. Reese

Université de Liège, Belgium

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Introduction

PLATO mission

Scientific goals:

- study exoplanetary systems as a whole
 - mass, radius, age determination of host stars
- gain a better understanding of stars

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Asteroseismology is extremely important because of its ability to probe stellar interiors and its high precision

Asteroseismology

Direct approach

- **description:** search for optimal model in a restricted parameter space
- **advantages:** simplicity, physically coherent models

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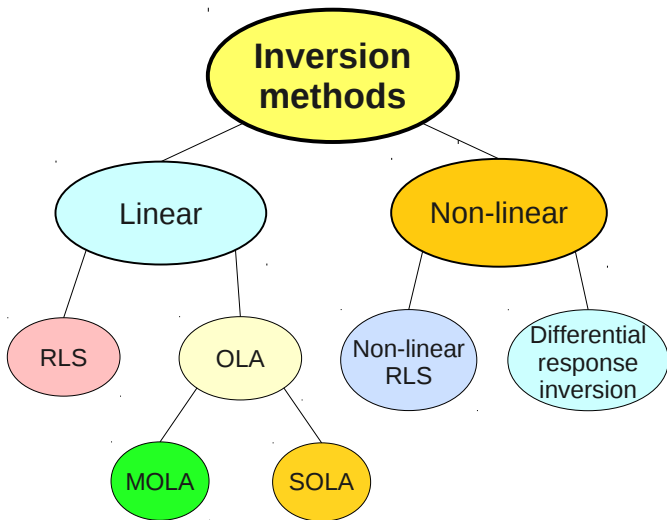
Inversion methods

- **description:** adjust the structure of a reference model so as to match the observed frequencies
- **advantages:** extracts more information from frequencies, open to new physics

Comparison

- rather than opposing each other, the two approaches are complementary:
 - the direct approach can provide an initial model for an inverse method

Classification of inversion methods



Linear inversion methods

- **assumption:** reference model sufficiently close to real star so that:



- **Rotation profile:**
$$\frac{\nu_{nlm} - \nu_{nl0}}{m} = \int_0^R K_{\Omega}^{nl}(r) \Omega(r) dr$$
- **Structural change:**
$$\frac{\delta\nu}{\nu} = \int_0^R \left[K_{c^2 \rho}^{nl}(r) \frac{\delta c^2}{c^2} + K_{\rho c^2}^{nl} \frac{\delta \rho}{\rho} \right] dr$$
 - the *kernels* K_{Ω}^{nl} , $K_{c^2 \rho}^{nl}$, and $K_{\rho c^2}^{nl}$ are deduced from the variational principle
- **Goal:** inverse above integral relations

Linear inversion methods

Averaging and cross-term kernels

- linear inversion \Rightarrow solution is a linear combination of frequency differences:

$$\Omega_{\text{inv}}(r_0) = \sum_{n\ell} c_{n\ell}(r_0) \frac{\nu_{n\ell m} - \nu_{n\ell 0}}{m} = \int_0^R \underbrace{\left[\sum_{n\ell} c_{n\ell}(r_0) K_{\Omega}^{n\ell}(r) \right]}_{\mathcal{K}_{\text{avg}}(r_0, r)} \Omega(r) dr$$

$$\frac{\delta c_{\text{inv}}^2(r_0)}{c^2(r_0)} = \sum_l c_l \frac{\delta \nu_l}{\nu_l} = \int_0^R \underbrace{\sum_l c_l K_{c^2}^l}_{\mathcal{K}_{\text{avg}}(r_0, r)} \frac{\delta c^2}{c^2} dr + \int_0^R \underbrace{\sum_l c_l K_{\rho c^2}^l}_{\mathcal{K}_{\text{cross}}(r_0, r)} \frac{\delta \rho}{\rho} dr$$

- \mathcal{K}_{avg} = averaging kernel (e.g. Christensen-Dalsgaard et al., 1990)
- $\mathcal{K}_{\text{cross}}$ = cross-term kernel

Linear inversion methods

Error propagation

- the observational errors propagate into the result as follows:

$$\sigma_{f(r_0)} = \sqrt{\sum_i c_i^2 \sigma_i^2}$$

- other sources of error are **not** taken into account in this formula:
 - poorly localised averaging kernel
 - strong cross-term kernel
 - underlying model too far from star

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 - underlying model too far from star

Two approaches

- **RLS**: Regularised Least-Squares
- **OLA**: Optimally Localised Averages

The RLS method

- **RLS**: Regularised Least-Squares
- **Goal**: minimise frequency differences by adjusting internal profiles
- minimisation of following cost function:

$$J(f) = \underbrace{\sum_{l=1}^L \left\{ \frac{\nu_m^l - \nu_0^l}{\sigma_l} - \int_0^R K_{\Omega}^l(r) f(r) dr \right\}^2}_{\text{fit data}} + \underbrace{\Lambda \left\langle \frac{1}{\sigma^2} \right\rangle \int_0^R \left\{ \frac{d^2 f}{dr^2} \right\}^2 dr}_{\text{regularisation}}$$

- where:

$$f = \sum_i a_i \phi_i(r) = \text{the function we're trying to invert}$$

$$\sigma_l = \text{observational errors}$$

$$\Lambda = \text{regularisation trade-off parameter}$$

The OLA methods

- **OLA**: Optimally Localised Averages
- **Goal**: optimise the averaging kernels

- **MOLA**: Multiplicative OLA (Backus & Gilbert, 1968)

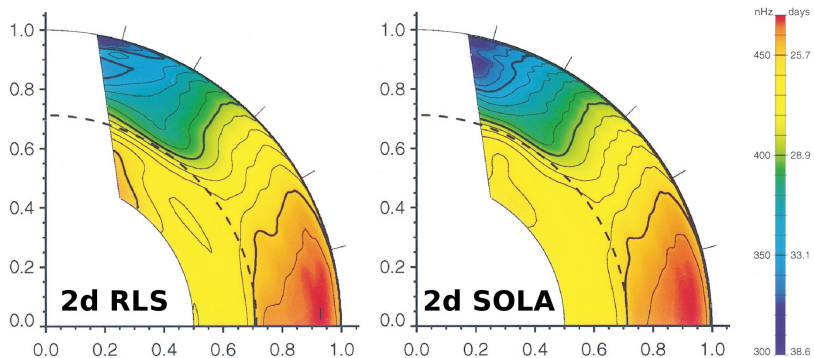
$$J(c_I(r_0)) = \underbrace{\int_0^R J(r_0, r) [\mathcal{K}_{\text{avg}}(r_0, r)]^2 dr}_{\text{fit data}} + \underbrace{\frac{\tan \theta}{\langle \sigma^2 \rangle} \sum_{l=1}^L (c_l \sigma_l)^2}_{\text{regularisation}} + \lambda \underbrace{\left\{ 1 - \int_0^R \mathcal{K}_{\text{avg}} \right\}}_{\mathcal{K}_{\text{avg}} \text{ unimodular}}$$

- **SOLA**: Subtractive OLA (Pijpers & Thompson, 1992, 1994)

$$J(c_I(r_0)) = \int_0^R \underbrace{[\mathcal{T}(r_0, r) - \mathcal{K}_{\text{avg}}(r_0, r)]^2}_{\text{target}} dr + \dots$$

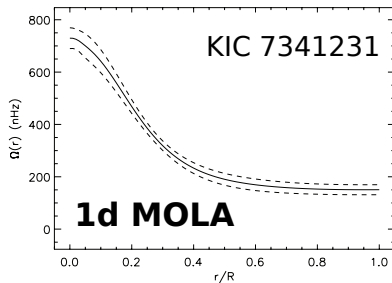
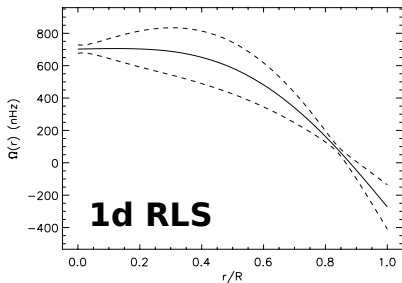
- MOLA method: fewer free parameters
- SOLA method: less computationally expensive (1 matrix inversion)

Some examples



The solar rotation profile
(Schou et al., 1998, see also Thompson et al., 2003)

Some examples



Rotation profile of a lower-giant-branch star
(Deheuvels et al., 2012)

Stellar parameters

- structural inversions are difficult for stars other than the Sun, due to the limited number of modes (e.g. Basu et al. 2002)
- one strategy is to invert stellar parameters rather than structural profiles

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How does it work?

$$\frac{\delta\rho_{\text{inv}}(r_0)}{\rho(r_0)} = \int_0^R \mathcal{K}_{\text{avg}}(r_0, r) \frac{\delta\rho}{\rho} dr + \int_0^R \mathcal{K}_{\text{cross}}(r_0, r) \frac{\delta\Gamma_1}{\Gamma_1} dr$$

- an inversion gives you a weighted average of the underlying profile
- **idea**: directly search for the appropriate weighting which yields the stellar parameter
- carry out a SOLA inversion with a suitable target function:

$$\text{Target function} = \frac{4\pi r^2 \rho R}{M} \Rightarrow \text{stellar mean density}$$

Stellar parameters

What parameters are accessible?

- total angular momentum (Pijpers, 1998)
- mean density (Reese et al. 2012)
- acoustic radius (Buldgen, Master's thesis, 2013)
- age indicator, based on small frequency separation (Buldgen, Master's thesis, 2013)
- ...

Stellar parameters

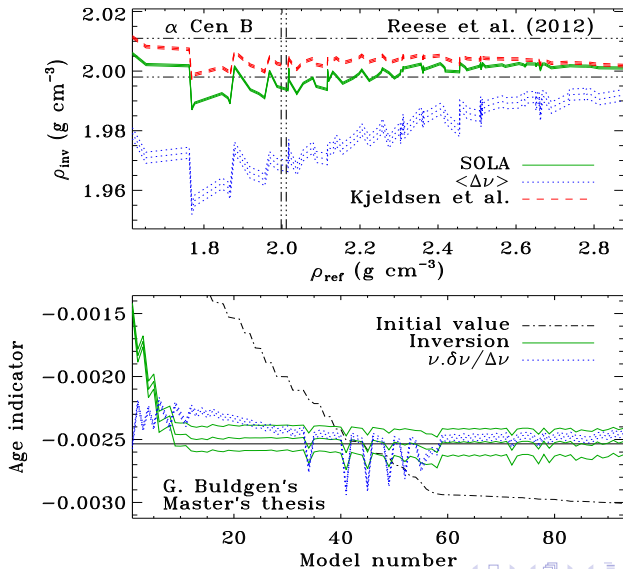
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Non-linear extension

- **purpose:** extend the inversion's range of application
- **applies to:** mean density and acoustic radius
- optimally scaling the reference model before carrying out the inversion

Some examples



Non-linear inversion methods

- a second strategy for structural inversions in stars other than the Sun
- useful for stars with mixed modes which are highly sensitive to structural changes
- applies even when the reference model is far away from true structure

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Two approaches

- frequency-based approach
- approach based on internal phase-shifts

Non-linear RLS

Description

- iterated RLS inversions
- minimisation of the following cost function:

$$J(f) = \sum_i \left(\frac{\nu_i^{\text{obs}} - \nu_i^{\text{theo}}(f)}{\sigma_i} \right)^2 + \Lambda \{\text{regularisation term}\}$$

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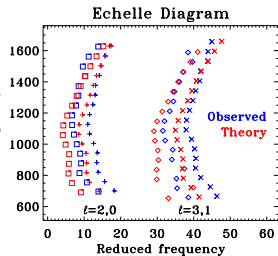
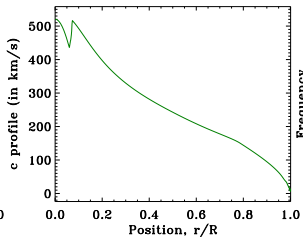
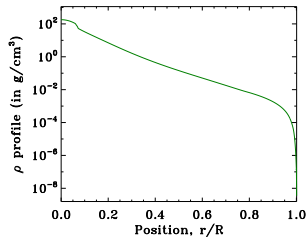
$$J(f) = \sum_i \left(\frac{\nu_i^{\text{obs}} - \nu_i^{\text{theo}}(f)}{\sigma_i} \right)^2 + \Lambda \{\text{regularisation term}\}$$

Different works

- **Antia (1996)**: inversion on (ρ, Γ_1) , regularisation of $\left(\frac{\delta\rho}{\rho}, \frac{\delta\Gamma_1}{\Gamma_1} \right)$
- **Reese (ongoing)**: inversion on ρ , fixed Γ_1 profile, regularisation of ρ

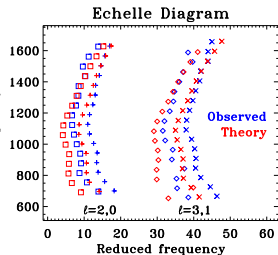
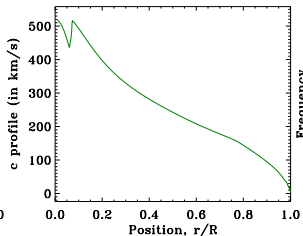
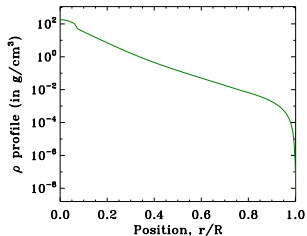
Some examples

Original model

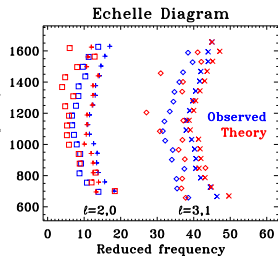
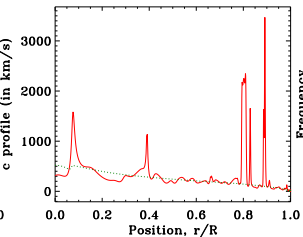
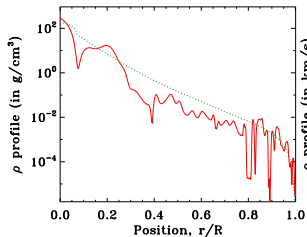


Some examples

Original model



Linear regularisation



Regularisation

- clearly, the regularisation term is unsuitable:

$$\Lambda \int_0^{R_{\text{cut}}} \left(\frac{\partial^2 \rho}{\partial r^2} \right)^2 dr$$

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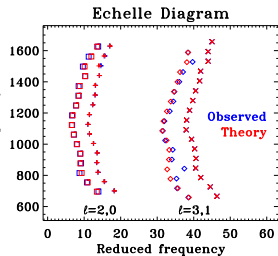
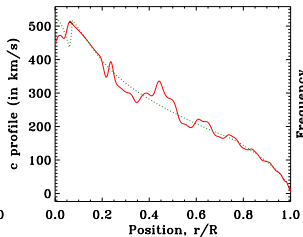
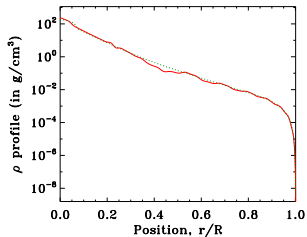
$$\Lambda \int_0^{R_{\text{cut}}} \left(\frac{\partial^2 \rho}{\partial r^2} \right)^2 dr$$

- therefore, a different regularisation term was tested out:

$$\Lambda \int_0^{R_{\text{cut}}} \left(\frac{\partial^2 (\ln \rho)}{\partial r^2} \right)^2 dr$$

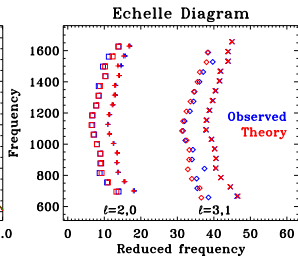
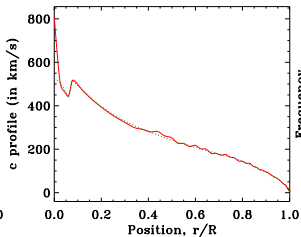
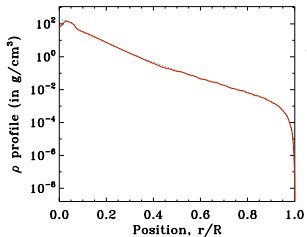
Some examples

Logarithmic regularisation

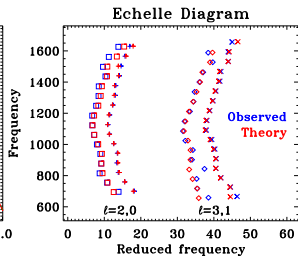
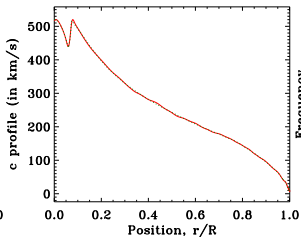
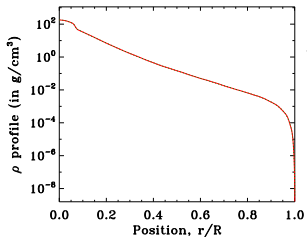


Some examples

With surface corrections

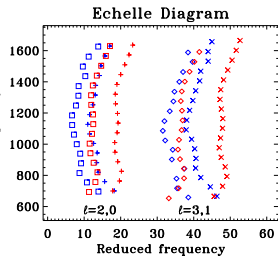
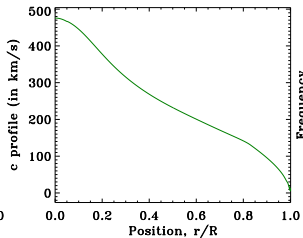
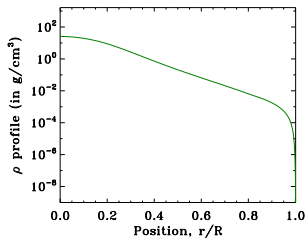


With surface corrections



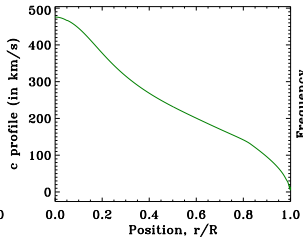
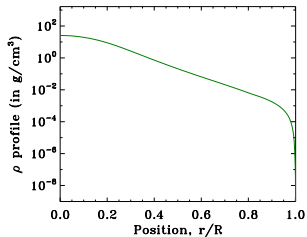
Some examples

Logarithmic regularisation

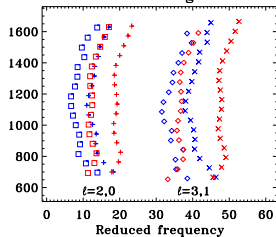


Some examples

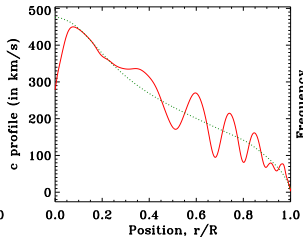
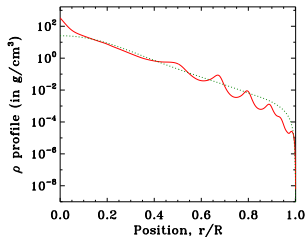
Logarithmic regularisation



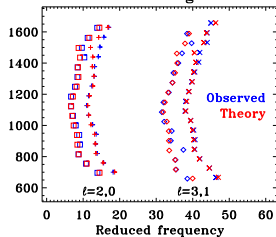
Echelle Diagram



Logarithmic regularisation



Echelle Diagram



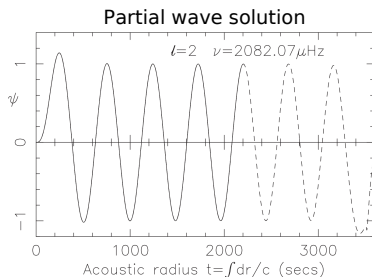
Differential Response Inversion

Description

- 1 Discretise (ρ, Γ_1) profiles up to a truncation point.
- 2 At the observed frequencies, obtain partial wave solutions and associated phase shifts.
- 3 Adjust model so that phase shifts become a function of frequency only.

Various articles

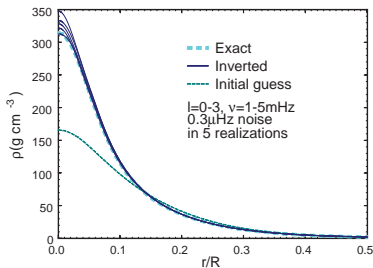
- Vorontsov (1998, 2001),
Roxburgh (2002, 2010)



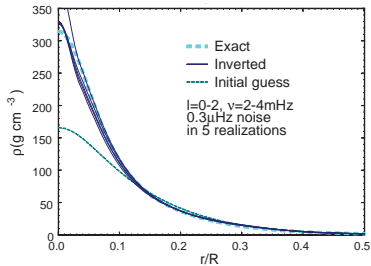
(Roxburgh & Vorontsov, 2003)

An example

Favourable



Unfavourable



(Roxburgh, 2002)

- multiple realisations are used to determine the uncertainty on the profile

Conclusion

- rotational inversions are feasible in stars other than the Sun
- structural inversions remain a challenge
- extraction of stellar parameters:
 - may provide a useful intermediate between scaling laws and inversions
 - still needs more exploration on large samples of models/stars
- non-linear inversions:
 - can reproduce frequency spectra
 - models can be somewhat unphysical
 - additional physics might improve results – room for new physical behaviours?